## THE MANGA GUIDE TO CALCULUS

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HIROYUKI KOJIMA SHIN TOGAMI BECOM CO., LTD.

Ohmsha



COMICS INSIDE!

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THE MANGA GUIDE™ TO CALCULUS



# THE MANGA GUIDE" TO

HIROYUKI KOJIMA SHIN TOGAMI BECOM CO., LTD.





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### PREFACE

There are some things that only manga can do.

You have just picked up and opened this book. You must be one of the following types of people.

The first type is someone who just loves manga and thinks, "Calculus illustrated with manga? Awesome!" If you are this type of person, you should immediately take this book to the cashier you won't regret it. This is a very enjoyable manga title. It's no surprise—Shin Togami, a popular manga artist, drew the manga, and Becom Ltd., a real manga production company, wrote the scenario.

"But, manga that teaches about math has never been very enjoyable," you may argue. That's true. In fact, when an editor at Ohmsha asked me to write this book, I nearly turned down the opportunity. Many of the so-called "manga for education" books are quite disappointing. They may have lots of illustrations and large pictures, but they aren't really manga. But after seeing a sample from Ohmsha (it was *The Manga Guide to Statistics*), I totally changed my mind. Unlike many such manga guides, the sample was enjoyable enough to actually read. The editor told me that my book would be like this, too—so I accepted his offer. In fact, I have often thought that I might be able to teach mathematics better by using manga, so I saw this as a good opportunity to put the idea into practice. I guarantee you that the bigger manga freak you are, the more you will enjoy this book. So, what are you waiting for? Take it up to the cashier and buy it already!

Now, the second type of person is someone who picked up this book thinking, "Although I am terrible at and/or allergic to calculus, manga may help me understand it." If you are this type of person, then this is also the book for you. It is equipped with various rehabilitation methods for those who have been hurt by calculus in the past. Not only does it explain calculus using manga, but the way it explains calculus is fundamentally different from the method used in conventional textbooks. First, the book repeatedly

presents the notion of what calculus really does. You will never understand this through the teaching methods that stick to limits (or  $\varepsilon$ - $\delta$  logic). Unless you have a clear image of what calculus really does and why it is useful in the world, you will never really understand or use it freely. You will simply fall into a miserable state of memorizing formulas and rules. This book explains all the formulas based on the concept of the first-order approximation, helping you to visualize the meaning of formulas and understand them easily. Because of this unique teaching method, you can quickly and easily proceed from differentiation to integration. Furthermore, I have adopted an original method, which is not described in ordinary textbooks, of explaining the differentiation and integration of trigonometric and exponential functions—usually, this is all Greek to many people even after repeated explanations. This book also goes further in depth than existing manga books on calculus do, explaining even Taylor expansions and partial differentiation. Finally, I have invited three regular customers of calculus—physics, statistics, and economics—to be part of this book and presented many examples to show that calculus is truly practical. With all of these devices, you will come to view calculus not as a hardship, but as a useful tool.

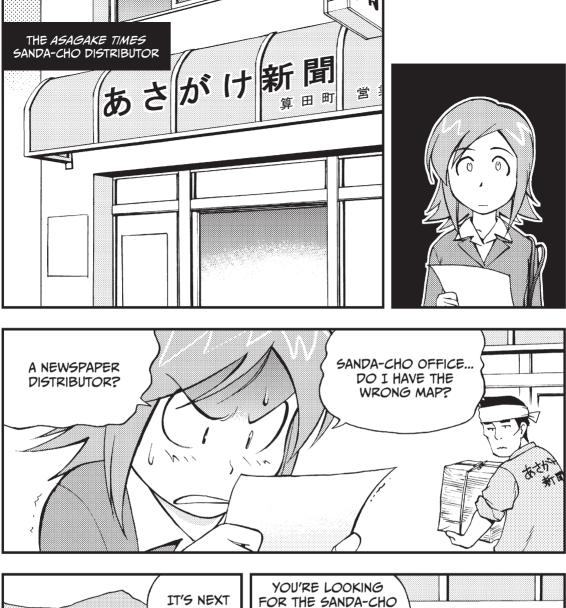
I would like to emphasize again: All of this has been made possible because of manga. Why can you gain more information by reading a manga book than by reading a novel? It is because manga is visual data presented as animation. Calculus is a branch of mathematics that describes dynamic phenomena—thus, calculus is a perfect concept to teach with manga. Now, turn the pages and enjoy a beautiful integration of manga and mathematics.

HIROYUKI KOJIMA NOVEMBER 2005

NOTE: For ease of understanding, some figures are not drawn to scale.

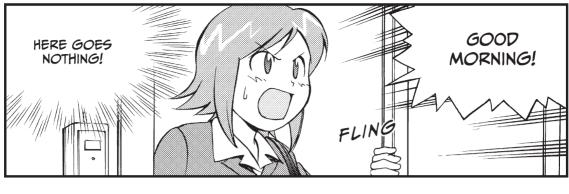


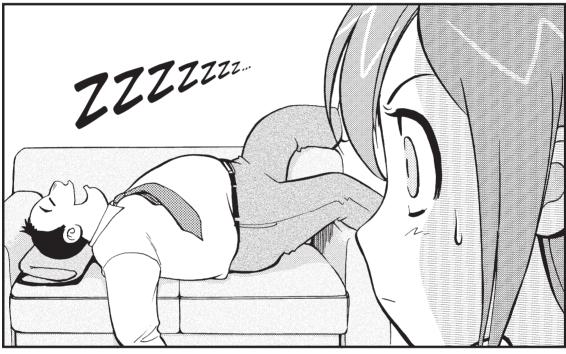


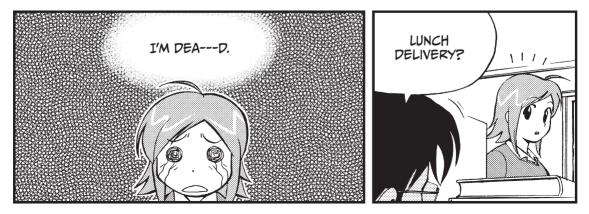






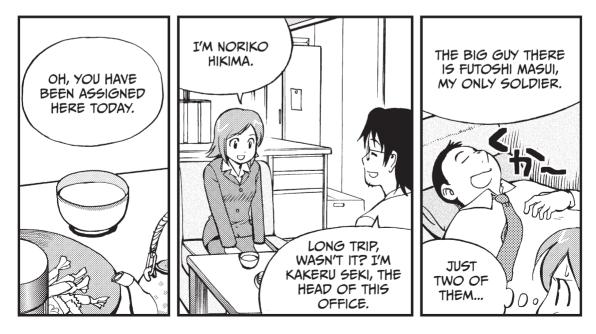




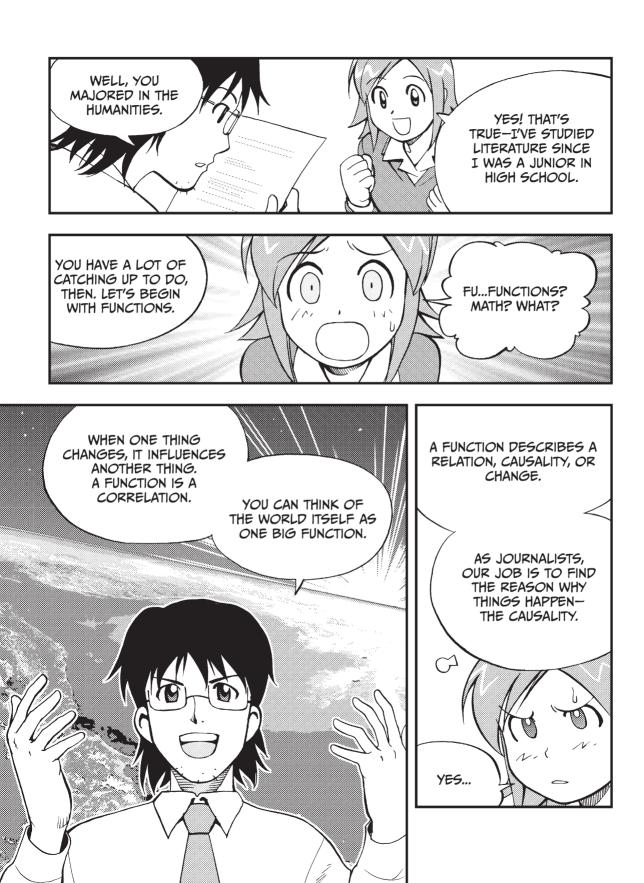


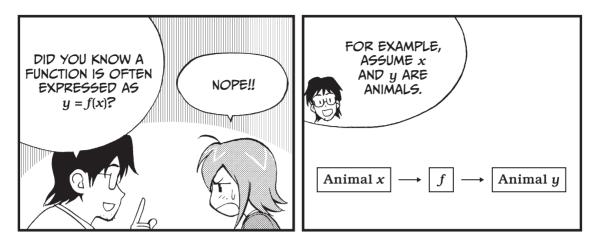


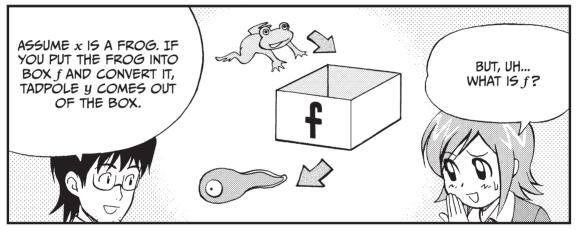


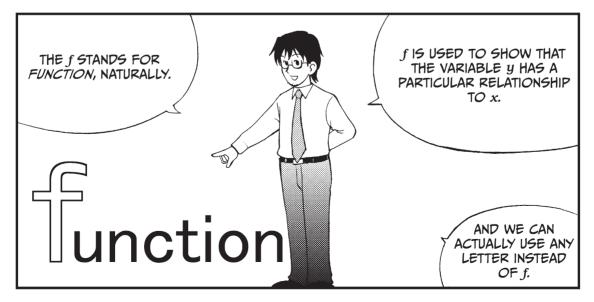




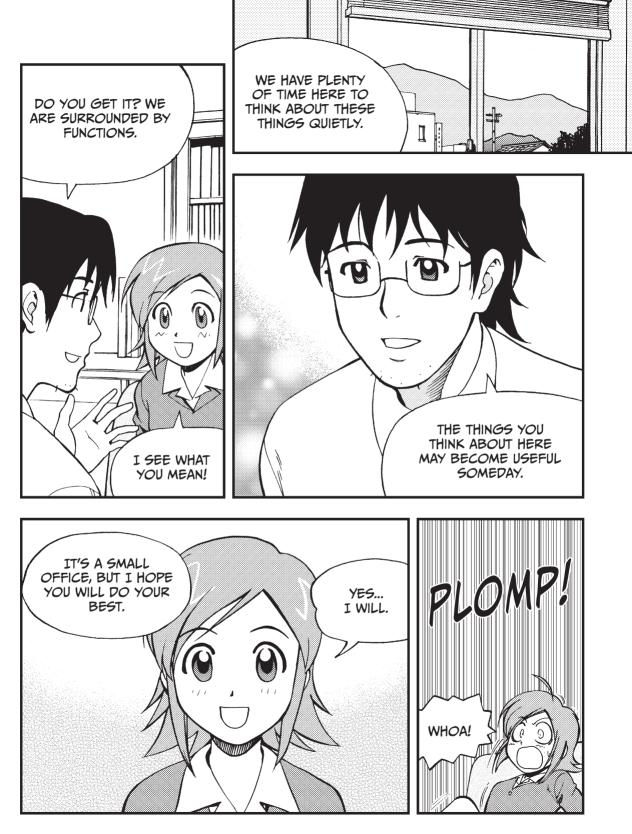


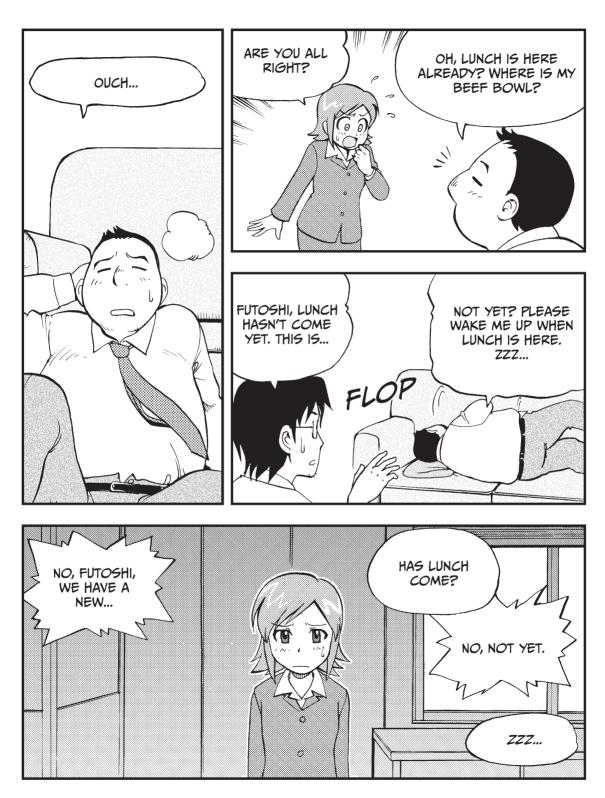




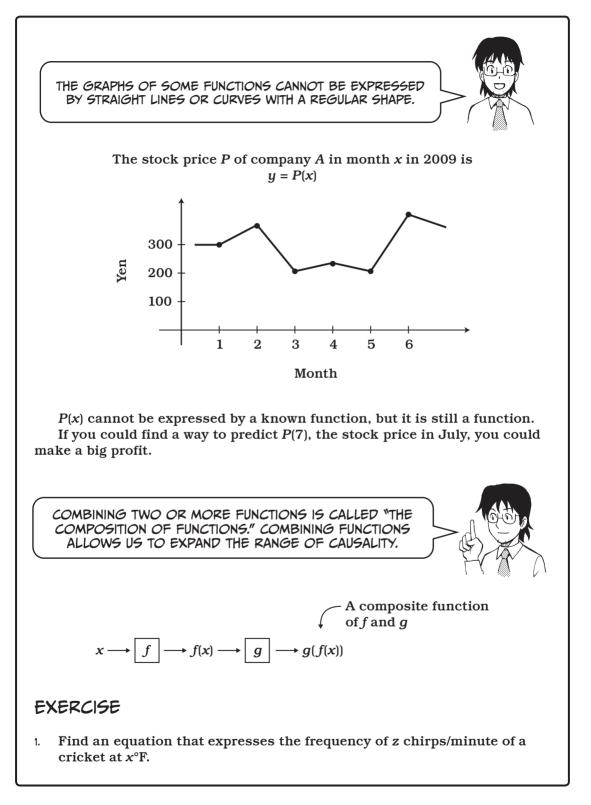








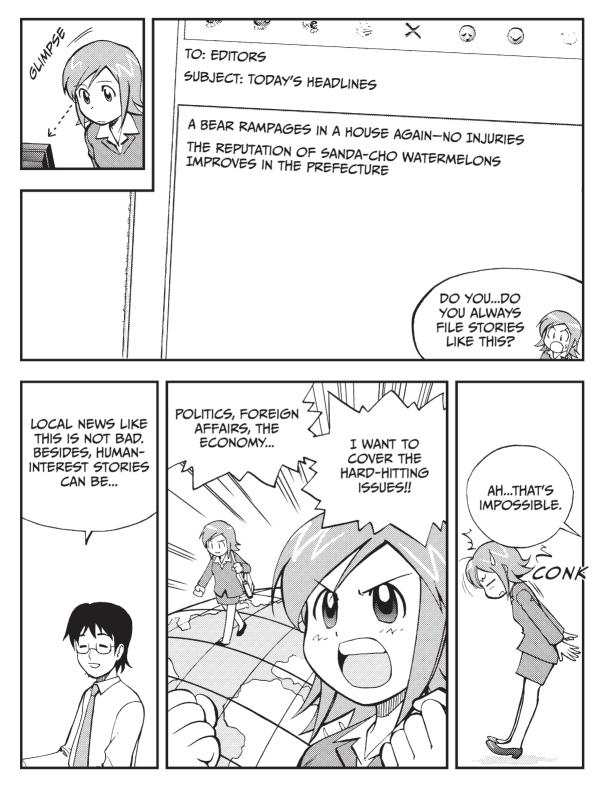
SUBJECT	CALCULATION	GRAPH
Causality	The frequency of a cricket's chirp is determined by temperature. We can express the relationship between y chirps per minute of a cricket at temperature x°C approximately as	When we graph these functions, the result is a straight line. That's why we call them linear functions.
	$y = g(x) = 7x - 30$ $\uparrow \qquad \downarrow$ $x = 27^{\circ}  7 \times 27 - 30$ The result is 159 chirps a minute.	y
Changes	The speed of sound y in meters per sec- ond (m/s) in the air at x°C is expressed as y = v(x) = 0.6x + 331 At 15°C, $y = v(15) = 0.6 \Box 15 + 331 = 340$ m/s At -5°C,	
Unit Conversion	$y = v(-5) = 0.6 \times (-5) + 331 = 328 \text{ m/s}$ Converting x degrees Fahrenheit (°F) into y degrees Celsius (°C) $y = f(x) = \frac{5}{9}(x - 32)$ So now we know 50°F is equivalent to $\frac{5}{9}(50 - 32) = 10°C$	
	9Computers store numbers using a binary system (1s and 0s). A binary number with x bits (or binary digits) has the potential to store y numbers. $y = b(x) = 2^x$ (This is described in more detail on page 131.)	The graph is an exponential function.

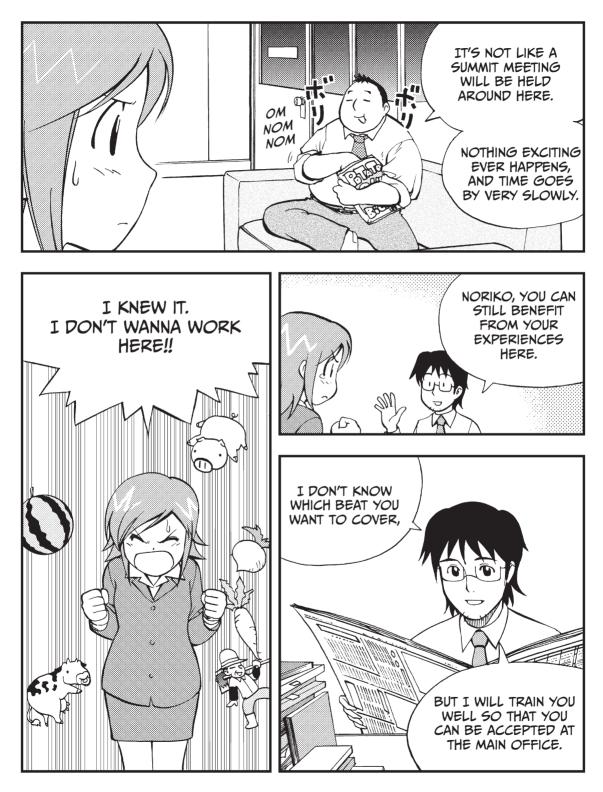


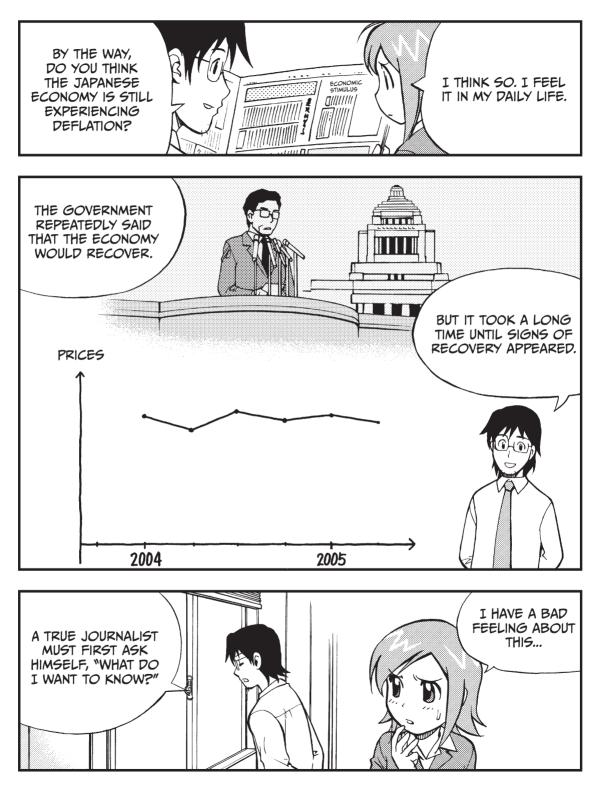
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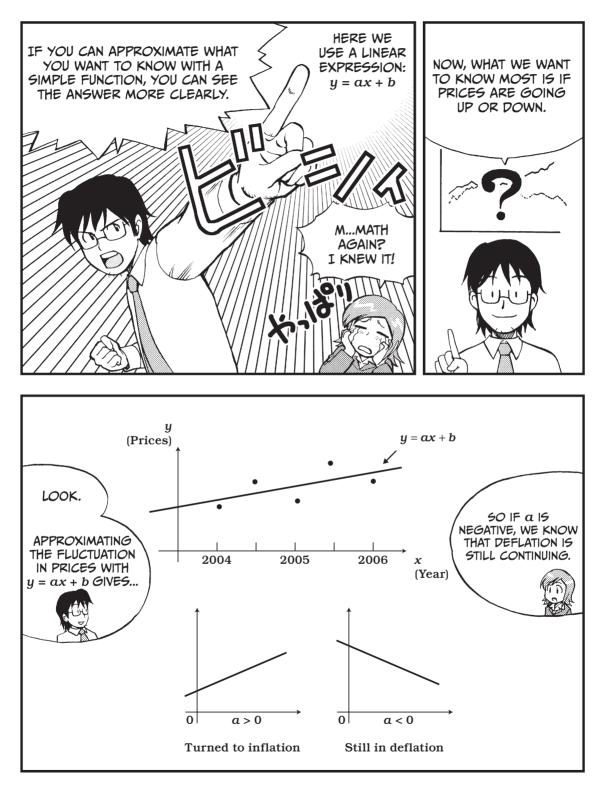
### APPROXIMATING WITH FUNCTIONS



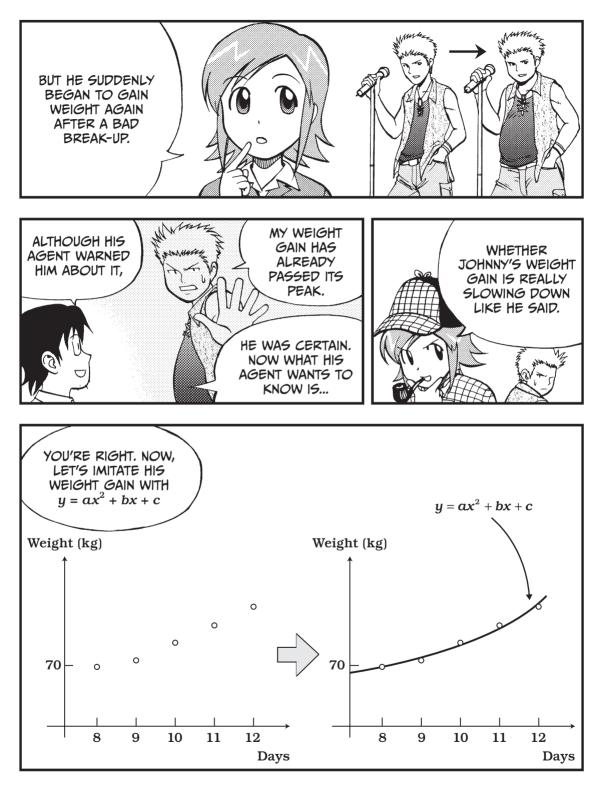


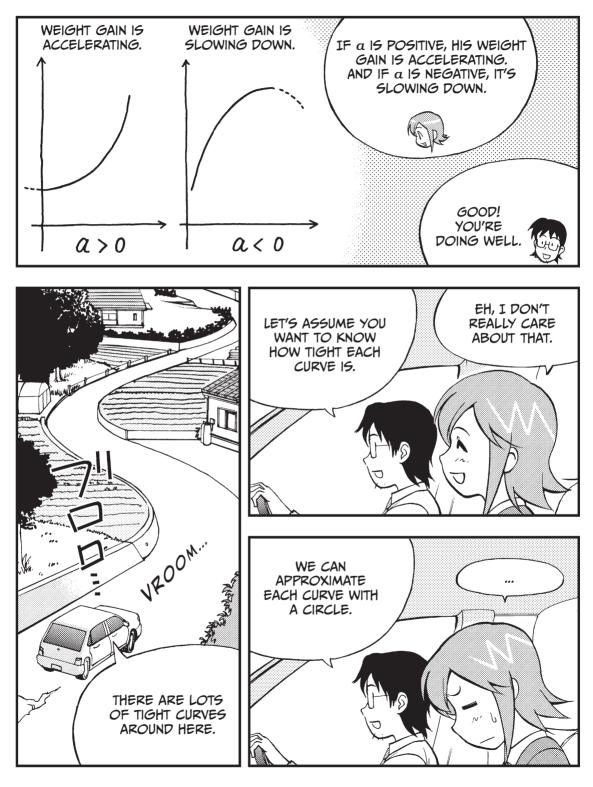


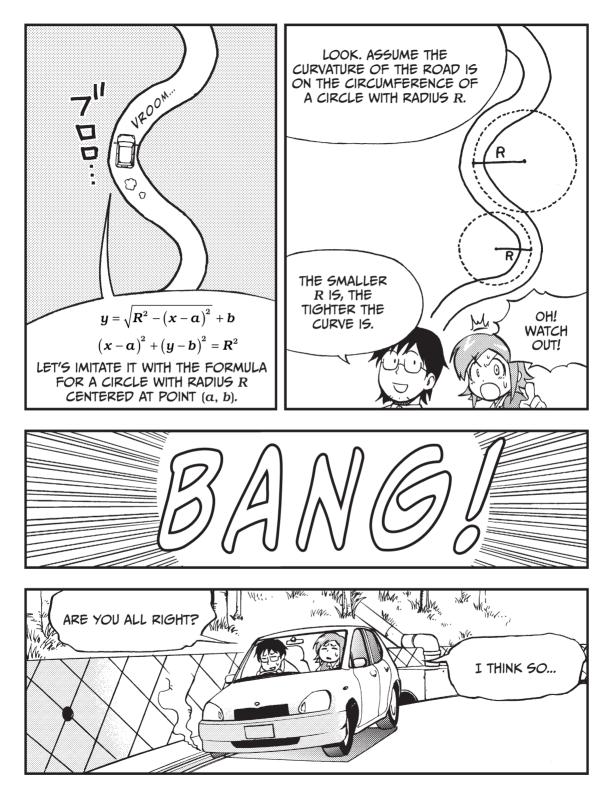


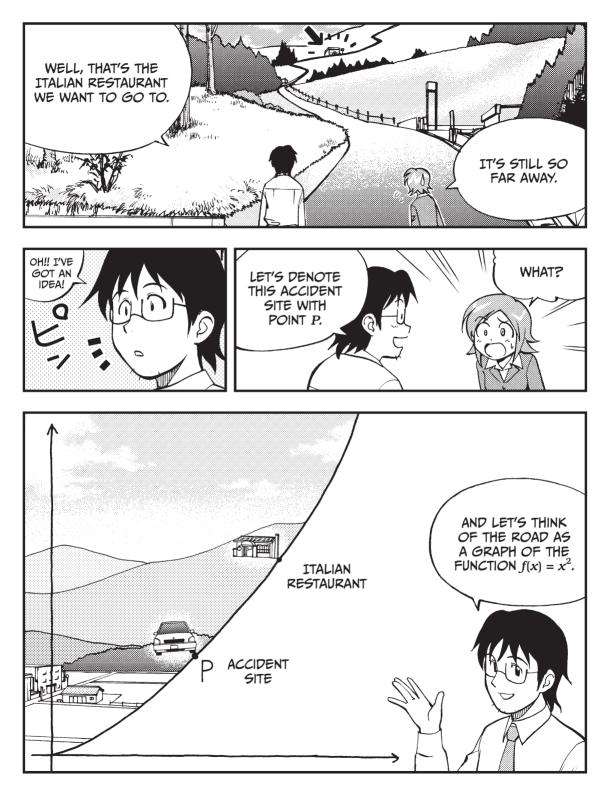


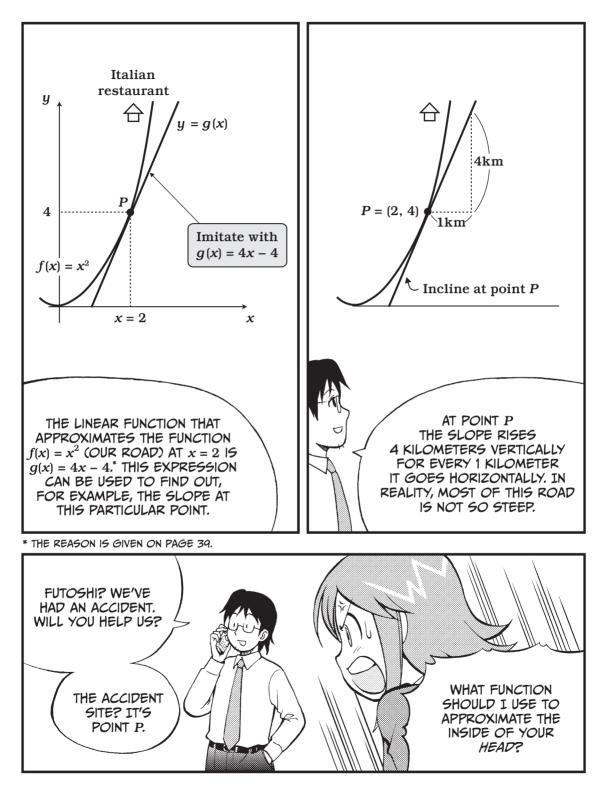




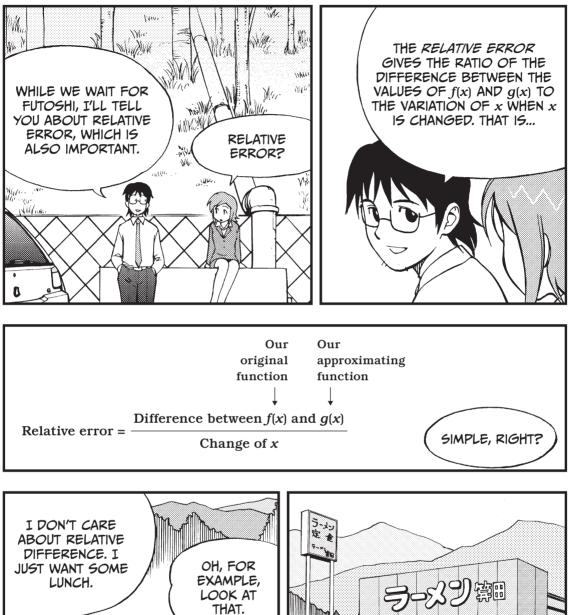




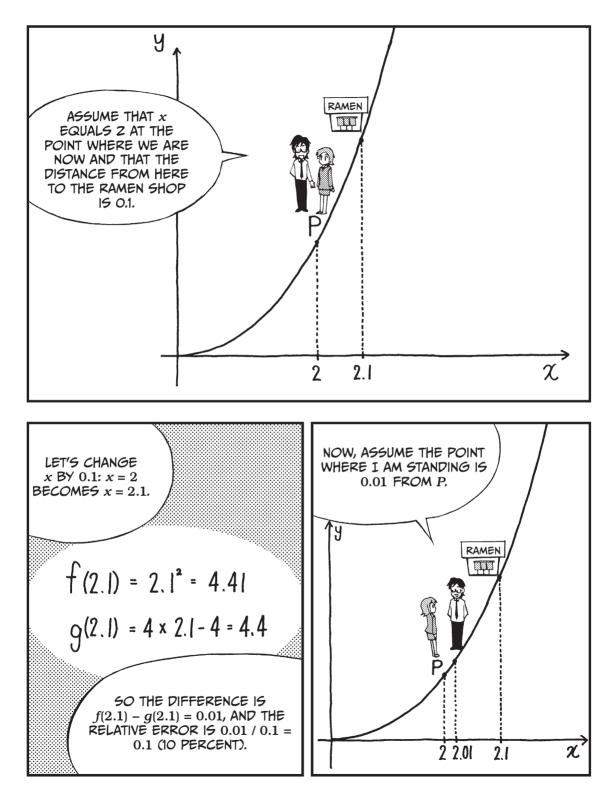


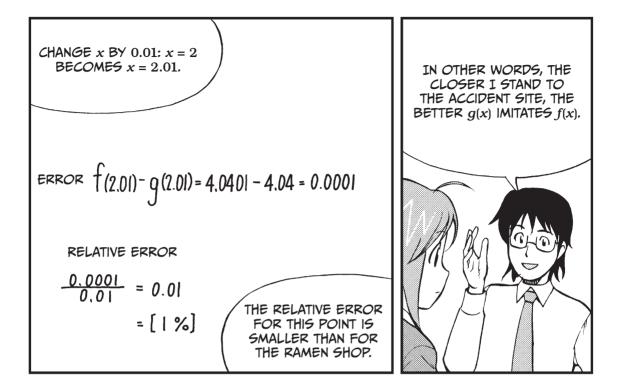


# CALCULATING THE RELATIVE ERROR



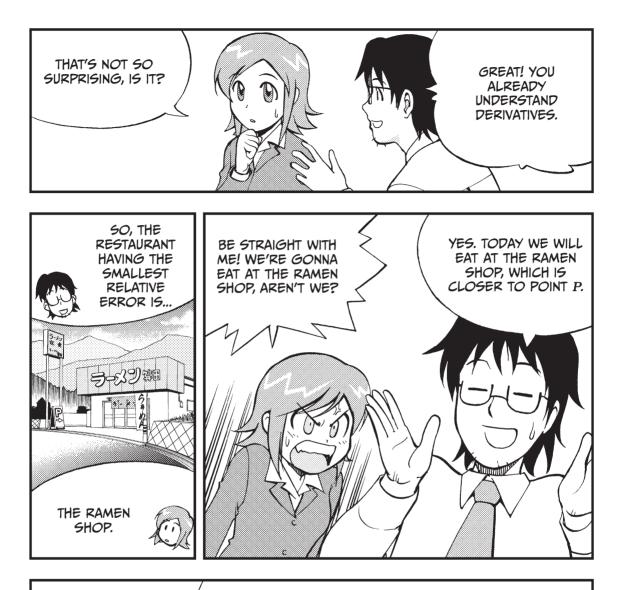
A RAMEN SHOP?

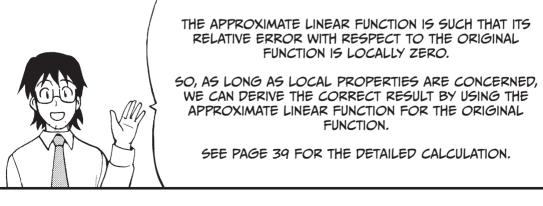




As the variation approaches 0, the relative error also approaches 0.

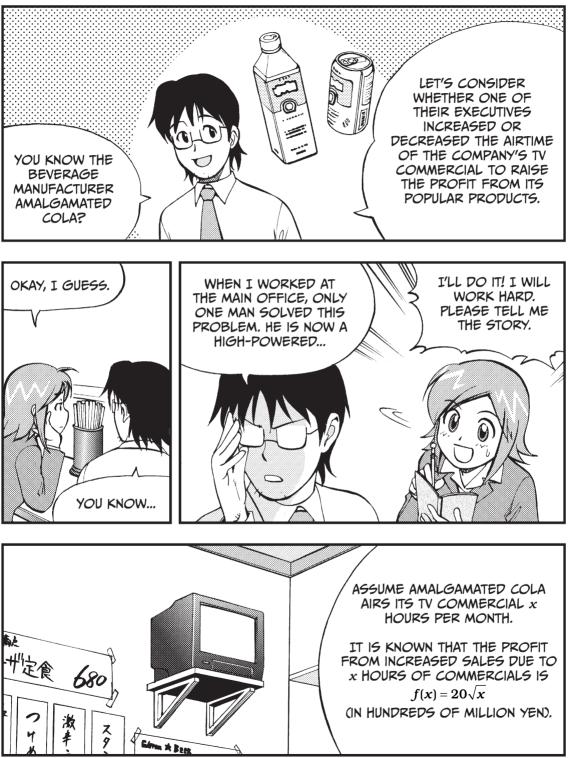
Variation of <i>x</i> from 2	$f(\mathbf{x})$	g(x)	Error	Relative error
1	9	8	1	100.0%
0.1	4.41	4.4	0.01	10.0%
0.01	4.0401	4.04	0.0001	1.0%
0.001	4.004001	4.004	0.000001	0.1%
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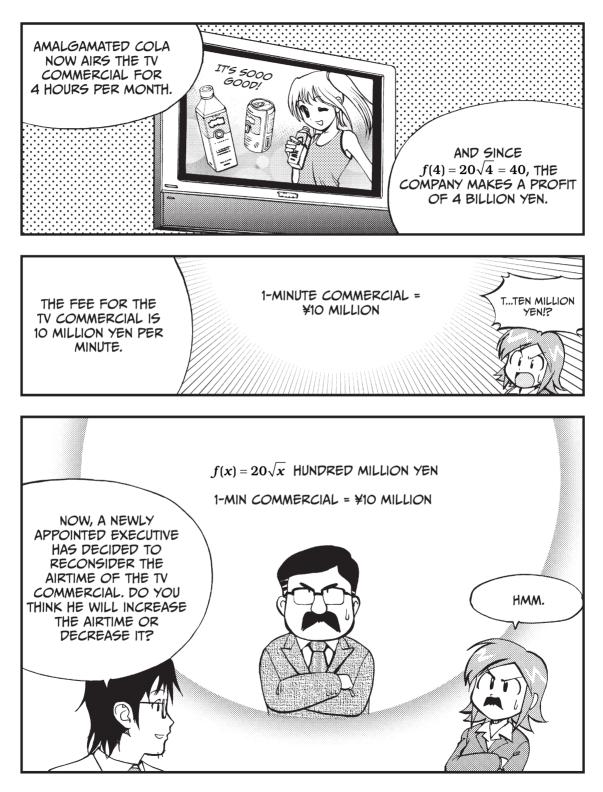


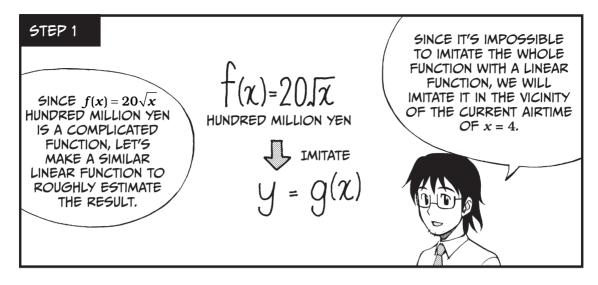


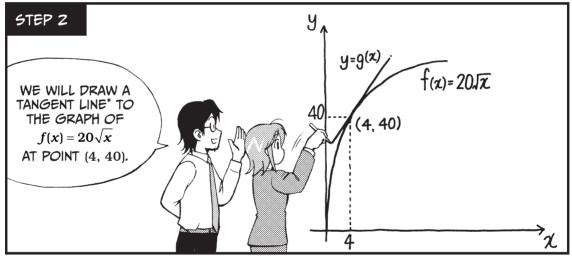


# THE DERIVATIVE IN ACTION!









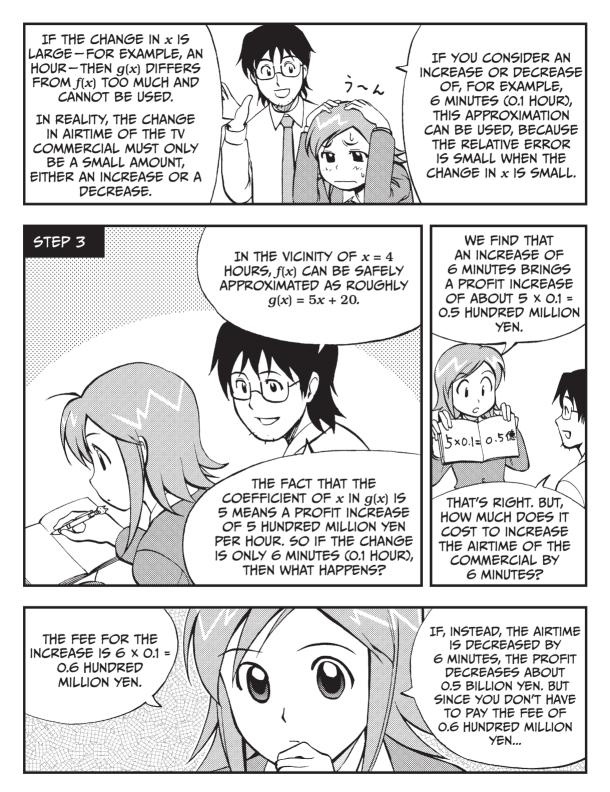
 $\ast$  Here is the calculation of the tangent line. (See also the explanation of the derivative on page 39.)

For  $f(x) = 20\sqrt{x}$ , f'(4) is given as follows.

$$\frac{f(4+\varepsilon)-f(4)}{\varepsilon} = \frac{20\sqrt{4+\varepsilon}-20\times 2}{\varepsilon} = 20\frac{\left(\sqrt{4+\varepsilon}-2\right)\times\left(\sqrt{4+\varepsilon}+2\right)}{\varepsilon\times\left(\sqrt{4+\varepsilon}+2\right)}$$

$$= 20 \frac{4+\varepsilon-4}{\varepsilon \left(\sqrt{4+\varepsilon}+2\right)} = \frac{20}{\sqrt{4+\varepsilon}+2} \quad \bullet$$

When  $\varepsilon$  approaches 0, the denominator of  $\mathbf{0}$   $\sqrt{4+\varepsilon} + 2 \rightarrow 4$ . Therefore,  $\mathbf{0} \rightarrow 20 \div 4 = 5$ . Thus, the approximate linear function g(x) = 5(x-4) + 40 = 5x + 20









### CALCULATING THE DERIVATIVE

Let's find the imitating linear function g(x) = kx + l of function f(x) at x = a. We need to find slope k.

Now, let's calculate the relative error when x changes from x = a to  $x = a + \varepsilon$ .

Relative error = 
$$\frac{\text{Difference between } f \text{ and } g \text{ after } x \text{ has changed}}{\text{Change of } x \text{ from } x = a}$$
$$= \frac{f(a + \varepsilon) - g(a + \varepsilon)}{\varepsilon}$$
$$g(a + \varepsilon) = k(a + \varepsilon - a) + f(a)$$
$$= k\varepsilon + f(a)$$
$$= \frac{f(a + \varepsilon) - f(a)}{\varepsilon} \rightarrow 0 \quad \text{When } \varepsilon \text{ approaches } 0,$$
the relative error also approaches 0.  
$$k = \lim_{\varepsilon \to 0} \frac{f(a + \varepsilon) - f(a)}{\varepsilon} \quad \text{of } (a + \varepsilon) - f(a)$$
$$\frac{f(a + \varepsilon) - f(a)}{\varepsilon} \quad \text{when } \varepsilon \to 0.$$

(The lim notation expresses the operation that obtains the value when  $\varepsilon$  approaches 0.)

Linear function  $\mathbf{0}$ , or g(x), with this k, is an approximate function of f(x). k is called the differential coefficient of f(x) at x = a.

$$\lim_{\varepsilon \to 0} \frac{f(a+\varepsilon) - f(a)}{\varepsilon}$$
 Slope of the line tangent to  $y = f(x)$  at any point  $(a, f(a))$ .

We make symbol f' by attaching a prime to f.

$$f'(a) = \lim_{\varepsilon \to 0} \frac{f(a+\varepsilon) - f(a)}{\varepsilon}$$
  $f'(a)$  is the slope of the line tangent to  $y = f(x)$  at  $x = a$ .

Letter a can be replaced with x.

Since f' can been seen as a function of x, it is called "the function derived from function f," or the *derivative* of function f.

CALCULATING THE DERIVATIVE OF A CONSTANT, LINEAR, OR QUADRATIC FUNCTION

1. Let's find the derivative of constant function  $f(x) = \alpha$ . The differential coefficient of f(x) at  $x = \alpha$  is

$$\lim_{\varepsilon \to 0} \frac{f(\alpha + \varepsilon) - f(\alpha)}{\varepsilon} = \lim_{\varepsilon \to 0} \frac{\alpha - \alpha}{\varepsilon} = \lim_{\varepsilon \to 0} 0 = 0$$

Thus, the derivative of f(x) is f'(x) = 0. This makes sense, since our function is constant—the rate of change is 0.

NOTE The differential coefficient of f(x) at x = a is often simply called the derivative of f(x) at x = a, or just f'(a).

2. Let's calculate the derivative of linear function  $f(x) = \alpha x + \beta$ . The derivative of f(x) at x = a is

$$\lim_{\varepsilon \to 0} \frac{f(a+\varepsilon) - f(a)}{\varepsilon} = \lim_{\varepsilon \to 0} \frac{\alpha (a+\varepsilon) + \beta - (\alpha a + \beta)}{\varepsilon} = \lim_{\varepsilon \to 0} \alpha = \alpha$$

Thus, the derivative of f(x) is  $f'(x) = \alpha$ , a constant value. This result should also be intuitive—linear functions have a constant rate of change by definition.

3. Let's find the derivative of  $f(x) = x^2$ , which appeared in the story. The differential coefficient of f(x) at x = a is

$$\lim_{\varepsilon \to 0} \frac{f(a+\varepsilon) - f(a)}{\varepsilon} = \lim_{\varepsilon \to 0} \frac{(a+\varepsilon)^2 - a^2}{\varepsilon} = \lim_{\varepsilon \to 0} \frac{2a\varepsilon + \varepsilon^2}{\varepsilon} = \lim_{\varepsilon \to 0} (2a+\varepsilon) = 2a$$

Thus, the differential coefficient of f(x) at x = a is 2a, or f'(a) = 2a. Therefore, the derivative of f(x) is f'(x) = 2x.

#### SUMMARY

- The calculation of a limit that appears in calculus is simply a formula calculating an error.
- A limit is used to obtain a derivative.
- The derivative is the slope of the tangent line at a given point.
- The derivative is nothing but the rate of change.

The derivative of f(x) at x = a is calculated by

$$\lim_{\varepsilon \to 0} \frac{f(a + \varepsilon) - f(a)}{\varepsilon}$$

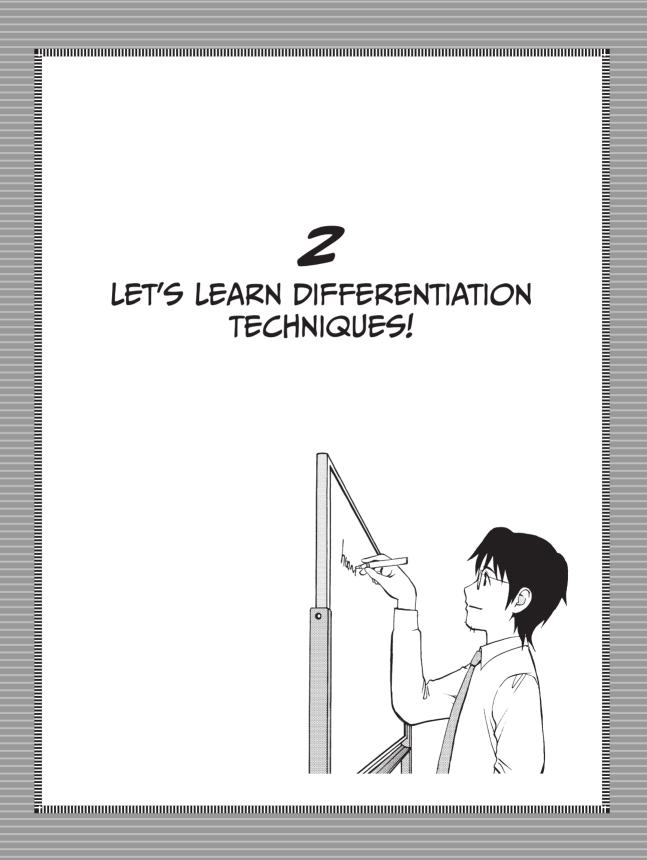
g(x) = f'(a) (x - a) + f(a) is then the approximate linear function of f(x). f'(x), which expresses the slope of the line tangent to f(x) at the point (x, f(x)), is called the *derivative* of f(x), because it is derived from f(x).

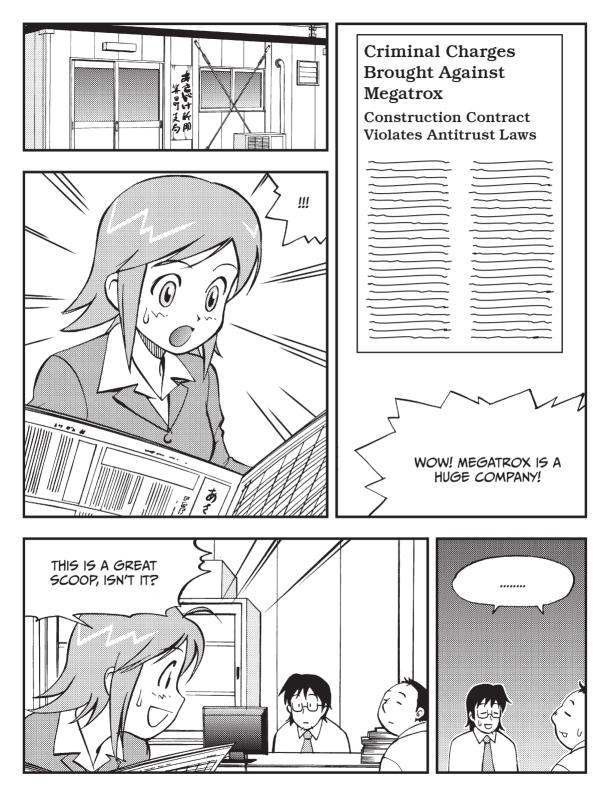
Other than f'(x), the following symbols are also used to denote the derivative of y = f(x).

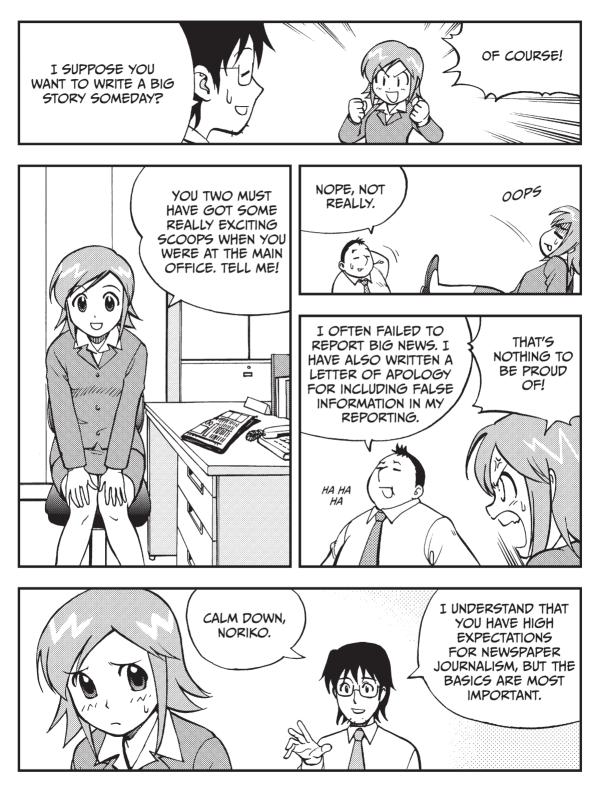
$$y', \ \frac{dy}{dx}, \ \frac{df}{dx}, \ \frac{d}{dx}f(x)$$

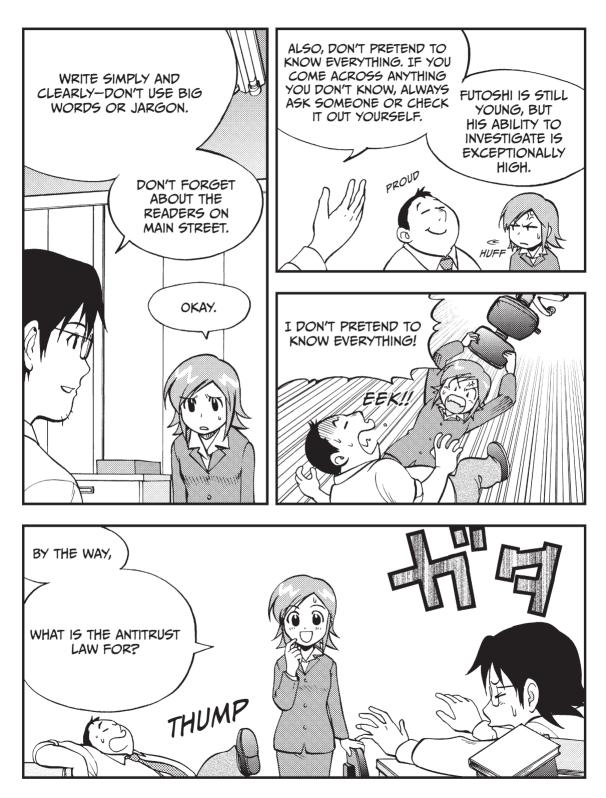
### EXERCISES

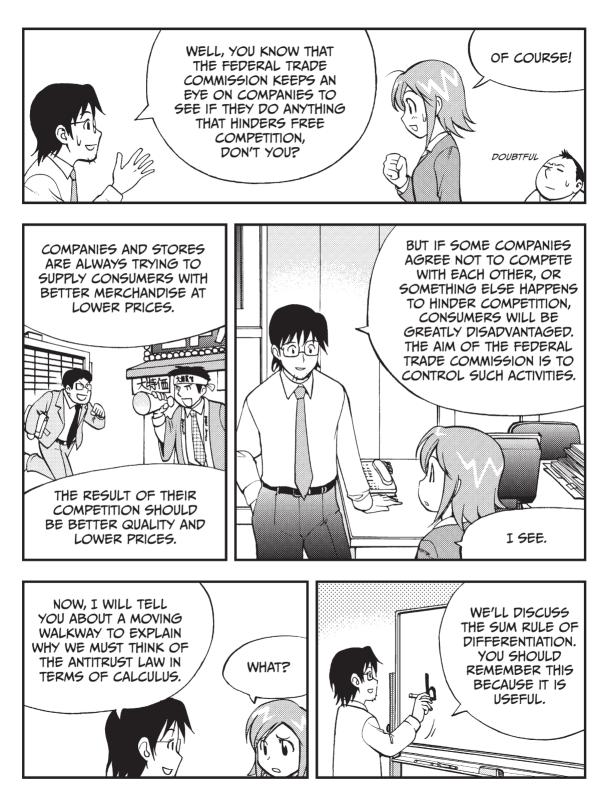
- 1. We have function f(x) and linear function g(x) = 8x + 10. It is known that the relative error of the two functions approaches 0 when x approaches 5.
  - A. Obtain f(5).
  - B. Obtain f'(5).
- 2. For  $f(x) = x^3$ , obtain its derivative f'(x).



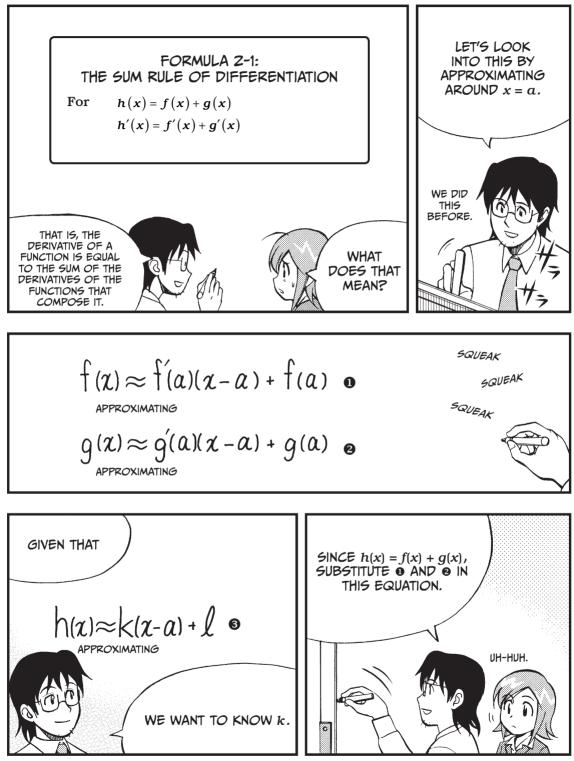


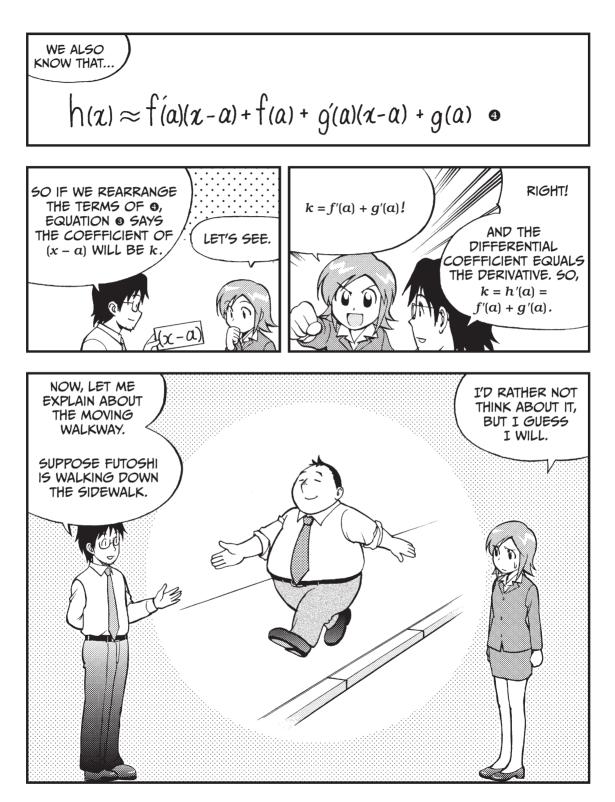


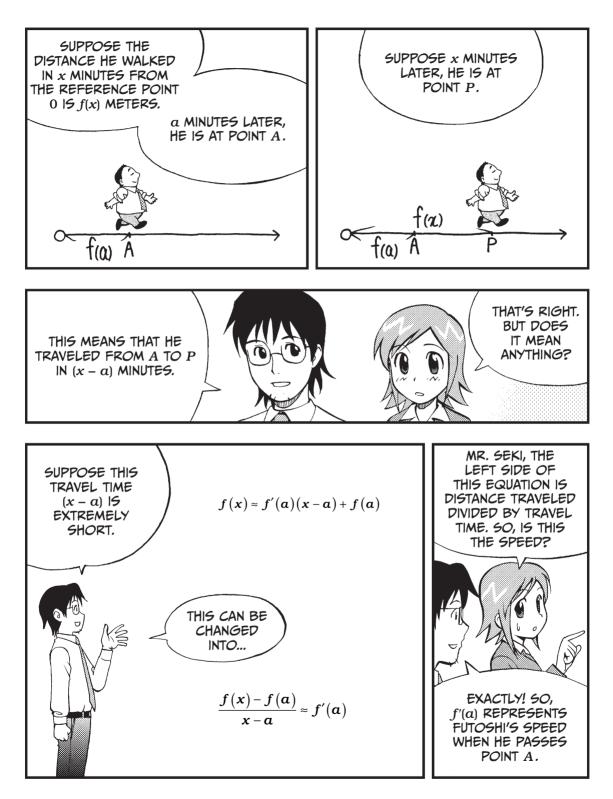


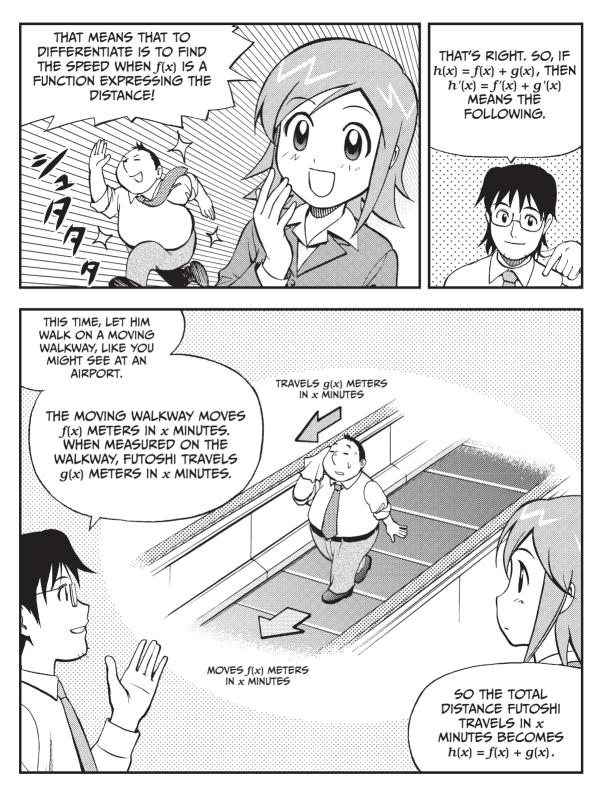


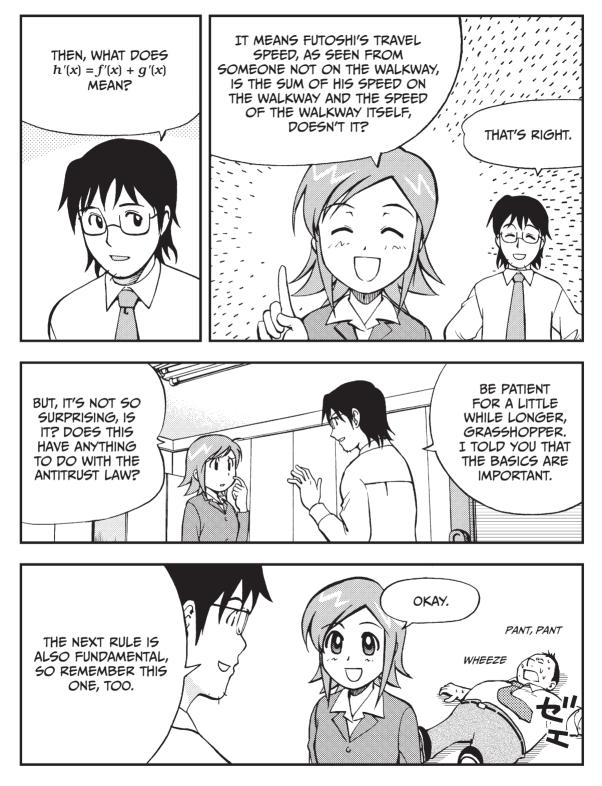
## THE SUM RULE OF DIFFERENTIATION











# THE PRODUCT RULE OF DIFFERENTIATION

FORMULA 2-2: THE PRODUCT RULE OF DIFFERENTIATION

For 
$$h(x) = f(x)g(x)$$
  
 $h'(x) = f'(x)g(x) + f(x)g'(x)$ 

The derivative of a product is the sum of the products with only one function differentiated.





$$f(\mathbf{x}) \approx f'(\mathbf{a})(\mathbf{x}-\mathbf{a}) + f(\mathbf{a})$$

$$g(x) \approx g'(a)(x-a) + g(a)$$

$$h(x) = f(x)g(x) \approx k(x-a) + l$$

$$h(x) \approx \{f'(a)(x-a) + f(a)\} \times \{g'(a)(x-a) + g(a)\}$$

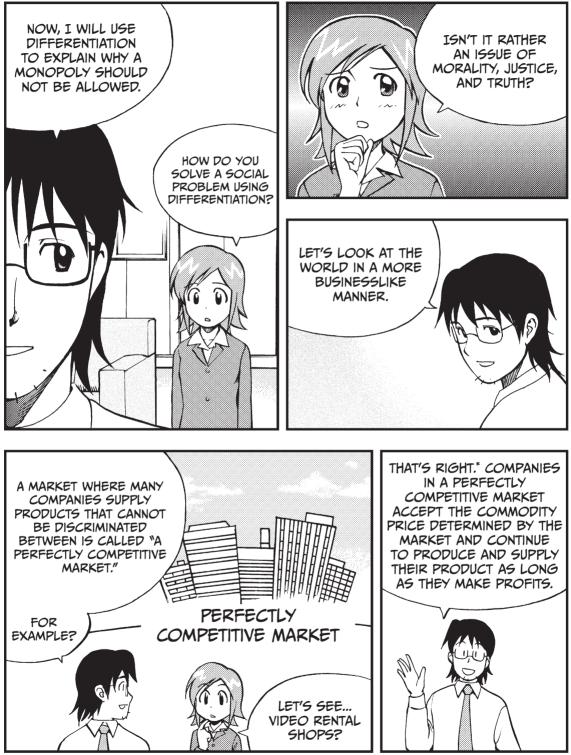
$$h(x) \approx f'(a)g'(a)(x-a)^{2} + f(a)g'(a)(x-a) + f'(a)(x-a)g(a) + f(a)g(a)$$

$$(x-a) + f(a)g(a) + f(a)g(a)$$

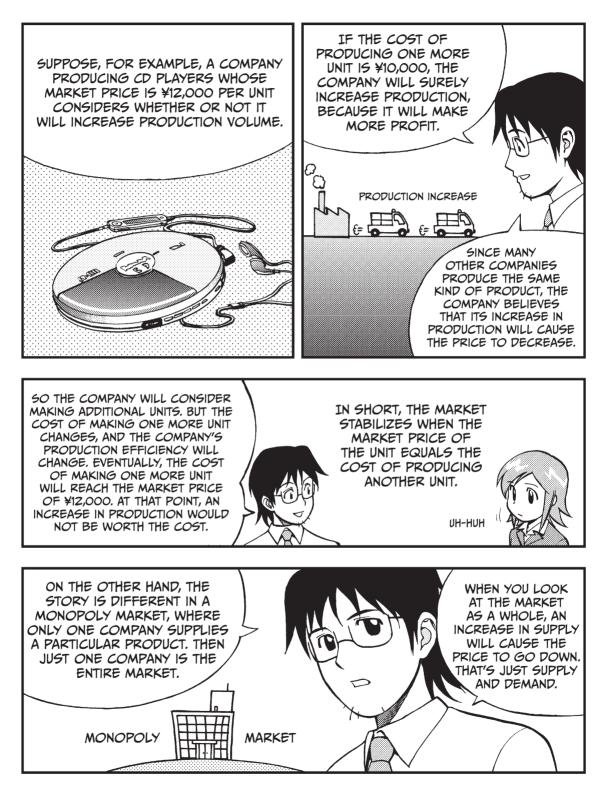
$$(x-a)^{2} + f(a)g(a) + f(a)g'(a)$$

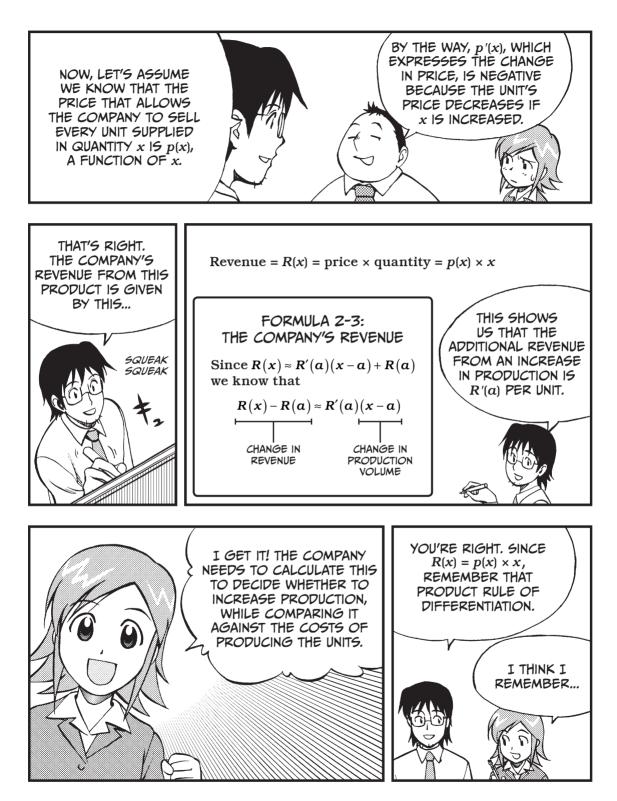
$$(x-a)^{2} + f(a)g(a) + f(a)g'(a)$$

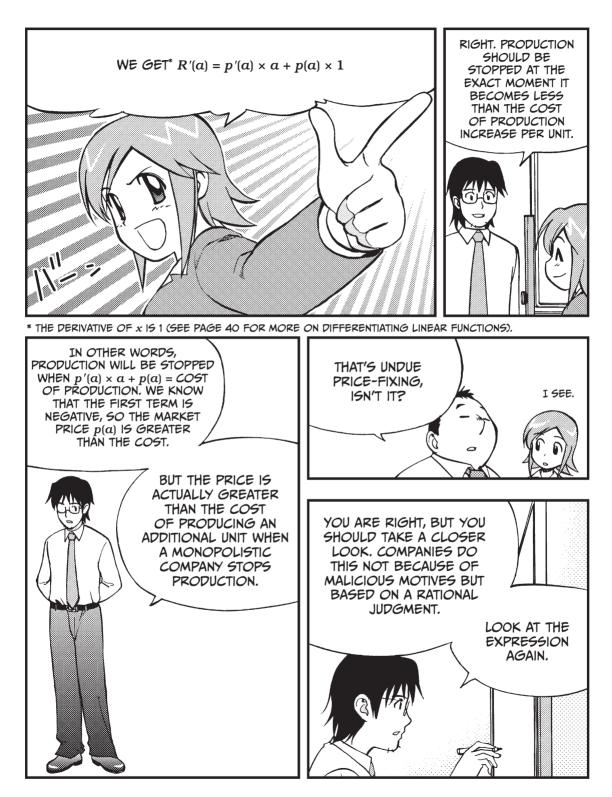
$$(x-a) + f(a)g(a)$$



\* IN REALITY, THERE ARE USUALLY BIG-NAME BRANDS FOR ANY COMMODITY. THERE ARE FAMOUS CHAIN SHOPS IN THE VIDEO RENTAL MARKET-NO MARKET CAN BE A PERFECTLY COMPETITIVE ONE, SO THIS IS A FICTITIOUS, IDEAL SITUATION.







Sales increase (per unit) when production is increased a little more:

R'(a) = p'(a)a + p(a)

The two terms in the last expression mean the following:

p(a) represents the revenue from selling a units

p'(a) a = Rate of price decrease × Amount of production = A heavy loss due to price decrease influencing all units



THE MONOPOLY STOPS PRODUCTION, CONSIDERING BOTH HOW MUCH IT OBTAINS BY SELLING ONE MORE UNIT AND HOW MUCH LOSS IT SUFFERS DUE TO A PRICE DECREASE.

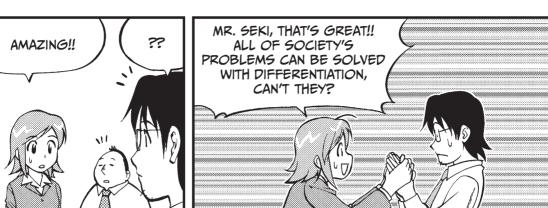


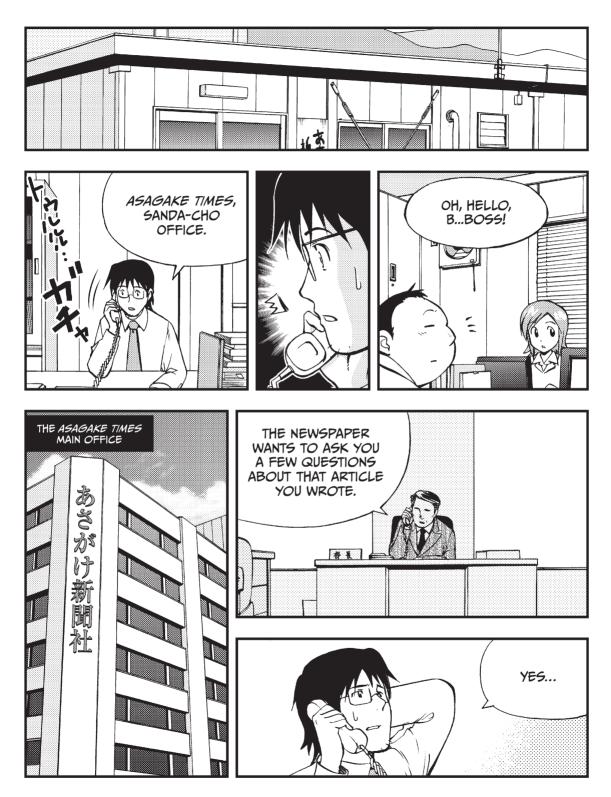


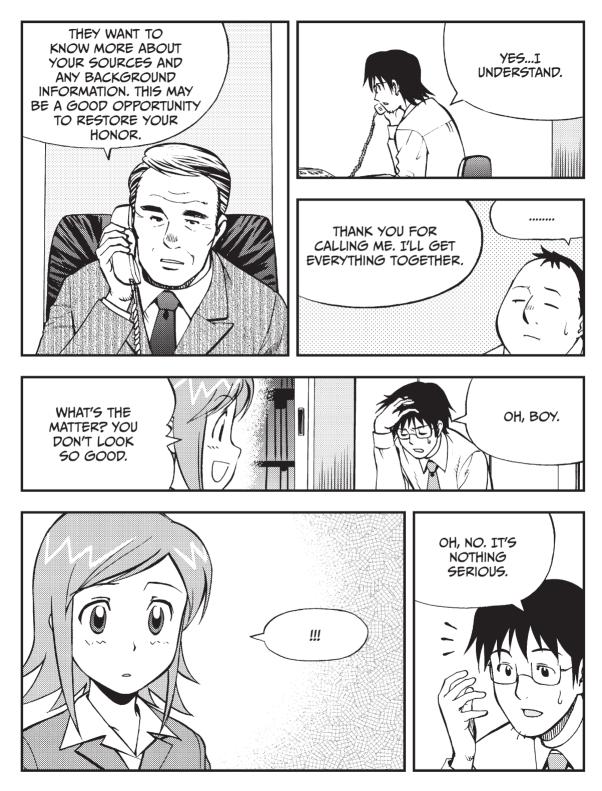




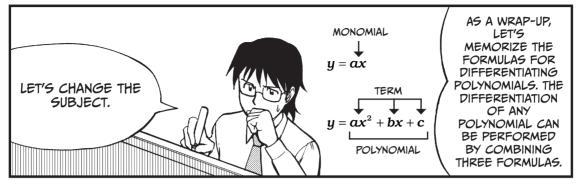








## DIFFERENTIATING POLYNOMIALS



FORMULA 2-4: THE DERIVATIVE OF AN nTH-DEGREE FUNCTION

The derivative of  $h(x) = x^n$  is  $h'(x) = nx^{n-1}$ 

How do we get this general rule? We use the product rule of differentiation repeatedly.

For  $h(x) = x^2$ , since  $h(x) = x \times x$ ,  $h'(x) = x \times 1 + 1 \times x = 2x$ 

THIS RESULT IS USED

The formula is correct in this case.

For  $h(x) = x^3$ , since  $h(x) = x^2 \Box x$ ,  $h'(x) = (x^2)' \times x + x^2 \times (x)' = (2x)x + x^2 \times 1 = 3x^2$ 

The formula is correct in this case, too.

For  $h(x) = x^4$ , since  $h(x) = x^3 \square x$ ,  $h'(x) = (x^3)' \times x + x^3 \times (x)' = 3x^2 \times x + x^3 \times 1 = 4x^3$ 

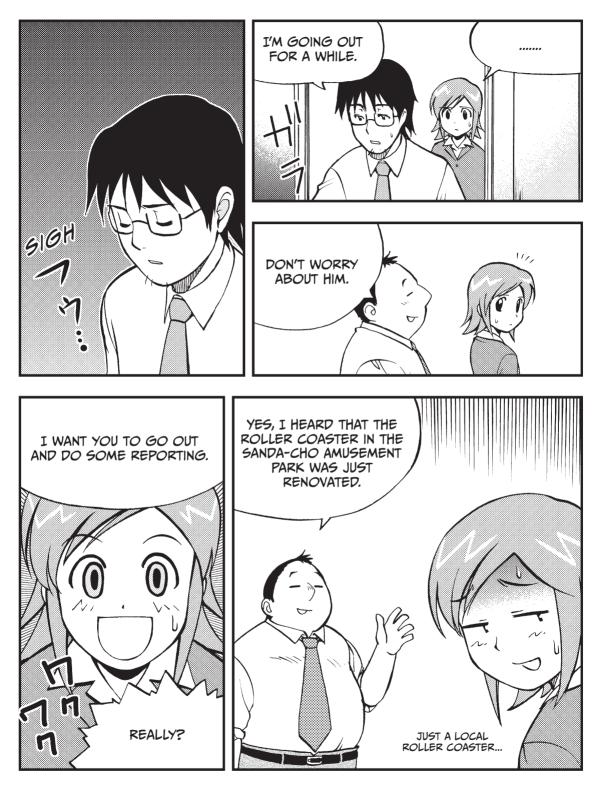
Again, the formula is correct. This continues forever. Any polynomial can be differentiated by combining the three formulas!

FORMULA 2-5: THE DIFFERENTIATION FORMULAS OF SUM RULE, CONSTANT MULTIPLICATION, AND  $x^n$ 

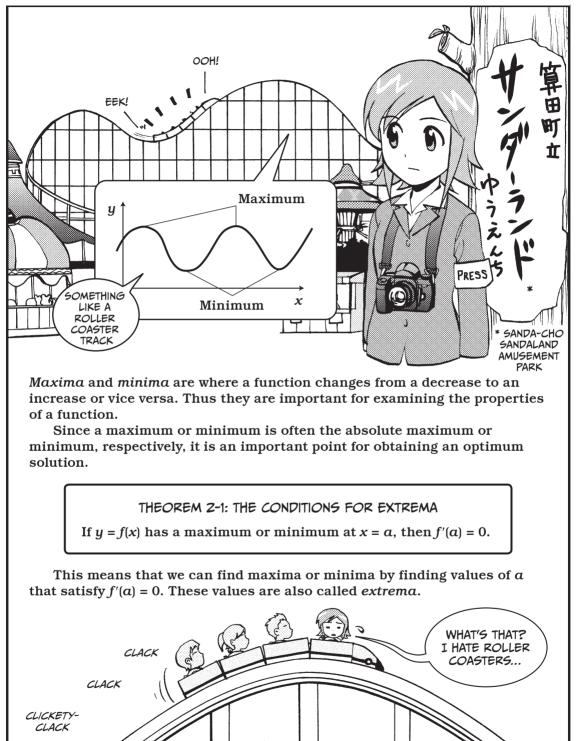
- **0** Sum rule:  $\{f(x) + g(x)\}' = f'(x) + g'(x)$  **6** Power rule  $(x^n)$ :  $\{x^n\}' = nx^{n-1}$
- **O** Constant multiplication:  $\{\alpha f(\mathbf{x})\}' = \alpha f'(\mathbf{x})$

Let's see it in action! Differentiate  $h(x) = x^3 + 2x^2 + 5x + 3$ 

$$\begin{array}{c} \text{rule } \mathbf{0} \\ h'(x) = \left\{ x^3 + 2x^2 + 5x + 3 \right\}' = \left[ x^3 \right]' + \left( 2x^2 \right)' + \left( 5x \right)' + \left( 3 \right)' \\ = \left[ x^3 \right]' + 2\left( x^2 \right)' + 5\left( x \right)' \\ \text{rule } \mathbf{0} \end{array}$$



### FINDING MAXIMA AND MINIMA



#### Assume f'(a) > 0.

Since  $f(x) \approx f'(a)$  (x - a) + f(a) near x = a, f'(a) > 0 means that the approximate linear function is increasing at x = a. Thus, so is f(x).

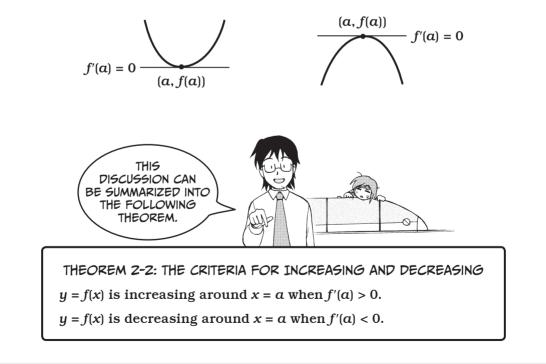
In other words, the roller coaster is ascending, and it is not at the top or at the bottom.

Similarly, y = f(x) is descending when f'(a) < 0, and it is not at the top or the bottom, either.



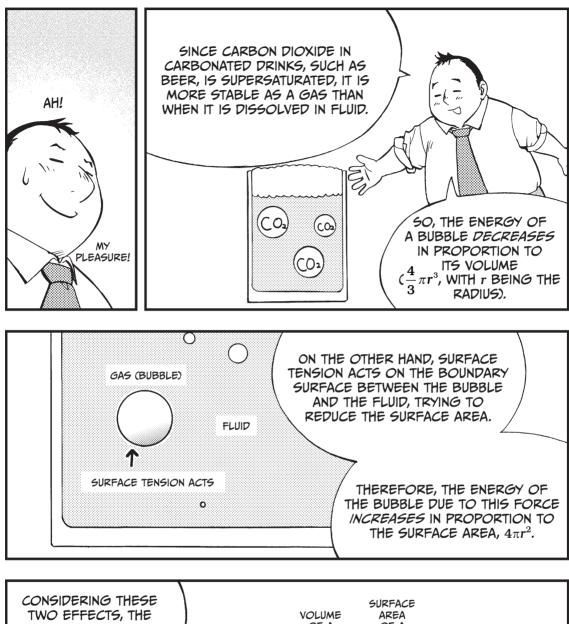
If y = f(x) is ascending or descending when f'(a) > 0 or f'(a) < 0, respectively, we can only have f'(a) = 0 at the top or bottom.

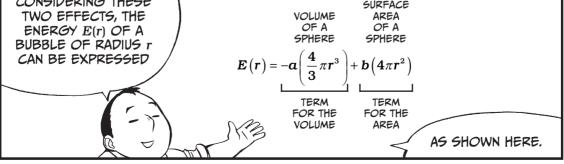
In fact, the approximate linear function  $y = f'(a) (x - a) + f(a) = 0 \times (x - a) + f(a)$  is a horizontal constant function when f'(a) = 0, which fits our understanding of maxima and minima.

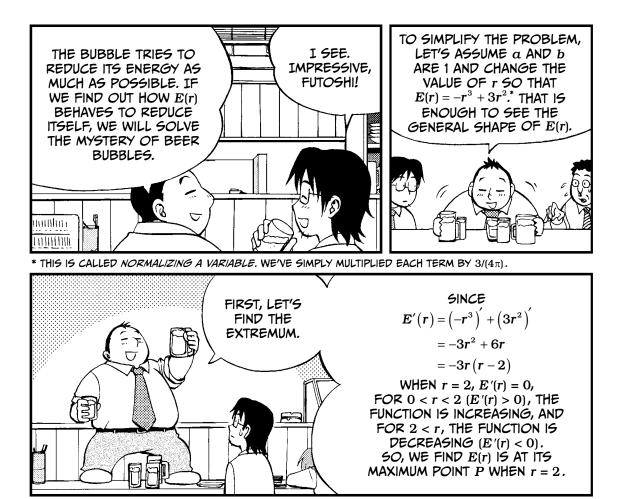


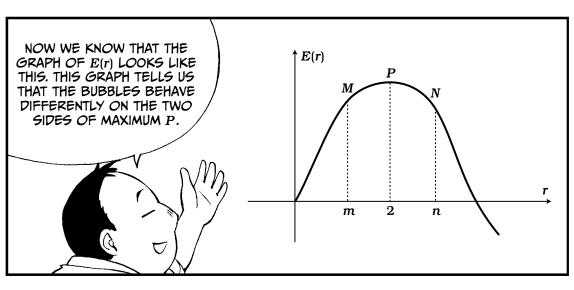


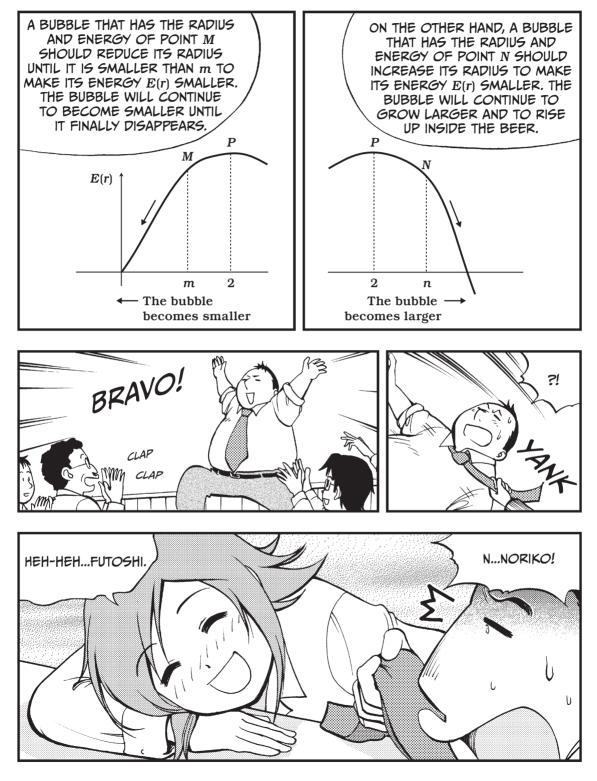














## USING THE MEAN VALUE THEOREM

We saw before that the derivative is the coefficient of x in the approximate linear function that imitates function f(x) in the vicinity of x = a.

That is,

 $f(x) \approx f'(a)(x-a) + f(a)$  (when x is very close to a)

But the linear function only "pretends to be" or "imitates" f(x), and for b, which is near a, we generally have

 $\bullet \quad f(b) \neq f'(a)(b-a) + f(a)$ 

So, this is not exactly an equation.

FOR THOSE WHO CANNOT STAND FOR THIS, WE HAVE THE FOLLOWING THEOREM.

THEOREM 2-3: THE MEAN VALUE THEOREM

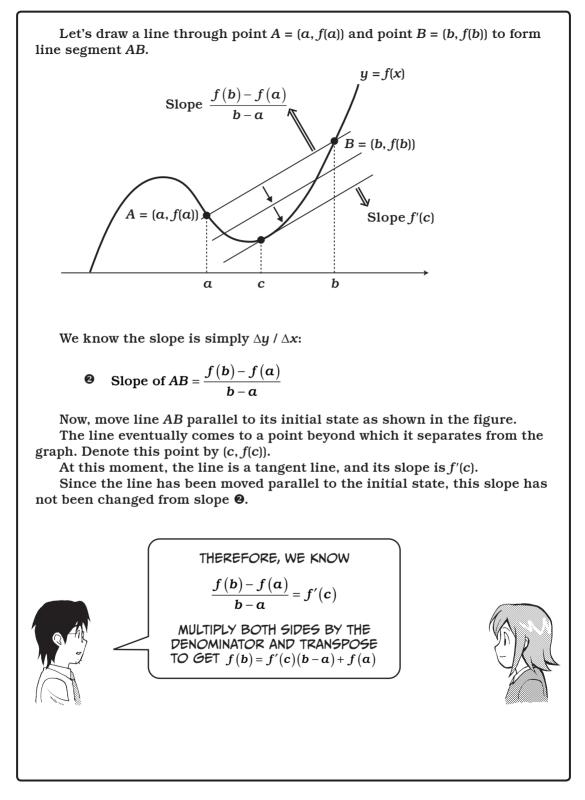
For a, b (a < b), and c, which satisfy a < c < b, there exists a number c that satisfies

$$f(b) = f'(c)(b-a) + f(a)$$

In other words, we can make expression ① hold with an equal sign not with f'(a) but with f'(c), where c is a value existing somewhere between a and b.



\* That is, there must be a value for x between a and b (which we'll call c) that has a tangent line matching the slope of a line connecting points A and B.



### USING THE QUOTIENT RULE OF DIFFERENTIATION

Let's find the formula for the derivative of  $h(x) = \frac{g(x)}{f(x)}$ 

First, we find the derivative of function  $p(x) = \frac{1}{f(x)}$ , which is the reciprocal of f(x).

If we know this, we'll be able to apply the product rule to h(x). Using simple algebra, we see that f(x)p(x) = 1 always holds.

$$\mathbf{1} = f(\mathbf{x}) p(\mathbf{x}) \approx \left\{ f'(\mathbf{a})(\mathbf{x} - \mathbf{a}) + f(\mathbf{a}) \right\} \left\{ p'(\mathbf{a})(\mathbf{x} - \mathbf{a}) + p(\mathbf{a}) \right\}$$

Since these two are equal, their derivatives must be equal as well.

$$\mathbf{0} = \boldsymbol{p}(\boldsymbol{x}) \boldsymbol{f}'(\boldsymbol{x}) + \boldsymbol{p}'(\boldsymbol{x}) \boldsymbol{f}(\boldsymbol{x})$$

Thus, we have  $p'(x) = -\frac{p(x)f'(x)}{f(x)}$ .

Since  $p(a) = \frac{1}{f(a)}$ , substituting this for p(a) in the numerator gives  $p'(a) = \frac{-f'(a)}{f(a)^2}$ .

For  $h(x) = \frac{g(x)}{f(x)}$  in general, we consider  $h(x) = g(x) \square \frac{1}{f(x)} = g(x) p(x)$ 

and use the product rule and the above formula.

$$h'(x) = g'(x) p(x) + g(x) p'(x) = g'(x) \frac{1}{f(x)} - g(x) \frac{f'(x)}{f(x)^2}$$
$$= \frac{g'(x) f(x) - g(x) f'(x)}{f(x)^2}$$

Therefore, we obtain the following formula.

FORMULA 2-6: THE QUOTIENT RULE OF DIFFERENTIATION

$$h'(x) = \frac{g'(x)f(x) - g(x)f'(x)}{f(x)^2}$$

# CALCULATING DERIVATIVES OF COMPOSITE FUNCTIONS

Let's obtain the formula for the derivative of h(x) = g(f(x)). Near x = a,

$$f(\mathbf{x}) - f(\mathbf{a}) \approx f'(\mathbf{a})(\mathbf{x} - \mathbf{a})$$

And near y = b,

$$\boldsymbol{g}(\boldsymbol{y}) - \boldsymbol{g}(\boldsymbol{b}) \approx \boldsymbol{g}'(\boldsymbol{b})(\boldsymbol{y} - \boldsymbol{b})$$

We now substitute b = f(a) and y = f(x) in the last expression. Near x = a,

$$g(f(x)) - g(f(a)) \approx g'(f(a))(f(x) - f(a))$$

Replace f(x) - f(a) in the right side with the right side of the first expression.

$$g(f(x)) - g(f(a)) \approx g'(f(a)) f'(a)(x-a)$$

Since g(f(x)) = h(x), the coefficient of (x - a) in this expression gives us h'(a) = g'(f(a))f'(a).

We thus obtain the following formula.

FORMULA 2-7: THE DERIVATIVES OF COMPOSITE FUNCTIONS

h'(x) = g'(f(x))f'(x)

### CALCULATING DERIVATIVES OF INVERSE FUNCTIONS

Let's use the above formula to find the formula for the derivative of x = g(y), the inverse function of y = f(x).

Since x = g(f(x)) for any x, differentiating both sides of this expression gives 1 = g'(f(x))f'(x).

Thus, 1 = g'(y) f'(x), and we obtain the following formula.

FORMULA 2-8: THE DERIVATIVES OF INVERSE FUNCTIONS

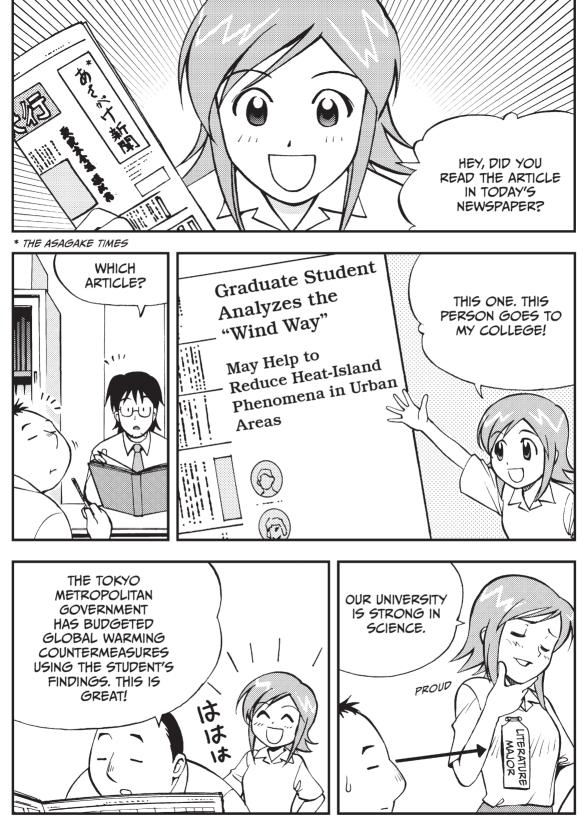
$$g'(y) = \frac{1}{f'(x)}$$

	FORMULA	KEY POINT
Constant multipli- cation	$\{\alpha f(\boldsymbol{x})\}' = \alpha f'(\boldsymbol{x})$	The multiplicative constant can be fac- tored out.
x <sup>n</sup> (Power)	$(\boldsymbol{x}^{n})' = \boldsymbol{n}\boldsymbol{x}^{n-1}$	The exponent becomes the coefficient, reduc- ing the degree by 1.
Sum	$\left\{f(x)+g(x)\right\}'=f'(x)+g'(x)$	The derivative of a sum is the sum of the derivatives.
Product	$\left\{f(x)g(x)\right\}' = f'(x)g(x) + f(x)g'(x)$	The sum of the prod- ucts with each func- tion differentiated in turn.
Quotient	$\left\{\frac{g(x)}{f(x)}\right)' = \frac{g'(x)f(x) - g(x)f'(x)}{f(x)^2}$	The denominator is squared. The numera- tor is the difference between the products with only one function differentiated.
Composite functions	$\left\{ \boldsymbol{g}(\boldsymbol{f}(\boldsymbol{x})) \right\}' = \boldsymbol{g}'(\boldsymbol{f}(\boldsymbol{x})) \boldsymbol{f}'(\boldsymbol{x})$	The product of the derivative of the outer and that of the inner.
Inverse functions	$g'(y) = rac{1}{f'(x)}$	The derivative of an inverse function is the reciprocal of the original.

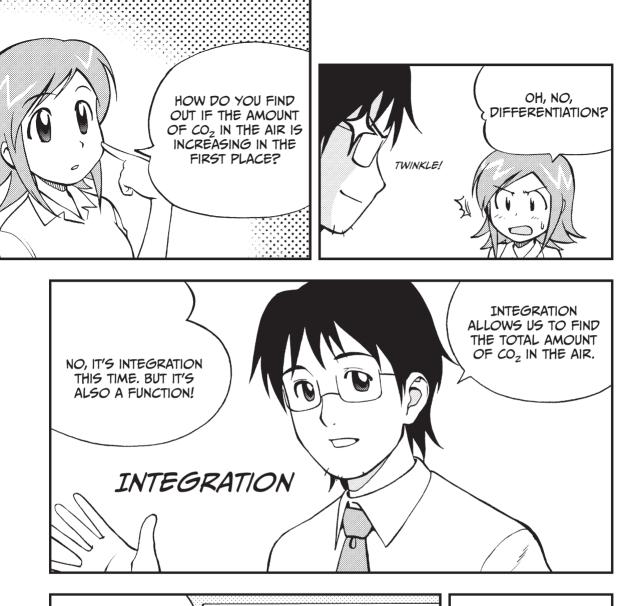
# EXERCISES

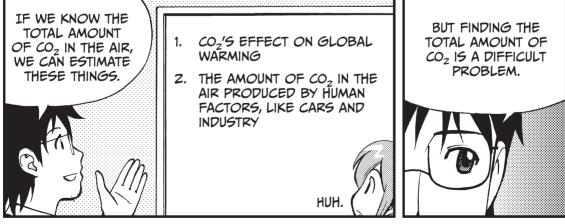
- 1. For natural number *n*, find the derivative f'(x) of  $f(x) = \frac{1}{x^n}$ .
- 2. Calculate the extrema of  $f(x) = x^3 12x$ .
- 3. Find the derivative f'(x) of  $f(x) = (1 x)^3$ .
- 4. Calculate the maximum value of  $g(x) = x^2(1-x)^3$  in the interval  $0 \le x \le 1$ .





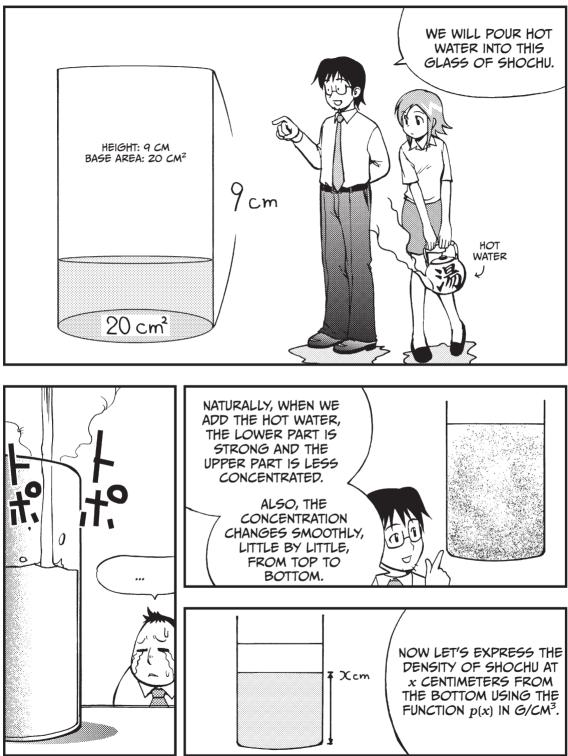


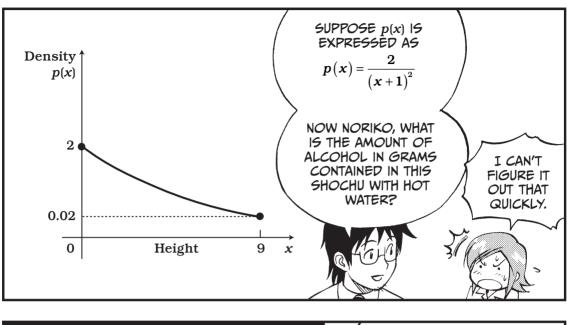


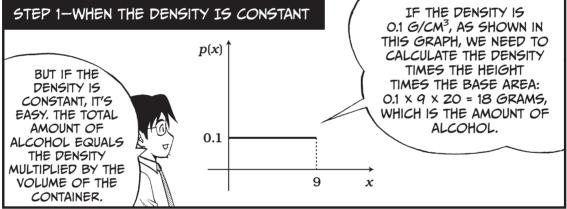


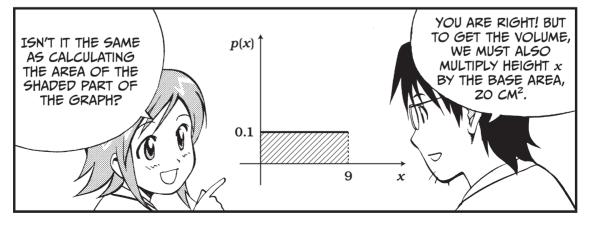


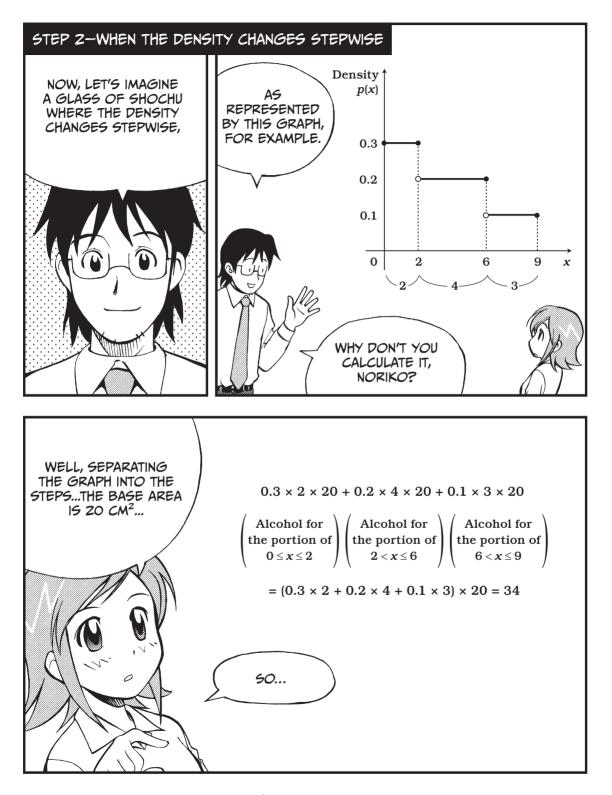
ILLUSTRATING THE FUNDAMENTAL THEOREM OF CALCULUS



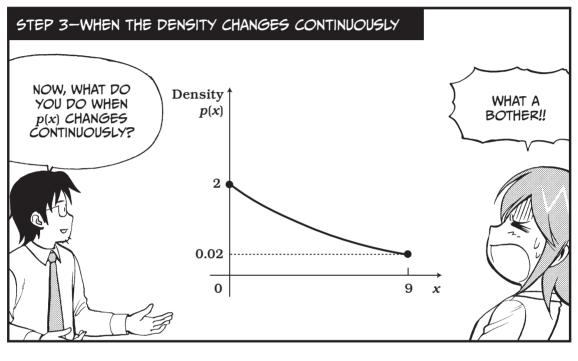


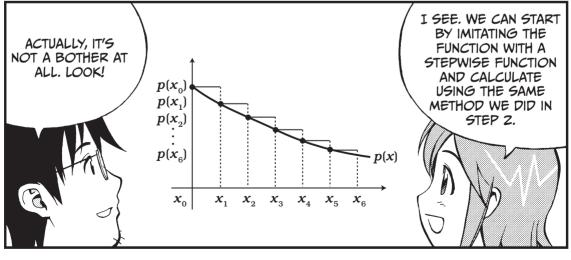




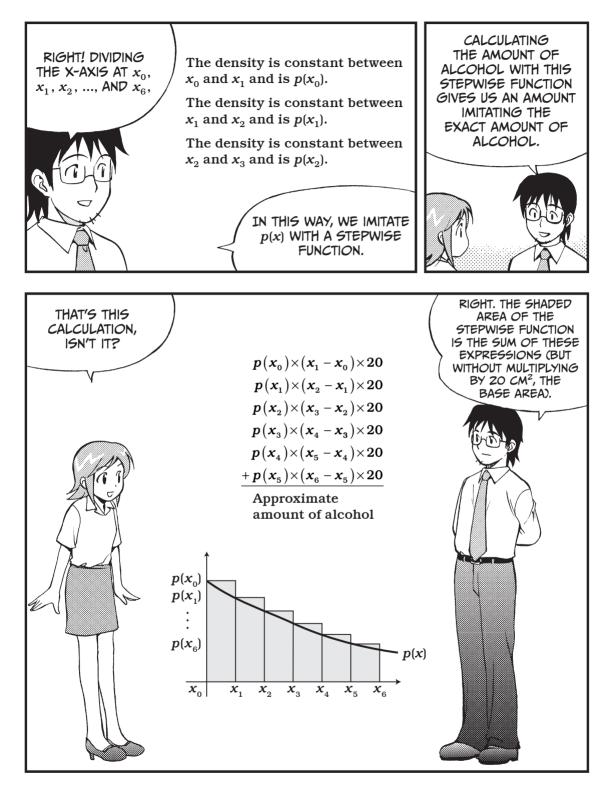








ILLUSTRATING THE FUNDAMENTAL THEOREM OF CALCULUS 85





#### STEP 4-REVIEW OF THE IMITATING LINEAR FUNCTION

When the derivative of f(x) is given by f'(x), we had  $f(x) \approx f'(a) (x - a) + f(a)$ near x = a.

Transposing f(a), we get

 $f(x) - f(a) \approx f'(a)(x-a)$ 

or (Difference in f)  $\approx$  (Derivative of f)  $\times$  (Difference in x)

If we assume that the interval between two consecutive values of  $x_0, x_1, x_2, x_3, ..., x_6$  is small enough,  $x_1$  is close to  $x_0, x_2$  is close to  $x_1$ , and so on.

Now, let's introduce a new function, q(x), whose derivative is p(x). This means q'(x) = p(x).

Using **0** for this q(x), we get

(Difference in q)  $\approx$  (Derivative of q)  $\times$  (Difference in x)

$$q(\mathbf{x}_1) - q(\mathbf{x}_0) \approx p(\mathbf{x}_0)(\mathbf{x}_1 - \mathbf{x}_0)$$
$$q(\mathbf{x}_2) - q(\mathbf{x}_1) \approx p(\mathbf{x}_1)(\mathbf{x}_2 - \mathbf{x}_1)$$

The sum of the right sides of these expressions is the same as the sum of the left sides.

Some terms in the expressions for the sum cancel each other out.

$$q(\overline{x_{1}}) - q(x_{0}) \approx p(x_{0})(x_{1} - x_{0})$$

$$q(\overline{x_{2}}) - q(\overline{x_{1}}) \approx p(x_{1})(x_{2} - x_{1})$$

$$q(\overline{x_{3}}) - q(\overline{x_{2}}) \approx p(x_{2})(x_{3} - x_{2})$$

$$q(\overline{x_{4}}) - q(\overline{x_{5}}) \approx p(x_{3})(x_{4} - x_{3})$$

$$q(\overline{x_{5}}) - q(\overline{x_{5}}) \approx p(x_{4})(x_{5} - x_{4})$$

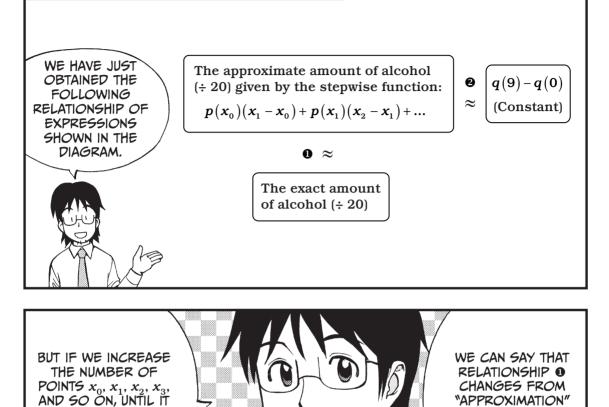
$$+ q(x_{6}) - q(\overline{x_{5}}) \approx p(x_{5})(x_{6} - x_{5})$$

$$q(\overline{x_{6}}) - q(\overline{x_{0}}) \approx \text{ The sum}$$
Substituting  $x_{6} = 9$  and  $x_{0} = 0$ , we get  
The approximate amount of alcohol = the sum × 20  

$$\{q(x_{6}) - q(x_{0})\} \times 20$$

$$\{q(9) - q(0)\} \times 20$$

#### STEP 5-APPROXIMATION → EXACT VALUE

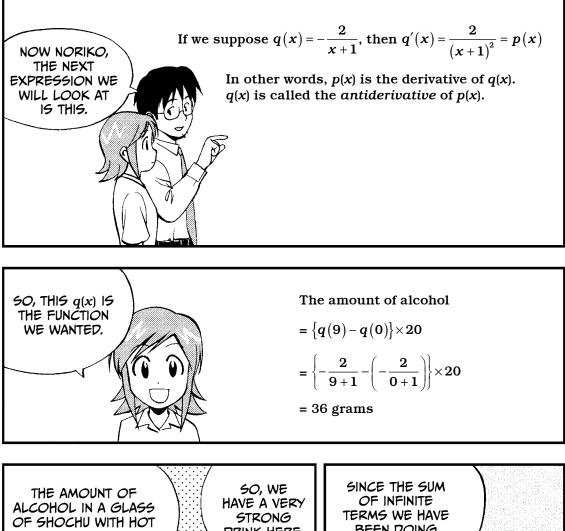


BECOMES INFINITE, TO "EQUALITY." BUT, SINCE THE SUM OF THE EXPRESSIONS The sum of  $p(x_i)(x_{i+1} - x_i)$ q(9) - q(0)= HAVE BEEN IMITATING for an infinite number of  $x_i$ THE CONSTANT VALUE q(9) - q(0), 1 11 The exact amount of alcohol  $(\div 20)$ WE GET THE RELATIONSHIP SHOWN HERE."

\* WE WILL OBTAIN THIS RELATIONSHIP MORE RIGOROUSLY ON PAGE 94.

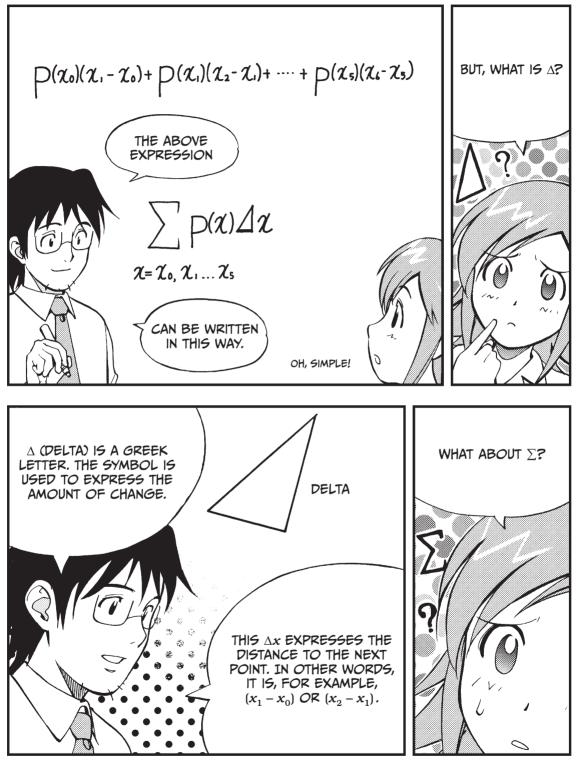
"APPROXIMATION"

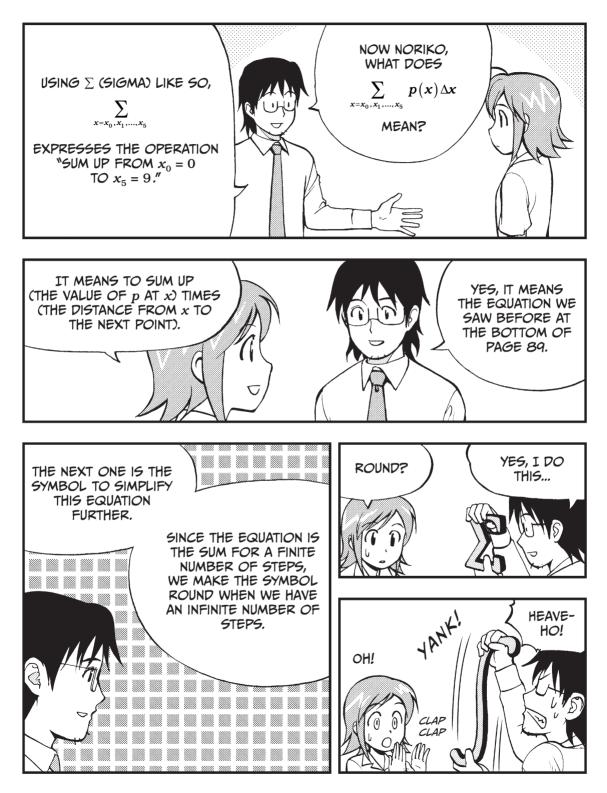
## STEP 6-p(x) is the derivative of q(x)

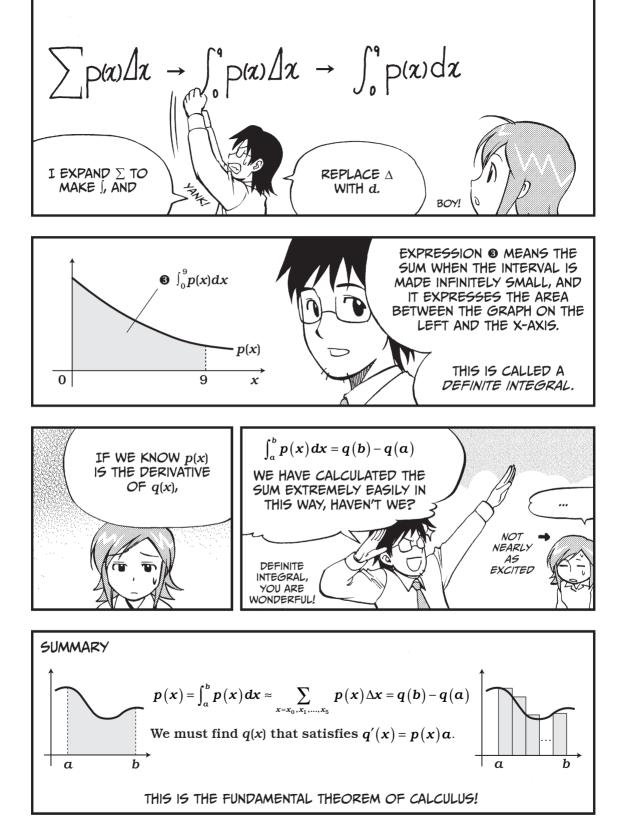




## USING THE FUNDAMENTAL THEOREM OF CALCULUS







USING THE FUNDAMENTAL THEOREM OF CALCULUS 93

#### A STRICT EXPLANATION OF STEP 5

In the explanation given before (page 89), we used, as the basic expression,  $q(x_1) - q(x_0) \approx p(x_0)(x_1 - x_0)$ , a "crude" expression which roughly imitates the exact expression. For those who think this is a sloppy explanation, we will explain more carefully here. Using the mean value theorem, we can reproduce the same result.

We first find q(x) that satisfies q'(x) = p(x).

We place points  $x_0 (= a)$ ,  $x_1$ ,  $x_2$ ,  $x_3$ , ...,  $x_n (= b)$  on the x-axis.

We then find point  $x_{01}$  that exists between  $x_0$  and  $x_1$  and satisfies  $q(x_1) - q(x_0) \approx q'(x_{01})(x_1 - x_0)$ .

The existence of such a point is guaranteed by the mean value theorem. Similarly, we find  $x_{12}$ between  $x_1$  and  $x_2$  and get

$$\boldsymbol{q}(\boldsymbol{x}_{2}) - \boldsymbol{q}(\boldsymbol{x}_{1}) \approx \boldsymbol{q}'(\boldsymbol{x}_{12})(\boldsymbol{x}_{2} - \boldsymbol{x}_{1})$$

Repeating this operation, we get

 $[x_0 = a]$ 

p(x)

 $[x_n = b]$ 

Areas of these steps

This corresponds to the diagram in step 5.

USING INTEGRAL FORMULAS

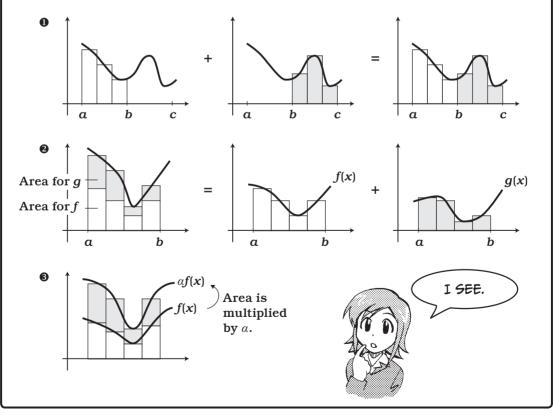
FORMULA 3-1: THE INTEGRAL FORMULAS

The intervals of definite integrals of the same function can be joined.

A definite integral of a sum can be divided into the sum of definite integrals.

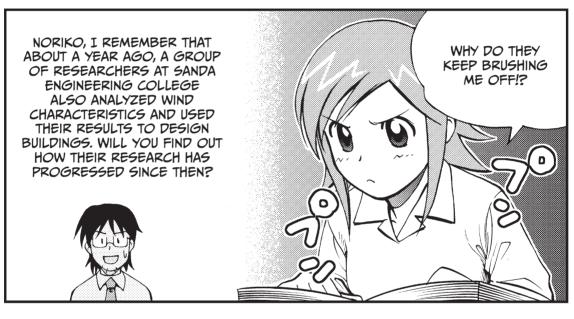
The multiplicative constant within a definite integral can be moved outside the integral.

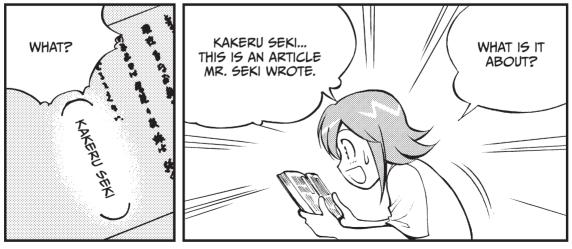
Expressions  ${\bf 0}$  through  ${\bf 0}$  can be understood intuitively if we draw their figures.







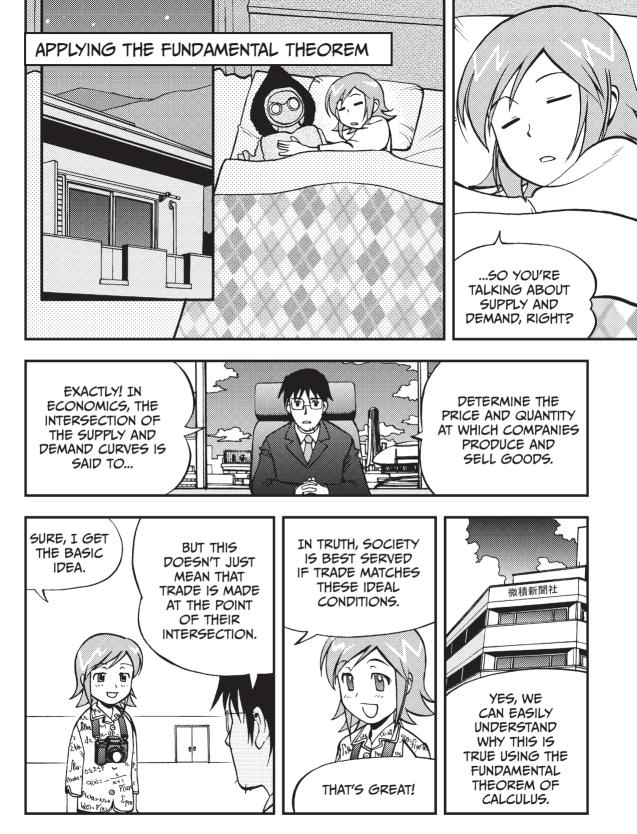


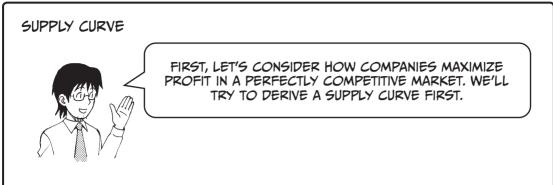












The profit P(x) when x units of a commodity are produced is given by the following function:

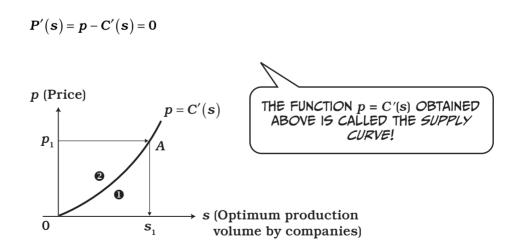


 $(Profit) = (Price) \times (Production Quantity) - (Cost) = px - C(x)$ 

where C(x) is the cost of production.

Let's assume the x value that maximizes the profit P(x) is the quantity of production s.

A company wants to maximize its profits. Recall that to find a function's extrema, we take the derivative and set it to zero. This means that the company's maximum profit occurs when



Price  $p_1$  corresponds to point A on the function, which leads us to optimum production volume  $s_1$ .

The rectangle bounded by these four points  $(p_1, A, s_1, and the origin)$  equals the price multiplied by the production quantity. This should be the companies' gross profits, before subtracting their costs of production. But look, the area **0** of this graph corresponds to the companies' production costs, and we can obtain it using an integral.

$$\int_{0}^{s_{1}} \mathbf{C}'(\mathbf{s}) d\mathbf{s} = \mathbf{C}(\mathbf{s}_{1}) - \mathbf{C}(\mathbf{0}) = \mathbf{C}(\mathbf{s}_{1}) = \text{Costs}$$
We used To simplify,  
the Fundamental we assume  
Theorem here.  $C(\mathbf{0}) = \mathbf{0}.$ 

This means we can easily find the companies' net profit, which is represented by area  $\Theta$  in the graph, or the area of the rectangle minus area  $\mathbf{0}$ .

#### DEMAND CURVE

Next, let's consider the maximum benefit for consumers.

When consumers purchase x units of a commodity, the benefit B(x) for them is given by the equation:

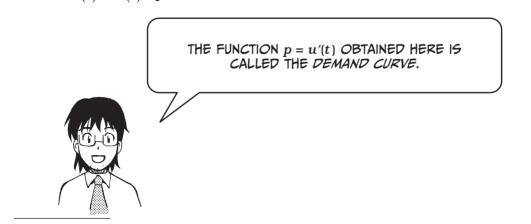
B(x) = Total Value of Consumption – (Price × Quantity) = u(x) - px

where u(x) is a function describing the value of the commodity for all consumers.

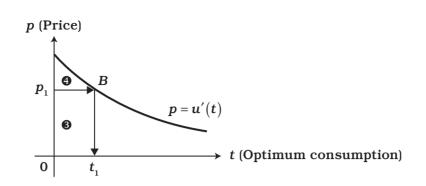
Consumers will purchase the most of this commodity when B(x) is maximized.

If we set the consumption value to t when the derivative of B(x) = 0, we get the following equation:<sup>\*</sup>

$$B'(t) = u'(t) - p = 0$$



\* Again, you can see we're looking for extrema (where B'(t) = 0), as consumers want to maximize their benefits.



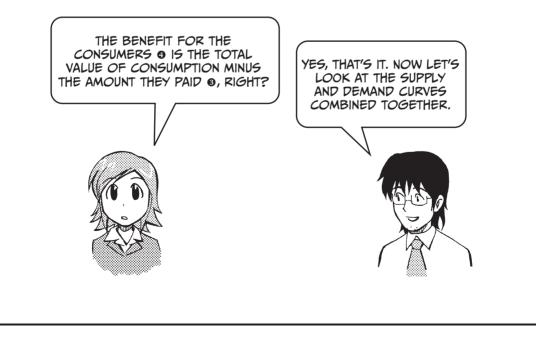
So let's consider the area of the rectangle labeled  $\Theta$ , above, which corresponds to the price multiplied by the product consumption. In other words, this is the total amount consumers pay for a product.

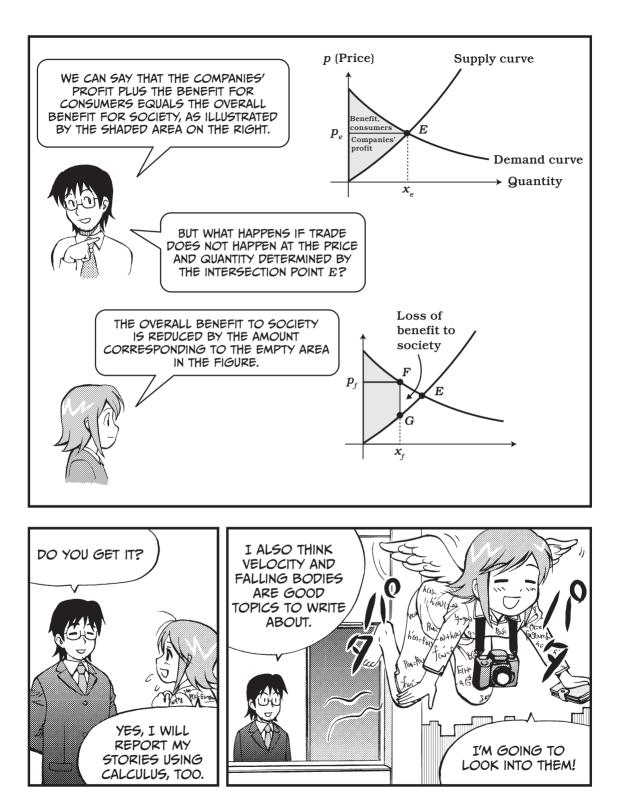
The total area of  $\Theta$  and  $\Theta$  can be obtained using integration.

$$\int_{0}^{t_{1}} u'(t) dt = u(t_{1}) - u(0) = u(t_{1}) = \text{Total value of consumption}$$
To simplify,  
we assume

u(0) = 0.

If you simply subtract the value of the rectangle  $\Theta$  from the integral from 0 to  $t_1$ , you can find the area of  $\Theta$ , the benefit to consumers.





¥50

Vol. 1

### The Integral of Velocity Proven to Be Distance!

The integral of velocity = difference in position = distance traveled

If we understand this formula, it's said that we can correctly calculate the distance traveled for objects whose velocity changes constantly. But is that true? Our promising freshman reporter Noriko Hikima closes in on the truth of this matter in her hard-hitting report.

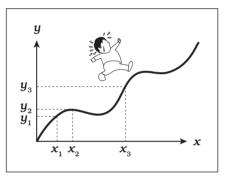


Figure 1: This graph represents Futoshi's distance traveled over time. He moves to point  $y_1, y_2, y_3...$ as time progresses to  $x_1, x_2, x_3...$ 

Sanda-Cho—Some readers will recall our earlier example describing Futoshi walking on a moving walkway. Others have likely deliberately blocked his sweaty image from their minds. But you almost certainly remember that the derivative of the distance is the speed.

$$y = F(x)$$

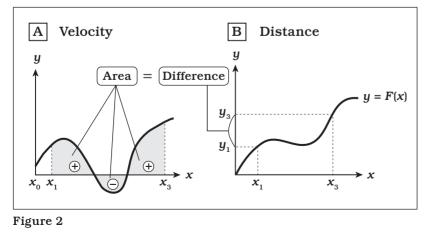
$$\int_{a}^{b} v(x) dx = F(b) - F(a)$$

Equation ① expresses the position of the monstrous, sweating Futoshi. In other words, after x seconds he has lumbered a total distance of y.

#### Integral of Velocity = Difference in Position

The derivative F'(x) of expression **0** is the "instantaneous velocity" at x seconds. If we rewrite F'(x) as v(x), using v for velocity, the Fundamental Theorem of Calculus can be used to obtain equation **0**! Look at the graph of v(x) in Figure 2-A— Futoshi's velocity over time. The shaded part of the graph is equal to the integral equation **0**.

But also look at Figure 2-B, which shows the distance Futoshi has traveled over time. If we look at Figures 2-A and 2-B side by side, we see that the integral of the velocity is equal to the difference in position (or distance)! Notice how the two



graphs match when Futoshi's velocity is positive, his distance increases, and vice versa.

#### Free Fall from Tokyo Tower How Many Seconds to the Ground?

It's easy to take things for granted consider gravity. If you drop an object from your hand, it naturally falls to the ground. We can say that this is a motion that changes every second—it is *accelerating* due to the Earth's gravitational pull. This motion can be easily described using calculus.

But let's consider a bigger drop—all the way from the top of Tokyo Tower—and find out, "How many seconds does it take an object to reach the ground?" Pay no attention to Futoshi's remark, "Why don't you go to the top of Tokyo Tower with a stopwatch and find out for yourself?"

The increase in velocity when an object is in free fall is called *gravitational* acceleration, or  $9.8 \text{ m/s}^2$ . In other words, this means that an object's velocity increases by 9.8 m/s every second. Why is this the rate of acceleration? Well, let's just assume the scientists are right for today.

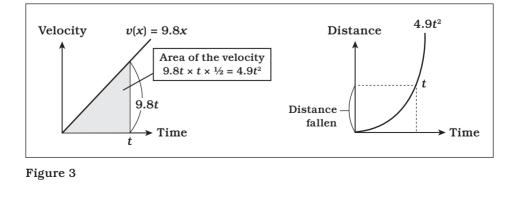
Expression **0** gives the distance the object falls in T seconds. Since the integral of the velocity is the difference in position (or the distance the object travels), equation **2** can be derived. Look at Figure 3—we've calculated the area by taking half of the product of the x and y values—in this case,  $\frac{1}{2} \times 9.8t \times t$ . And we know that the height of Tokyo Tower is 333 m. The square root of (333 / 4.9) equals about 8.2, so an object takes about 8.2 seconds to reach the ground. (We've neglected air resistance here for convenience.)

init it that

 $\mathbf{O} \quad \mathbf{F}(\mathbf{T}) - \mathbf{F}(\mathbf{O}) = \int_0^T \boldsymbol{v}(\mathbf{x}) d\mathbf{x} = \int_0^T \mathbf{9.8}(\mathbf{x}) d\mathbf{x}$ 

$$\mathbf{2} \quad \mathbf{4.9T}^2 - \mathbf{4.9} \times \mathbf{0}^2 = \mathbf{4.9T}^2$$

$$333 = 4.9T^2 \Rightarrow T = \sqrt{\frac{333}{4.9}} = 8.2 \text{ seconds}$$



#### The Die Is Cast!!! The Fundamental Theorem of Calculus Applies to Dice, Too

f(x)

<sup>1</sup>/<sub>6</sub>

You probably remember playing games with dice as a child. Since ancient times, these hexahedrons have been rolled around the world, not only in games, but also for fortune telling and gambling.

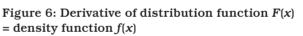
Mathematically, you can say that dice are the world's smallest random-number generator. Dice are wonderful. Now we'll cast them for calculus! A die can show a 1, 2, 3, 4, 5, or 6-the probability of any one number is 1 in 6. This can be shown with a histogram (Figure 4), with their numbers on the x-axis and the probability on the y-axis.

This can be expressed by equation  $\mathbf{0}$ , or f(x) = Probability of rolling x. This becomes equation **2** when we try to predict a single result-for example, a roll of 4.

- f(x) = Probability of rolling x
- $f(4) = \frac{1}{6}$  = Probability of rolling 4

Now let's take a look at Figure 5, which describes a distribution function. First, start at 1 on the x-axis. Since no number less than 1 exists on a die, the probability in this region is 0. At x = 1, the graph jumps to 1/6, because the probability of rolling a number less than or equal to 1 is 1 in 6. You can also see that the probability of rolling a number equal to or greater than 1 and less than 2 is 1/6 as well. This should make intuitive sense. At 2, the probability jumps up to 2/6, which means the probability for rolling a number equal to or less than 2 is 2/6. Since this probability remains until

F(x)

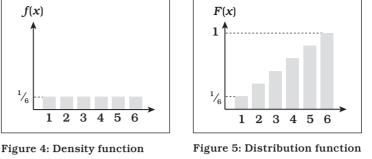


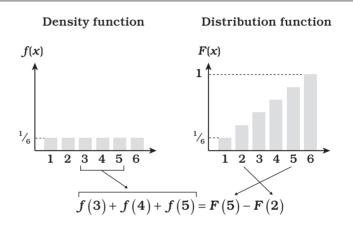
right below 3, the probability of numbers less than 3 is 2/6.

= Probability of rolling *x* where  $a \le x \le b$ 

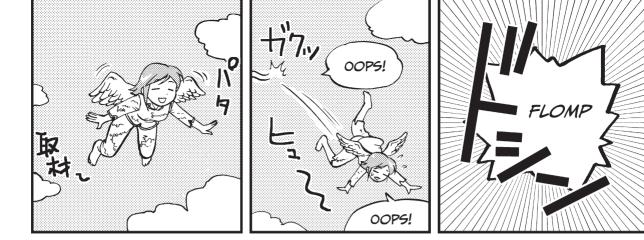
In the same way, we can find that the probability of rolling a 6 or any number smaller than 6 (that is, any number on the die) is 1. After all, a die cannot stand on one of its corners. Now let's look at the probability of rolling numbers greater than 2 and equal to or less than 5. The equation in Figure 6 explains this relationship.

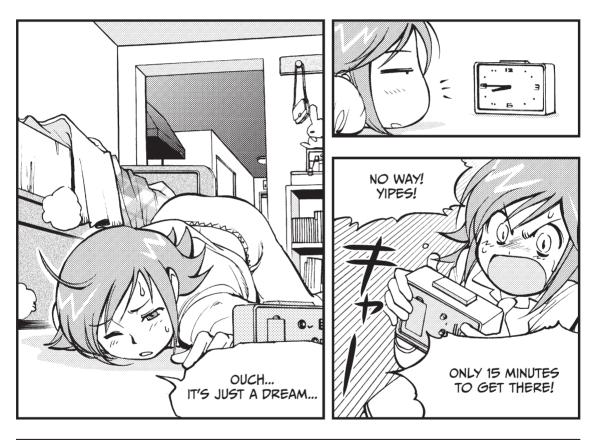
If we look at equation **(6)**, we see that it describes what we know—"A definite integral of a differentiated function = The difference in the original function." This is nothing but the Fundamental Theorem of Calculus! How wonderful dice are.



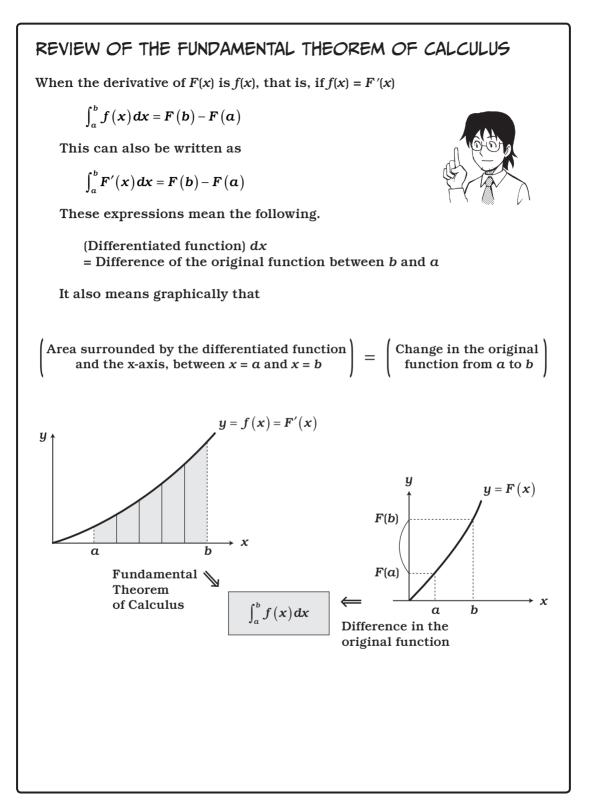


Section A1









### FORMULA OF THE SUBSTITUTION RULE OF INTEGRATION

When a function of y is substituted for variable x as x = g(y), how do we express

$$\mathbf{S} = \int_{a}^{b} f(\mathbf{x}) d\mathbf{x}$$

a definite integral with respect to x, as a definite integral with respect to y?

First, we express the definite integral in terms of a stepwise function approximately as

$$\mathbf{S} \approx \sum_{k=0,1,2,\dots,n-1} f(\mathbf{x}_k) (\mathbf{x}_{k+1} - \mathbf{x}_k) \quad (\mathbf{x}_0 = \mathbf{a}, \mathbf{x}_n = \mathbf{b})$$

Transforming variable x as x = g(y), we set

$$\boldsymbol{y}_0 = \boldsymbol{\alpha}, \boldsymbol{y}_1, \boldsymbol{y}_2, \dots, \boldsymbol{y}_n = \boldsymbol{\beta}$$

so that

$$\boldsymbol{a} = \boldsymbol{g}(\alpha), \boldsymbol{x}_1 = \boldsymbol{g}(\boldsymbol{y}_1), \boldsymbol{x}_2 = \boldsymbol{g}(\boldsymbol{y}_2), \dots, \boldsymbol{b} = \boldsymbol{g}(\beta)$$

Note here that using an approximate linear function of

 $\boldsymbol{x}_{k+1} - \boldsymbol{x}_{k} = \boldsymbol{g}(\boldsymbol{y}_{k+1}) - \boldsymbol{g}(\boldsymbol{y}_{k}) \approx \boldsymbol{g}'(\boldsymbol{y}_{k})(\boldsymbol{y}_{k+1} - \boldsymbol{y}_{k})$ 

Substituting these expressions in S, we get

$$\mathbf{S} \approx \sum_{k=0,1,2,\dots,n-1} f(\mathbf{x}_k) (\mathbf{x}_{k+1} - \mathbf{x}_k) \approx \sum_{k=0,1,2,\dots,n-1} f(\mathbf{g}(\mathbf{y}_k)) \mathbf{g}'(\mathbf{y}_k) (\mathbf{y}_{k+1} - \mathbf{y}_k)$$

The last expression is an approximation of

$$\int_{lpha}^{eta} fig(oldsymbol{g}(oldsymbol{y})ig)oldsymbol{g}'(oldsymbol{y})doldsymbol{y}$$

Therefore, by making the divisions infinitely small, we obtain the following formula.

FORMULA 3-2: THE SUBSTITUTION RULE OF INTEGRATION

$$\int_{a}^{b} f(\boldsymbol{x}) d\boldsymbol{x} = \int_{a}^{\beta} f(\boldsymbol{g}(\boldsymbol{y})) \boldsymbol{g}'(\boldsymbol{y}) d\boldsymbol{y}$$

EXAMPLE:

Calculate:

$$\int_0^1 10 \left(2x+1\right)^4 dx$$

We first substitute the variable so that y = 2x + 1, or  $x = g(y) = \frac{y-1}{2}$ .

Since y = 2x + 1, if we take the derivative of both sides, we get dy = 2dx. Then we get  $dx = \frac{1}{2}dy$ .

Since we now integrate with respect to y, the new interval of integration is obtained from 0 = g(1) and 1 = g(3) to be 1 - 3.<sup>\*</sup>

$$\int_{0}^{1} 10 (2x+1)^{4} dx = \int_{1}^{3} 10y^{4} \frac{1}{2} dy = \int_{1}^{3} 5y^{4} dy = 3^{5} - 1^{5} = 242$$

#### THE POWER RULE OF INTEGRATION

In the example above we remembered that  $5y^4$  is the derivative of  $y^5$  to finish the problem. Since we know that if  $F(x) = x^n$ , then  $F'(x) = f(x) = nx^{(n+1)}$ , we should be able to find a general rule for finding F(x) when  $f(x) = x^n$ . We know that F(x) should have  $x^{(n+1)}$  in it, but what about that coef-

We know that F(x) should have  $x^{(n+1)}$  in it, but what about that coefficient? We don't have a coefficient in our derivative, so we'll need to start with one. When we take the derivative, the coefficient will be (n + 1), so it follows that 1 / (n + 1) will cancel it out. That means that the general rule for finding the antiderivative F(x) of  $f(x) = x^n$  is

$$F(x) = \frac{1}{n+1} \times x^{(n+1)} = \frac{x^{(n+1)}}{n+1}$$

<sup>\*</sup> In other words, when x = 0, y = 1, and when x = 1, y = 3. We then use that as the range of our definite integral.

## EXERCISES

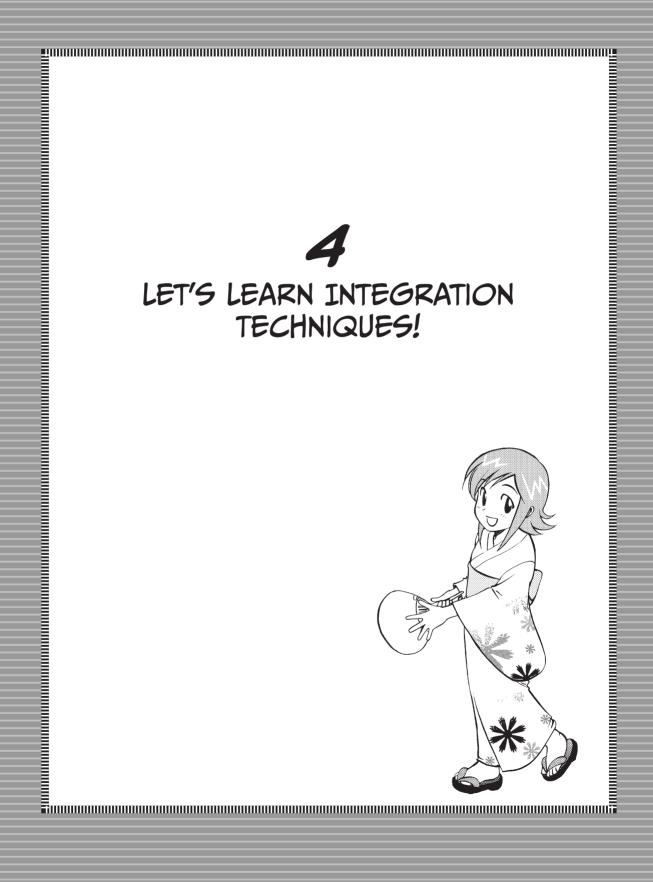
1. Calculate the definite integrals given below.

$$\int_{1}^{3} 3x^{2} dx$$

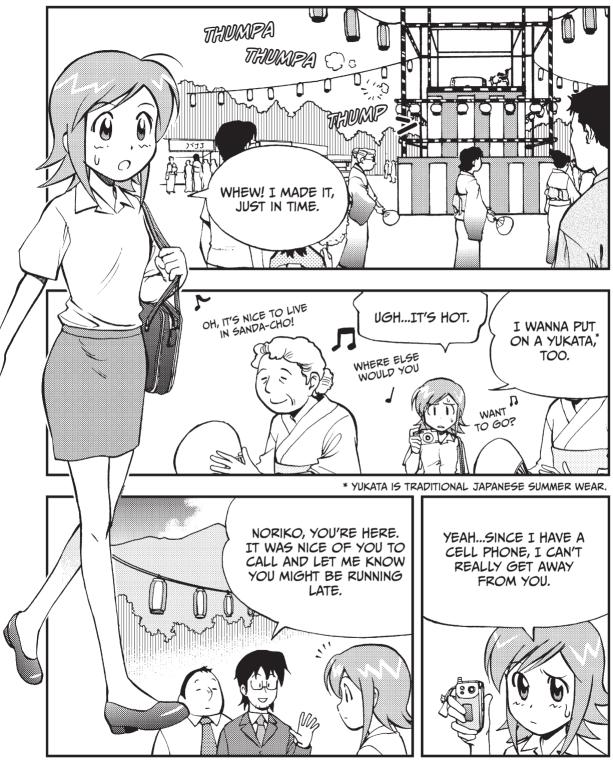
$$\int_{2}^{4} \frac{x^{3} + 1}{x^{2}} dx$$

$$\int_{0}^{5} x + (1 + x^{2})^{7} dx + \int_{0}^{5} x - (1 + x^{2})^{7} dx$$

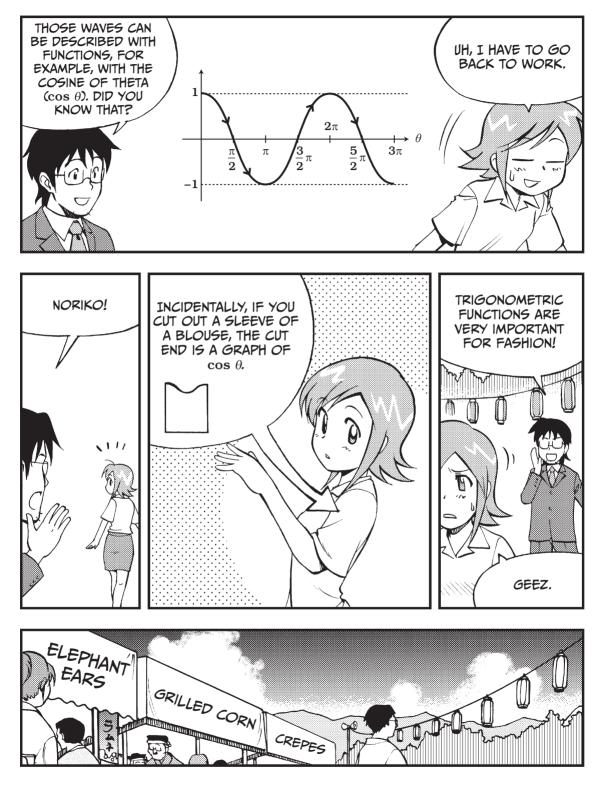
- z. Answer the following questions.
  - A. Write an expression of the definite integral which calculates the area surrounded by the graph of  $y = f(x) = x^2 3x$  and the x-axis.
  - B. Calculate the area given by this expression.

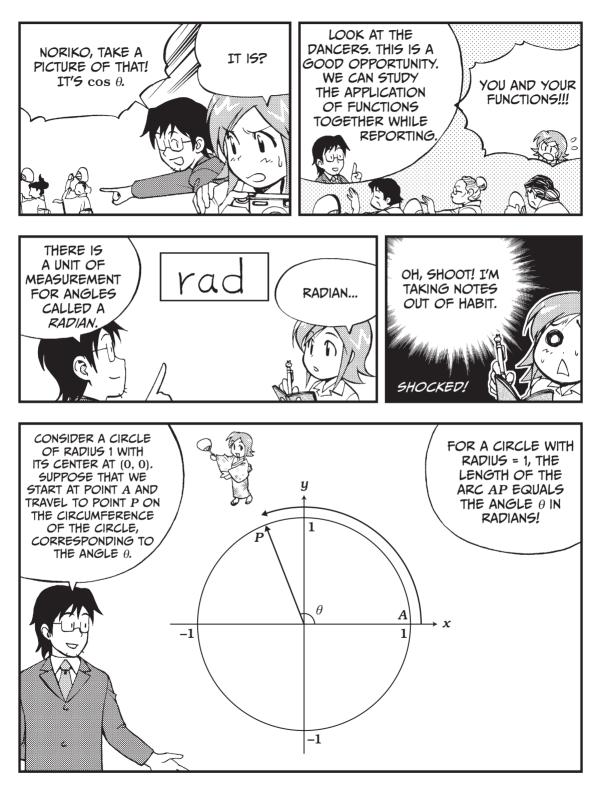


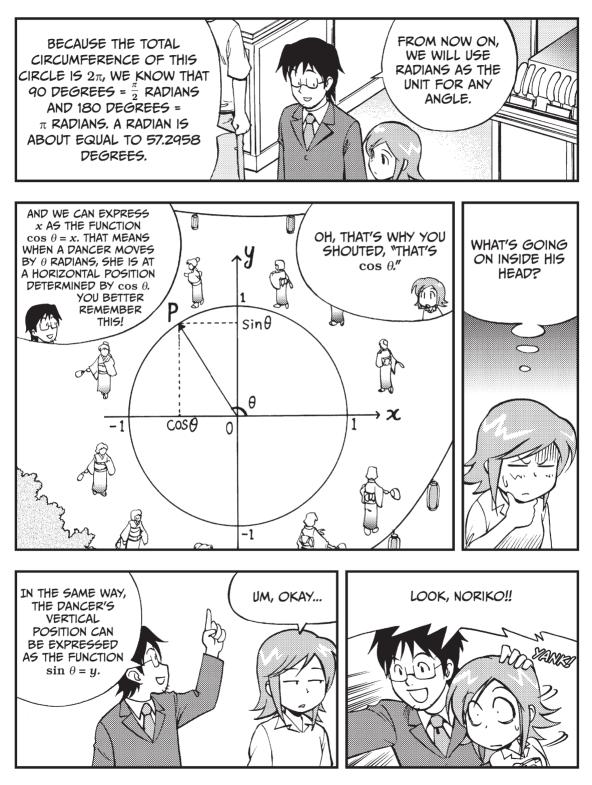
# USING TRIGONOMETRIC FUNCTIONS

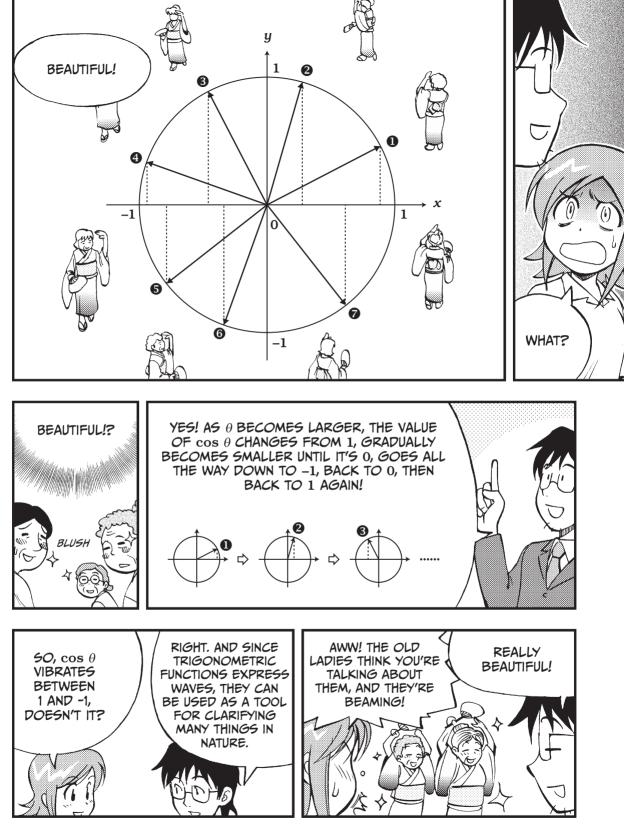






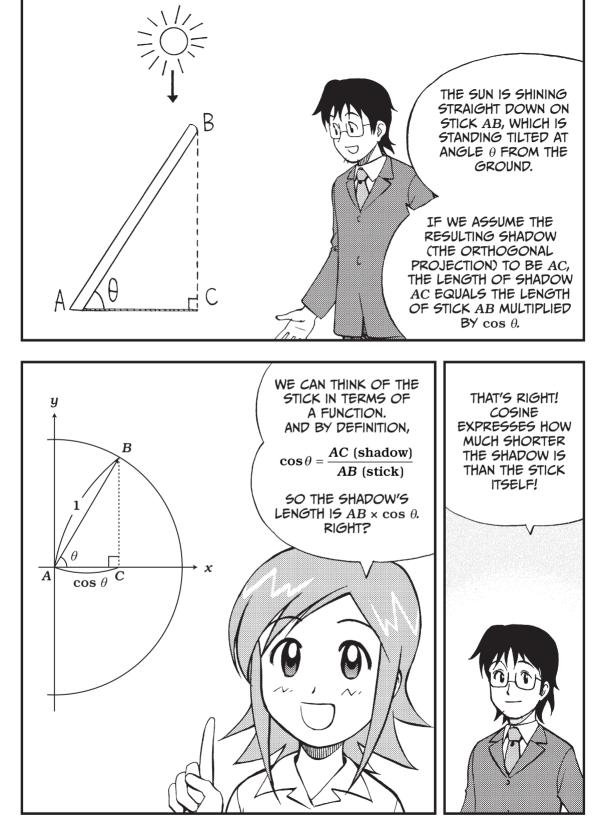


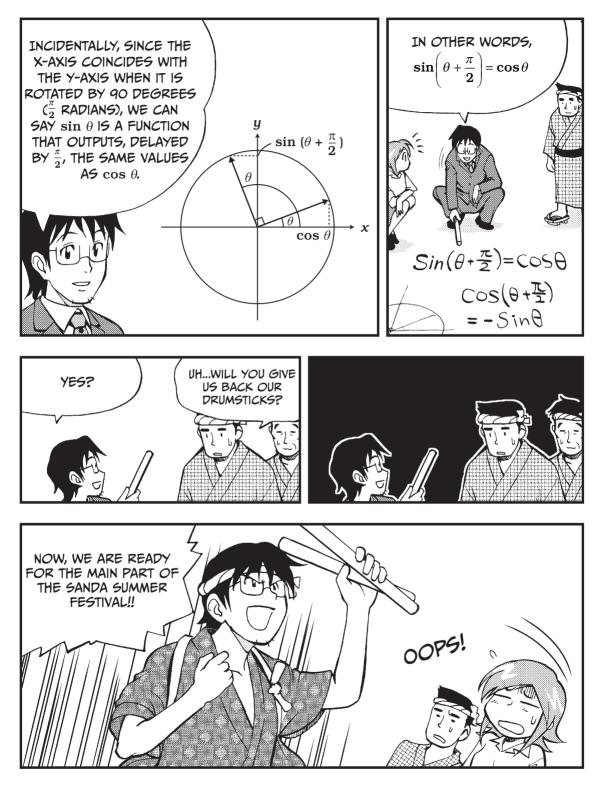




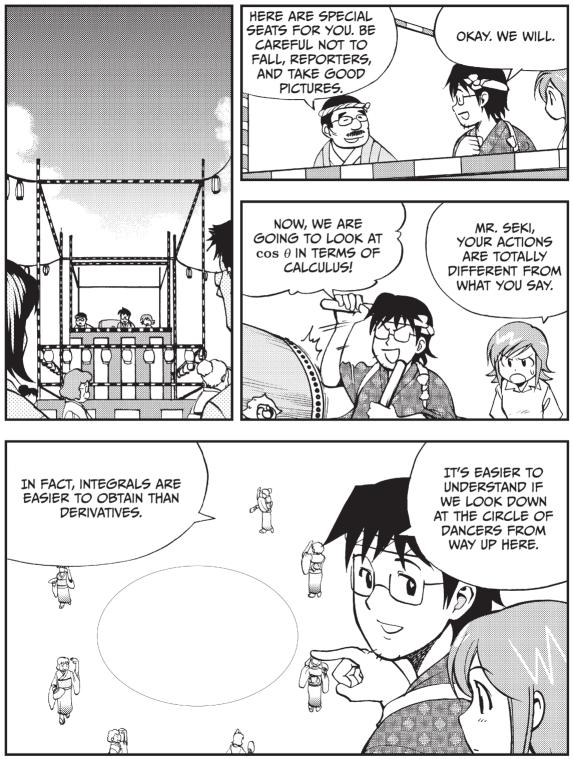


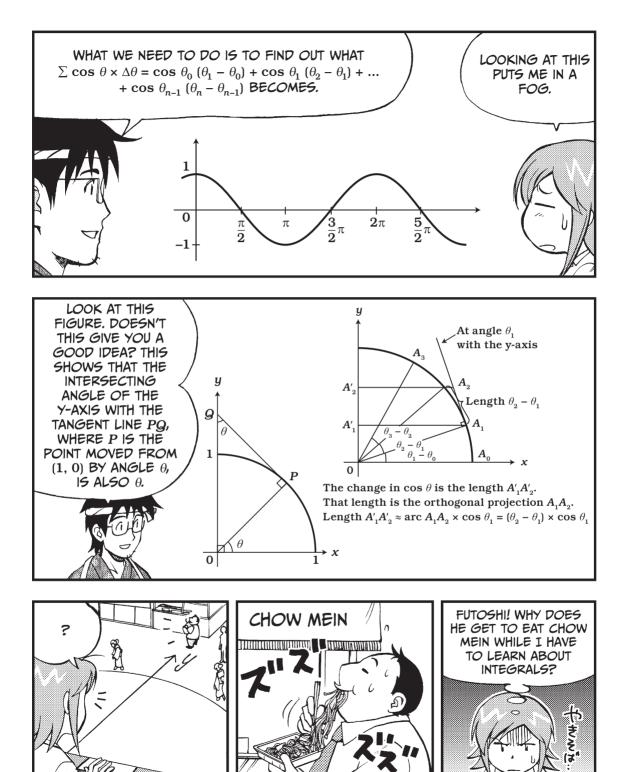
122 CHAPTER 4 LET'S LEARN INTEGRATION TECHNIQUES!



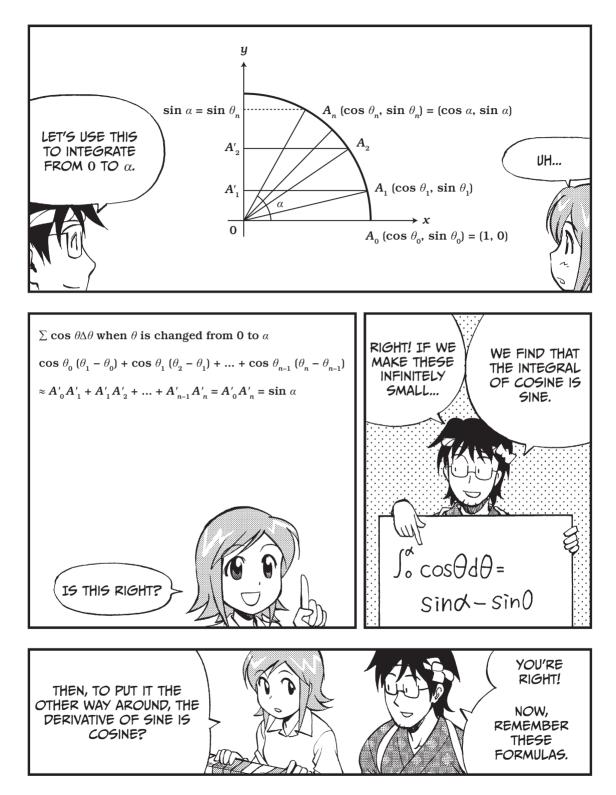


### USING INTEGRALS WITH TRIGONOMETRIC FUNCTIONS





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FORMULA 4-1: THE DIFFERENTIATION AND INTEGRATION OF TRIGONOMETRIC FUNCTIONS Since **1**  $\int_{0}^{\alpha} \cos\theta d\theta = \sin\alpha - \sin 0$ , we know that sine must be cosine's derivative. **2**  $(\sin\theta)' = \cos\theta$ 

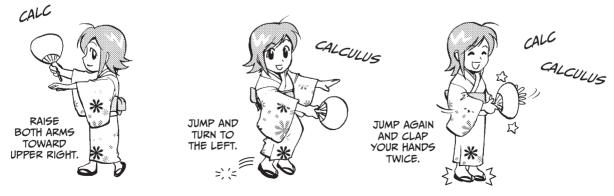
Now, substitute  $\theta + \frac{\pi}{2}$  for  $\theta$  in  $\Theta$ . We get  $\left\{ \sin\left(\theta + \frac{\pi}{2}\right) \right\}' = \cos\left(\theta + \frac{\pi}{2}\right)$ . Using the equations from page 124, we then know that

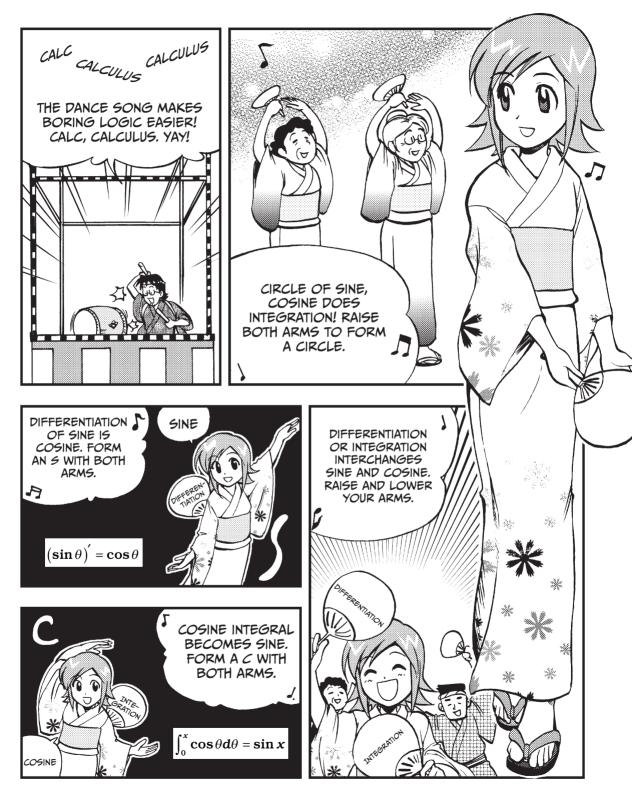
$$(\cos\theta)' = -\sin\theta$$

We find that differentiating or integrating sine gives cosine and vice versa.



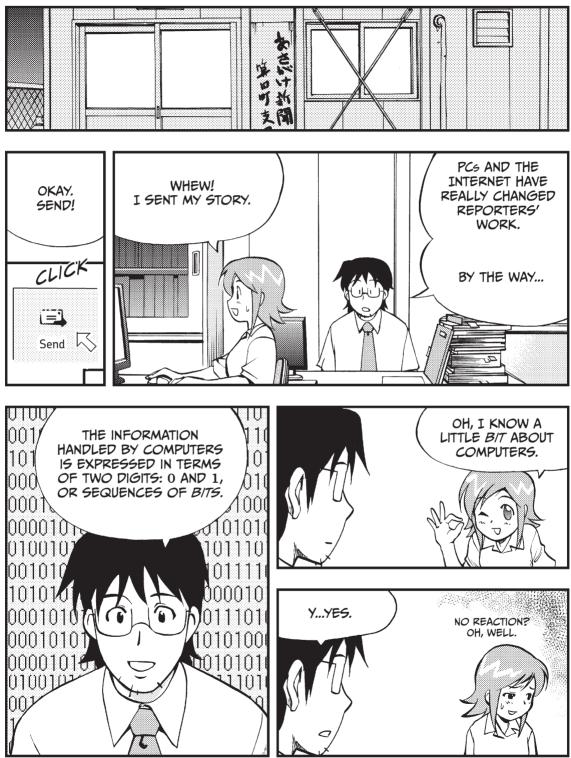
CALCULUS DANCE SONG TRIGONOMETRIC VERSION

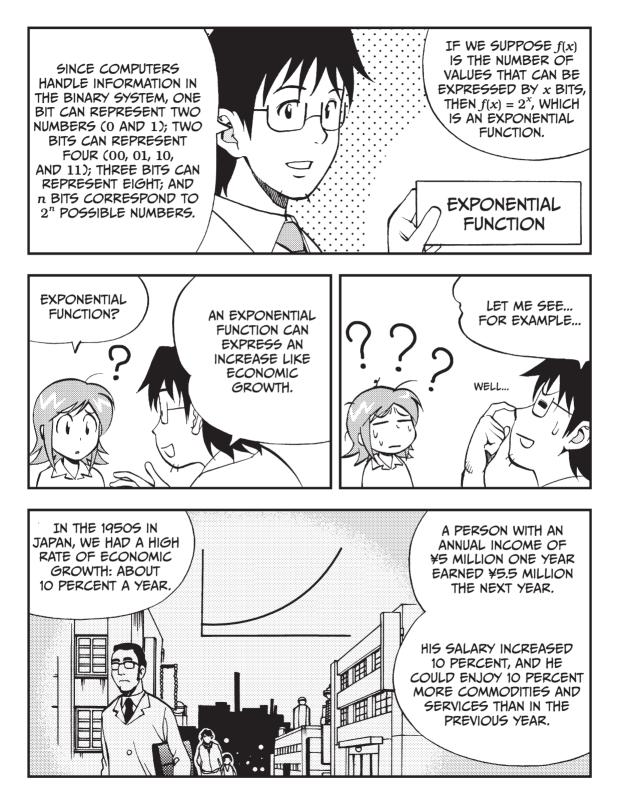


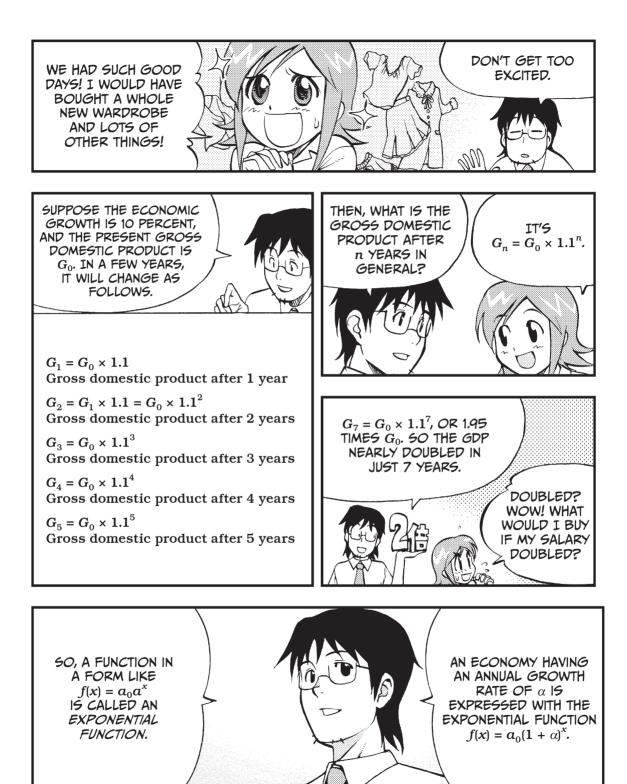


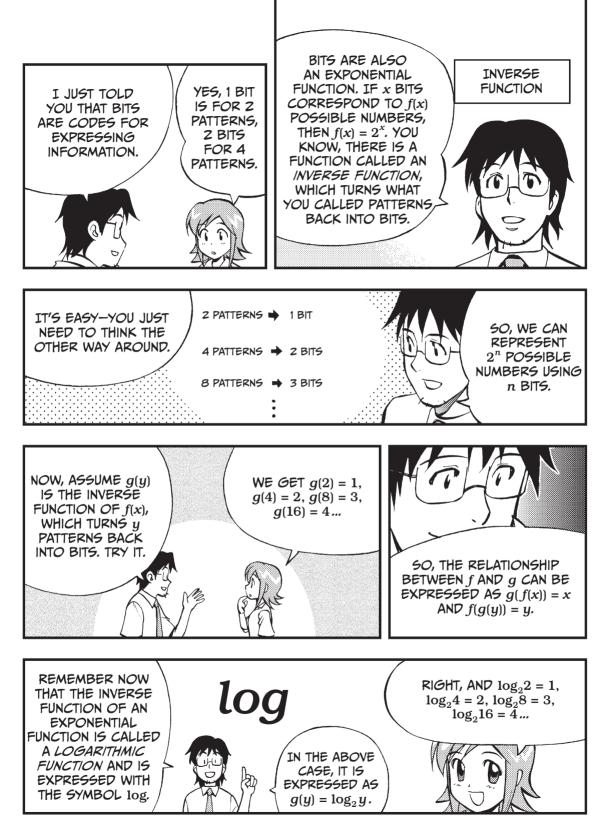


# USING EXPONENTIAL AND LOGARITHMIC FUNCTIONS

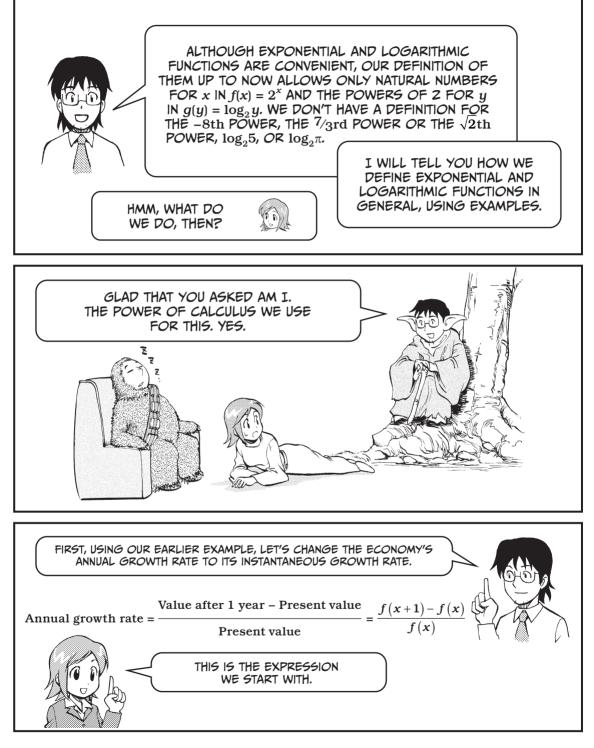


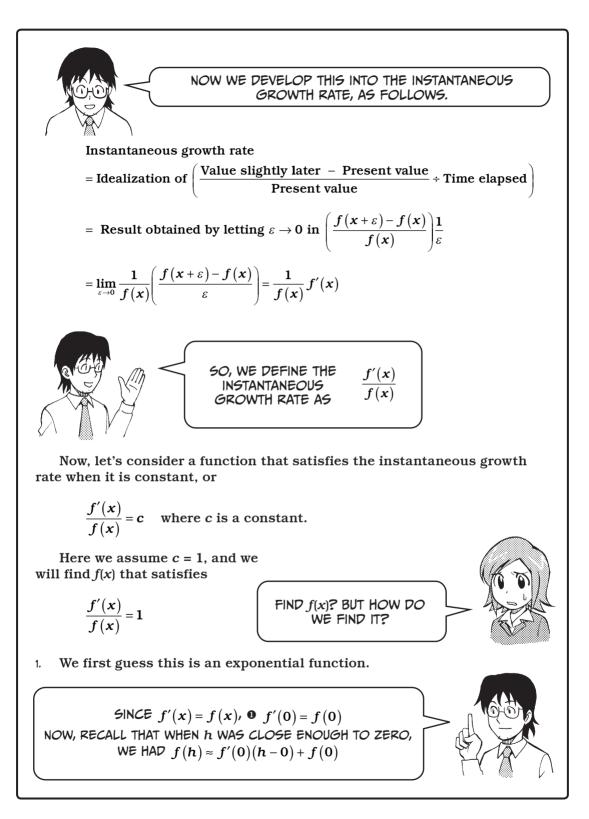






#### GENERALIZING EXPONENTIAL AND LOGARITHMIC FUNCTIONS





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From **0**, we have  $f(h) \approx f(0)h + f(0)$  and get

 $\Theta \quad f(h) \approx f(0)(h+1)$ 

If x is close enough to h, we have

$$f(\mathbf{x}) \approx f'(\mathbf{h})(\mathbf{x}-\mathbf{h}) + f(\mathbf{h})$$

Replacing x with 2h and using f'(h) = f(h),

$$egin{aligned} &f(2h)pprox f'(h)(2h-h)+f(h)\ &f(2h)pprox f(h)(h)+f(h)\ &f(2h)pprox f(h)(h+1) \end{aligned}$$

We'll then substitute  $f(h) \approx f(0)(h+1)$  into our equation.

.)

$$f(2h) \approx f(0)(h+1)(h+1)$$
$$f(2h) \approx f(0)(h+1)^{2}$$

In the same way, we substitute 3h, 4h, 5h, ..., for x and allow mh = 1.

$$f(1) = f(mh) \approx f(0)(h+1)^m$$

Similarly,

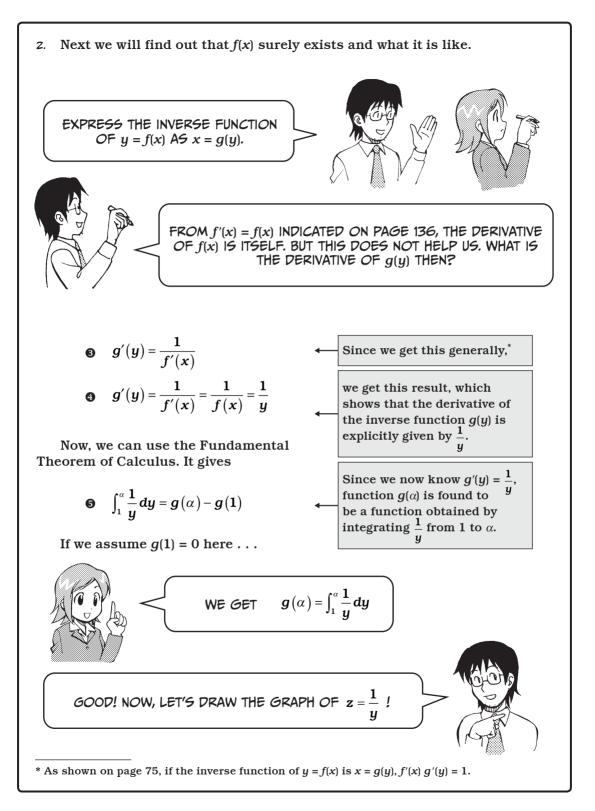
$$f(2) = f(2mh) \approx f(0)(h+1)^{2m} = f(0)\{(1+h)^m\}^2$$
$$f(3) = f(3mh) \approx f(0)(h+1)^{3m} = f(0)\{(1+h)^m\}^3$$

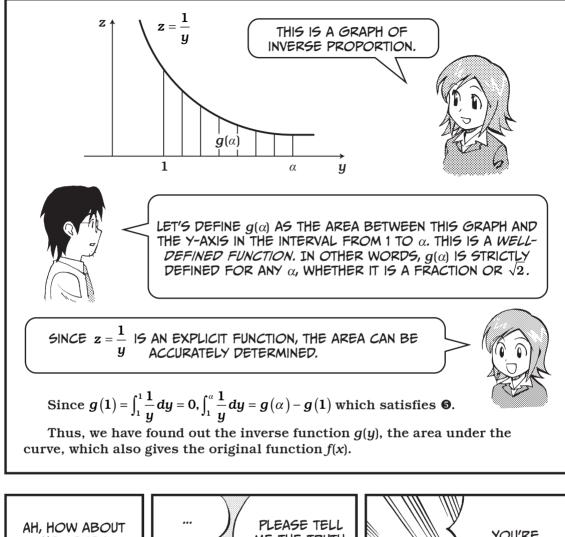
Thus, we get

$$f(n) \approx f(0)a^n$$
 where we used  $a = (1 + h)^m$ 

which is suggestive of an exponential function.\*

\* Since mh = 1,  $h = \frac{1}{m}$ . Then,  $f(1) \approx f(0) \left(1 + \frac{1}{m}\right)^m$ . If we let  $m \to \infty$  here,  $\left(1 + \frac{1}{m}\right)^m \to e$ , or Euler's number, a number about equal to 2.718. Thus,  $f(1) = f(0) \times e$ , which is consistent with the discussion on page 141.







SUMMARY OF EXPONENTIAL AND LOGARITHMIC FUNCTIONS

•  $\frac{f'(x)}{f(x)}$  is thought to be the growth rate.

**2** y = f(x) which satisfies  $\frac{f'(x)}{f(x)} = 1$  is the function that has a constant growth rate of 1.

This is an exponential function and satisfies

$$f'(\mathbf{x}) = f(\mathbf{x})$$

• If the inverse function of y = f(x) is given by x = g(y), we have

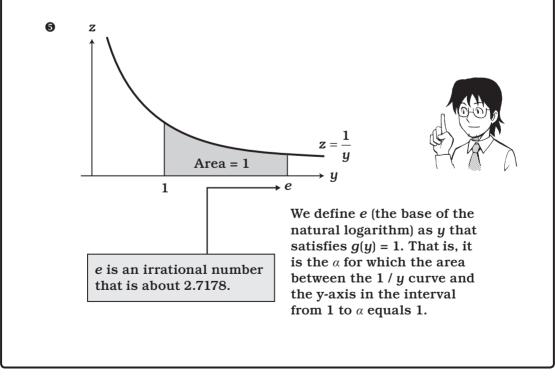
$$g'(y) = \frac{1}{y} \quad \star$$

4

If we define  $g(\alpha)$ , we can find the area of  $h(y) = \frac{1}{y}$ ,

$$\boldsymbol{g}(\alpha) = \int_{1}^{\alpha} \frac{1}{y} dy$$

The inverse function of f(x) is the function that satisfies  $\star$  and g(1) = 0.



Since f(x) is an exponential function, we can write, using constant  $a_0$ ,

$$f(\mathbf{x}) = \mathbf{a}_0 \mathbf{a}^x$$

Since  $f(g(1)) = f(0) = a_0 a^0 = a_0$  and f(g(1)) = 1, we get

$$f(\boldsymbol{g}(1)) = 1 = \boldsymbol{a}_0$$

And so we know

$$f(\mathbf{x}) = \mathbf{a}^{\mathbf{x}}$$

Similarly, since

$$f(g(e)) = f(1) = a^1$$
 and  
 $f(g(e)) = e$   
 $e = a^1$ 

Thus, we have  $f(x) = e^{x}$ .

The inverse function g(y) of this is  $\log_e y$ , which can be simply written as  $\ln y$  (ln stands for the natural logarithm).

Now let's rewrite  $\Theta$  through  $\Theta$  in terms of  $e^x$  and  $\ln y$ .

$$\bullet \quad f'(\mathbf{x}) = f(\mathbf{x}) \Leftrightarrow (\mathbf{e}^{\mathbf{x}})' = \mathbf{e}^{\mathbf{x}}$$

$$\Theta \quad g'(y) = \frac{1}{y} \Leftrightarrow (\ln y)' = \frac{1}{y}$$

**9** To define  $2^x$ , a function of bits, for any real number x, we look at

$$f(x) = e^{(\ln 2)x}$$
 (x is any real number)

The reason is as follows. Because  $e^x$  and  $\ln y$  are inverse functions to each other,

$$e^{\ln 2} = 2$$

Therefore, for any natural number x, we have

$$f(\mathbf{x}) = (\mathbf{e}^{\ln 2})^{\mathbf{x}} = 2^{\mathbf{x}}$$

MORE APPLICATIONS OF THE FUNDAMENTAL THEOREM

Other functions can be expressed in the form of  $f(x) = x^{\alpha}$ . Some of them are

$$\frac{1}{x} = x^{-1}, \frac{1}{x^2} = x^{-2}, \frac{1}{x^3} = x^{-3}, \dots$$

For such functions in general, the formula we found earlier holds true.

FORMULA 4-2: THE POWER RULE OF DIFFERENTIATION

$$f(\mathbf{x}) = \mathbf{x}^{\alpha} \qquad f'(\mathbf{x}) = \alpha \mathbf{x}^{\alpha-1}$$

EXAMPLE:

For 
$$f(x) = \frac{1}{x^3}$$
,  $f'(x) = (x^{-3})' = -3x^{-4} = -\frac{3}{x^4}$   
For  $f(x) = \sqrt[4]{x}$ ,  $f'(x) = (x^{\frac{1}{4}})' = \frac{1}{4}x^{-\frac{3}{4}} = \frac{1}{4\sqrt[4]{x^3}}$ 



PROOF:

Let's express f(x) in terms of *e*. Noting  $e^{\ln x} = x$ , we have

$$f(\boldsymbol{x}) = \boldsymbol{x}^{\alpha} = (\boldsymbol{e}^{\ln x})^{\alpha} = \boldsymbol{e}^{\alpha \ln x}$$

Thus,

 $\ln f(\mathbf{x}) = \alpha \ln \mathbf{x}$ 

Differentiating both sides, remembering that the derivative of  $\ln w = \frac{1}{w}$ , and applying the chain rule,

$$\frac{1}{f(x)} \times f'(x) = \alpha \times \frac{1}{x}$$

Therefore,

$$f'(\mathbf{x}) = \alpha \times \frac{1}{\mathbf{x}} \times f(\mathbf{x}) = \alpha \times \frac{1}{\mathbf{x}} \times \mathbf{x}^{\alpha} = \alpha \mathbf{x}^{\alpha-1}$$

#### INTEGRATION BY PARTS

If h(x) = f(x) g(x), we get from the product rule of differentiation,

$$h'(x) = f'(x)g(x) + f(x)g'(x)$$

Thus, since the function (the antiderivative) that gives f'(x) g(x) + f(x) g'(x) after differentiation is f(x) g(x), we obtain from the Fundamental Theorem of Calculus,

$$\int_{a}^{b} \left\{ f'(x)g(x) + f(x)g'(x) \right\} dx = f(b)g(b) - f(a)g(a)$$

Using the sum rule of integration, we obtain the following formula.

#### FORMULA 4-3: INTEGRATION BY PARTS

$$\int_{a}^{b} f'(x) g(x) dx + \int_{a}^{b} f(x) g'(x) dx = f(b) g(b) - f(a) g(a)$$

As an example, let's calculate:

$$\int_0^\pi x \sin x \, dx$$

We guess the integral's answer will be a similar form to  $x \cos x$ , so we say f(x) = x and  $g(x) = \cos x$ . So we try,

$$\int_{0}^{\pi} x' \cos x \, dx + \int_{0}^{\pi} x \left( \cos x \right)' \, dx = f(x) g(x) \Big|_{0}^{\pi}$$

We can evaluate that

$$= \boldsymbol{f}(\pi)\boldsymbol{g}(\pi) - \boldsymbol{f}(\mathbf{0})\boldsymbol{g}(\mathbf{0})$$

Substituting in our original functions of f(x) and g(x), we find that

$$=\pi\cos\pi-0\cos0=\pi\left(-1\right)-0=-\pi$$

We can use this result in our first equation.

$$\int_0^{\pi} \mathbf{x}' \cos \mathbf{x} \, d\mathbf{x} + \int_0^{\pi} \mathbf{x} \left(\cos \mathbf{x}\right)' \, d\mathbf{x} = -\pi$$

We then get:

$$\int_0^{\pi} \cos x \, dx + \int_0^{\pi} x \left(-\sin x\right) dx = -\pi$$

Rearranging it further by pulling out the negatives, we find:

$$\int_0^\pi \cos x\,dx - \int_0^\pi x\sin x\,dx = -\pi$$

And you can see here that we have the original integral, but now we have it in terms that we can actually solve! We solve for our original function:

$$\int_0^\pi x \sin x \, dx = \int_0^\pi \cos x \, dx + \pi$$

Remember that  $\int \cos x \, dx = \sin x$ , and you can see that

$$\int_0^{\pi} x \sin x \, dx = \sin x \Big|_0^{\pi} + \pi$$
$$= \sin \pi - \sin 0 + \pi$$
$$= 0 - 0 + \pi = \pi$$

There you have it.

## EXERCISES

- 1.  $\tan x$  is a function defined as  $\sin x / \cos x$ . Obtain the derivative of  $\tan x$ .
- z. Calculate

$$\int_0^{\frac{\pi}{4}} \frac{1}{\cos^2 x} dx$$

- 3. Obtain such x that makes  $f(x) = xe^x$  minimum.
- 4. Calculate

 $\int_{1}^{e} 2x \ln x \, dx$ 

A clue: Suppose  $f(x) = x^2$  and  $g(x) = \ln x$ , and use integration by parts.



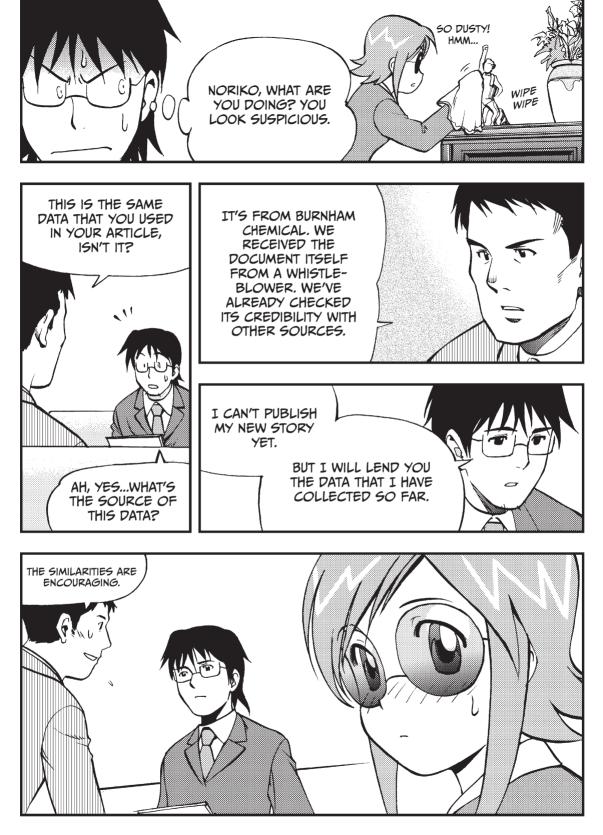




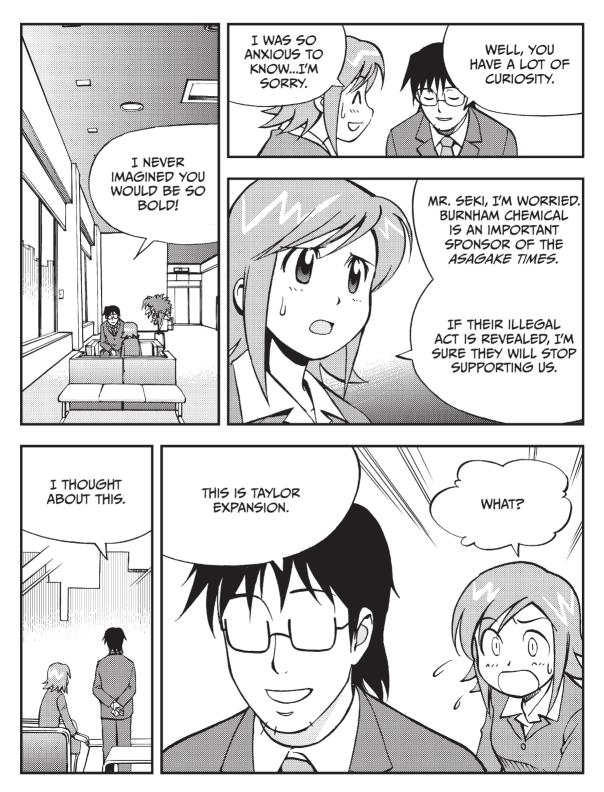
146 CHAPTER 5 LET'S LEARN ABOUT TAYLOR EXPANSIONS!

# IMITATING WITH POLYNOMIALS





148 CHAPTER 5 LET'S LEARN ABOUT TAYLOR EXPANSIONS!







FORMULA 5-1: THE FORMULA OF QUADRATIC APPROXIMATION

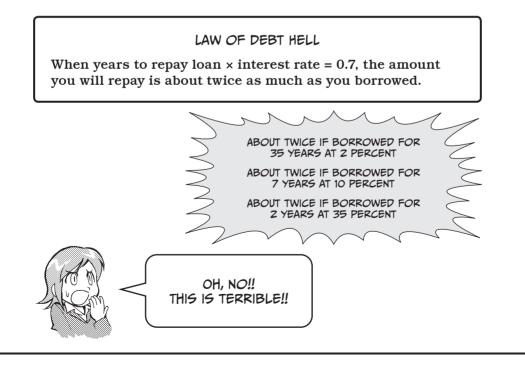
$$(1+x)^n \approx 1+nx+\frac{n(n-1)}{2}x^2$$

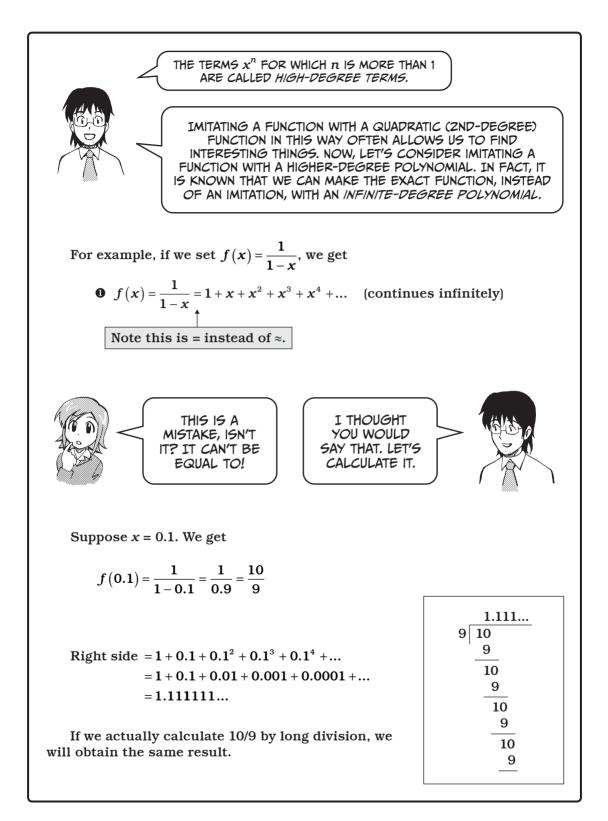


For any pair of *n* and *x* that satisfy nx = 0.7, we get

$$(1+x)^{n} \approx 1 + nx + \frac{n(n-1)}{2}x^{2} \approx 1 + nx + \frac{1}{2}(nx)^{2} - \frac{1}{2}nx^{2}$$
$$\approx 1 + 0.7 + \frac{1}{2} \times 0.7^{2} = 1.945 \approx 2$$
Nearly zero, so we neglect it.

In short, if nx = 0.7,  $(1 + x)^n$  is almost 2. This can be written as a law as follows.

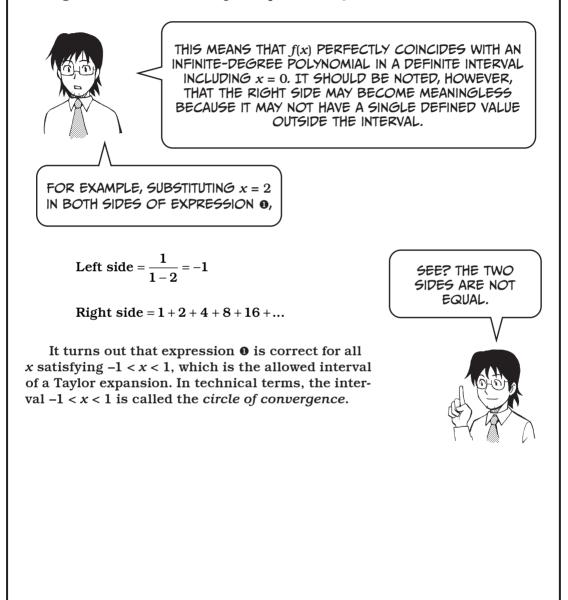




When a general function f(x) (provided it is differentiable infinitely many times) can be expressed as

$$f(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots + a_n x^n + \dots$$

the right side is called the *Taylor expansion* of f(x) (about x = 0).



## HOW TO OBTAIN A TAYLOR EXPANSION

When we have

$$\bullet \quad f(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots + a_n x^n + \dots$$

let's find the coefficient  $a_n$ .

Substituting x = 0 in the above equation and noting  $f(0) = a_0$ , we find that the 0th-degree coefficient  $a_0$  is f(0).

We then differentiate @.

•  $f'(x) = a_1 + 2a_2x + 3a_3x^2 + \dots + na_nx^{n-1} + \dots$ 

Substituting x = 0 in  $\Theta$  and noting  $f'(0) = a_1$ , we find that the 1st-degree coefficient  $a_1$  is f'(0).

We differentiate 
 to get

**9** 
$$f''(x) = 2a_2 + 6a_3x + ... + n(n-1)a_nx^{n-2} + ...$$

Substituting x = 0 in **0**, we find that the 2nd-degree coefficient  $a_2$  is  $\frac{1}{2}f''(0)$ .

<sup>2</sup> Differentiating **9**, we get

$$f'''(x) = 6a_3 + ... + n(n-1)(n-2)a_nx^{n-3} + ...$$

From this, we find that the 3rd-degree coefficient  $a_3$  is  $\frac{1}{2} f''(0)$ .

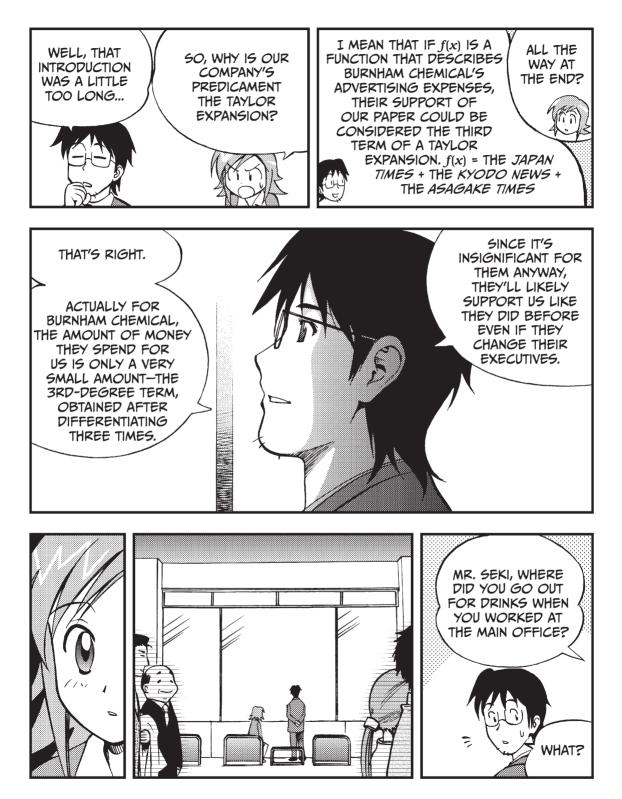
Repeating this differentiation operation n times, we get

 $f^{(n)}(\mathbf{x}) = \mathbf{n}(\mathbf{n}-\mathbf{1})...\times\mathbf{2}\times\mathbf{1}a_n + ...$ 

where  $f^{(n)}(x)$  is the expression obtained after differentiating f(x) n times. From this result, we find

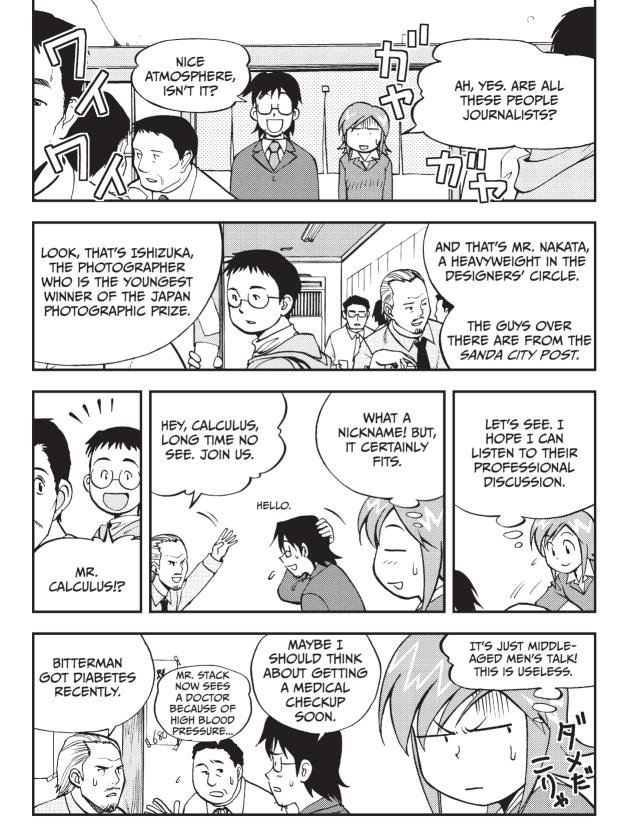
nth-degree coefficient  $a_n = \frac{1}{n!} f^{(n)}(0)$ 

*n*! is read "*n* factorial" and means  $n \times (n-1) \times (n-2) \times ... \times 2 \times 1$ .









FORMULA 5-2: THE FORMULA OF TAYLOR EXPANSIONIf 
$$f(x)$$
 has a Taylor expansion about  $x = 0$ , it is given by $f(x) = f(0) + \frac{1}{1!} f'(0) x + \frac{1}{2!} f''(0) x^2 + \frac{1}{3!} f'''(0) x^3 + ... + \frac{1}{n!} f^{(n)}(0) x^n + ...$ For the above, $f(0)$ Oth-degree constant term $a_0 = f(0)$  $f'(0)x$ Ist-degree term $a_1 = f'(0)$  $\frac{1}{2!} f''(0) x^2$ 2nd-degree term $a_2 = \frac{1}{2} f''(0)$  $\frac{1}{3!} f'''(0) x^3$ 3rd-degree term $a_3 = \frac{1}{6} f'''(0)$ 

For the moment, we forget about the conditions for having Taylor expansion and the circle of convergence.

Using this formula, we check  $\mathbf{0}$  on page 153.

$$f(x) = \frac{1}{1-x}, f'(x) = \frac{1}{(1-x)^2}, f''(x) = \frac{2}{(1-x)^3}, f'''(x) = \frac{6}{(1-x)^4}, \dots$$
  
$$f(0) = 1, f'(0) = 1, f''(0) = 2, f'''(0) = 6, \dots, f^{(n)}(0) = n!$$

Thus, we have

$$f(x) = f(0) + \frac{1}{1!} f'(0) x + \frac{1}{2!} f''(0) x^{2} + \frac{1}{3!} f'''(0) x^{3} + \dots + \frac{1}{n!} f^{(n)}(0) x^{n} + \dots$$
  
= 1 + x +  $\frac{1}{2!} \times 2x^{2} + \frac{1}{3!} \times 6x^{3} + \dots + \frac{1}{n!} n! x^{n} + \dots$   
= 1 + x +  $x^{2} + x^{3} + \dots x^{n} + \dots$   
THEY  
COINCIDE!

THE FORMULA ABOVE IS FOR AN INFINITE-DEGREE POLYNOMIAL THAT COINCIDES WITH THE ORIGINAL NEAR x = 0. THE FORMULA FOR A POLYNOMIAL THAT COINCIDES NEAR x = a IS GENERALLY GIVEN AS FOLLOWS. TRY THE EXERCISE ON PAGE 178 TO CHECK THIS!

$$f(x) = f(a) + \frac{1}{1!} f'(a)(x-a) + \frac{1}{2!} f''(a)(x-a)^{2} + \frac{1}{3!} f'''(a)(x-a)^{3} + \dots + \frac{1}{n!} f^{(n)}(a)(x-a)^{n} + \dots$$

TAYLOR EXPANSION IS A SUPERIOR IMITATING FUNCTION.

## TAYLOR EXPANSION OF VARIOUS FUNCTIONS

[1] TAYLOR EXPANSION OF A SQUARE ROOT

We set 
$$f(x) = \sqrt{1+x} = (1+x)^{\frac{1}{2}}$$
.  
Thus, from  $f'(x) = \frac{1}{2}(1+x)^{-\frac{1}{2}}$   
 $f''(x) = -\frac{1}{2} \times \frac{1}{2}(1+x)^{-\frac{3}{2}}$   
 $f'''(x) = \frac{1}{2} \times \frac{1}{2} \times \frac{3}{2}(1+x)^{-\frac{5}{2}}$ ,...  
 $f'(0) = \frac{1}{2}$ ,  $f''(0) = -\frac{1}{4}$ ,  $f'''(0) = \frac{3}{8}$ ,...  
 $f(x) = \sqrt{1+x}$   
 $= 1 + \frac{1}{2}x + \frac{1}{2!} \times \left(-\frac{1}{4}\right)x^2 + \frac{1}{3!} \times \frac{3}{8}x^3 + ...$   
 $\sqrt{1+x} = 1 + \frac{1}{2}x - \frac{1}{8}x^2 + \frac{1}{16}x^3$ ...

[3] TAYLOR EXPANSION OF LOGARITHMIC FUNCTION  $\ln (1 + x)$ 

We set  $f(x) = \ln(x+1)$ 

$$f'(x) = \frac{1}{1+x} = (1+x)^{-1}$$
  

$$f''(x) = -(1+x)^{-2}, f^{(3)}(x) = 2(1+x)^{-3},$$
  

$$f^{(4)}(x) = -6(1+x)^{-4}, \dots$$
  

$$f(0) = 0, f'(0) = 1, f''(0) = -1, f^{(3)}(0) = 2!,$$
  

$$f^{(4)}(0) = -3!, \dots$$

Thus, we have

$$\ln(1+x) = 0 + x - \frac{1}{2}x^{2} + \frac{1}{3!} \times 2! x^{3} - \frac{1}{4}3! x^{4} + \dots$$
$$\ln(1+x) = x - \frac{1}{2}x^{2} + \frac{1}{3}x^{3} - \frac{1}{4}x^{4} + \dots + (-1)^{n+1}\frac{1}{n}x^{n} + \dots$$

[2] TAYLOR EXPANSION OF EXPONENTIAL FUNCTION  $\boldsymbol{e}^{\boldsymbol{x}}$ 

If we set  $f(x) = e^x$ ,

$$f'(x) = e^x, f''(x) = e^x, f'''(x) = e^x, \dots$$

So, from

$$e^{x} = 1 + \frac{1}{1!}x + \frac{1}{2!}x^{2} + \frac{1}{3!}x^{3} + \frac{1}{4!}x^{4} + \dots$$
$$+ \frac{1}{n!}x^{n} + \dots$$

Substituting x = 1, we get

$$e = 1 + \frac{1}{1!} + \frac{1}{2!} + \frac{1}{3!} + \frac{1}{4!} + \dots + \frac{1}{n!} + \dots$$

IN CHAPTER 4, WE LEARNED THAT e IS ABOUT 2.7. HERE, WE HAVE OBTAINED THE EXPRESSION TO CALCULATE IT EXACTLY.



[4] TAYLOR EXPANSION OF TRIGONOMETRIC FUNCTIONS

We set  $f(x) = \cos x$ .

$$f'(x) = -\sin x, f''(x) = -\cos x, f^{(3)}(x)$$
$$= \sin x, f^{(4)}(x) = \cos x, \dots$$

From

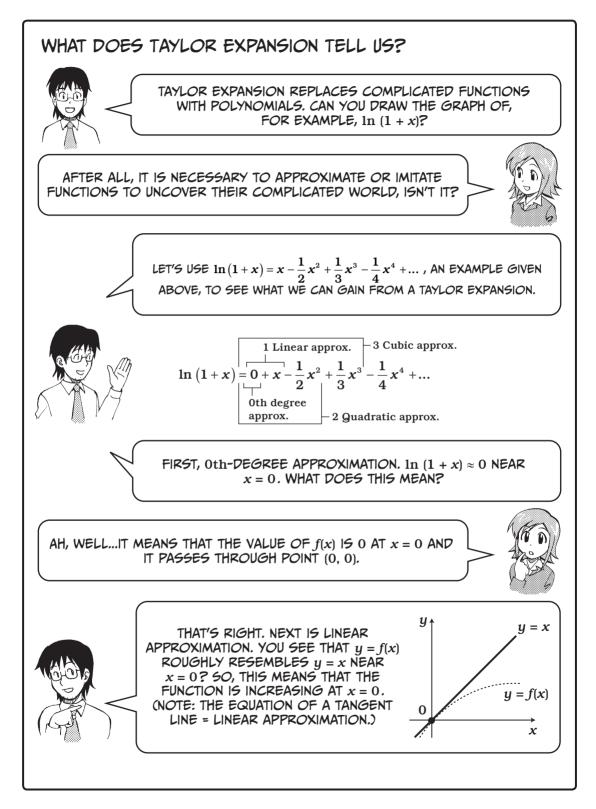
$$f(0) = 1, f'(0) = 0, f''(0) = -1,$$
  
$$f^{(3)}(0) = 0, f^{(4)}(0) = 1, \dots$$

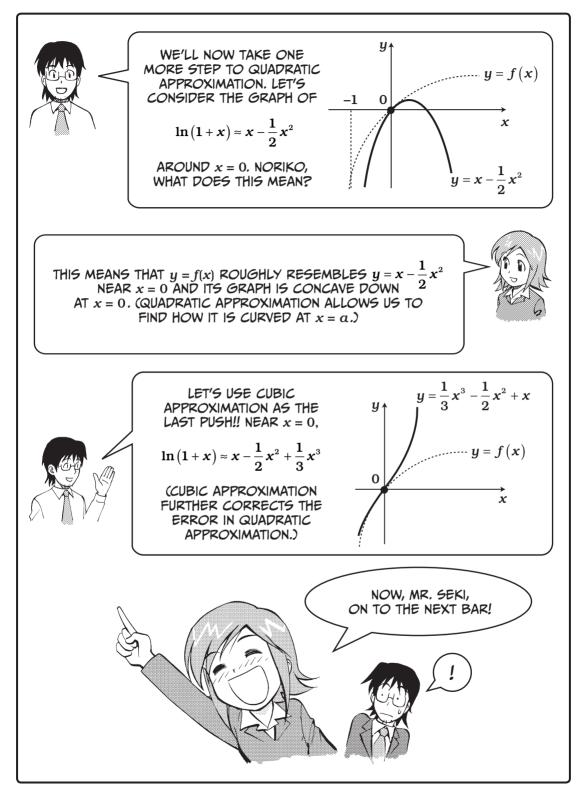
Thus,

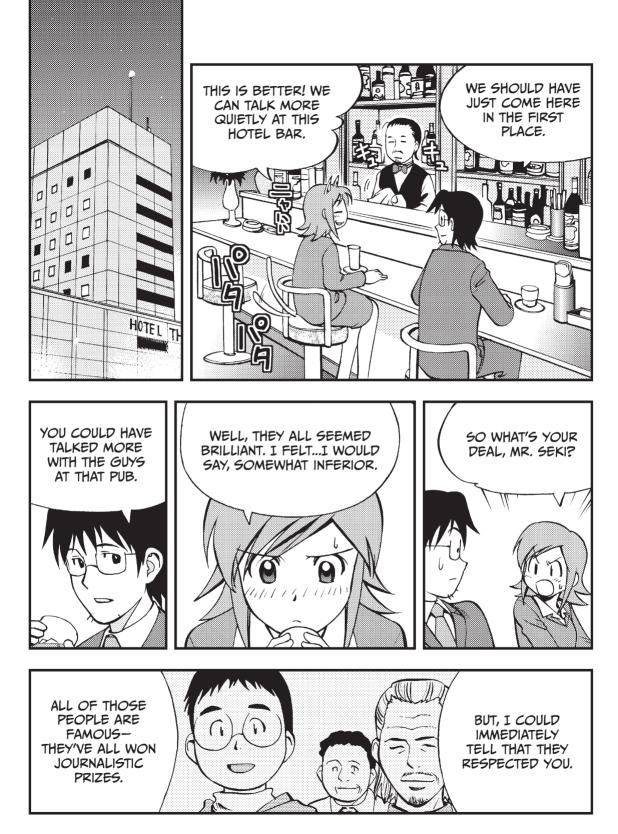
$$\cos x = 1 + 0x - \frac{1}{2!} \times 1 \times x^{2} + \frac{1}{3!} \times 0 \times x^{3} + \frac{1}{4!} \times 1 \times x^{4} + \dots$$
$$\cos x = 1 - \frac{1}{2!} x^{2} + \frac{1}{4!} x^{4} + \dots + (-1)^{n} \frac{1}{(2n)!} x^{2n} + \dots$$

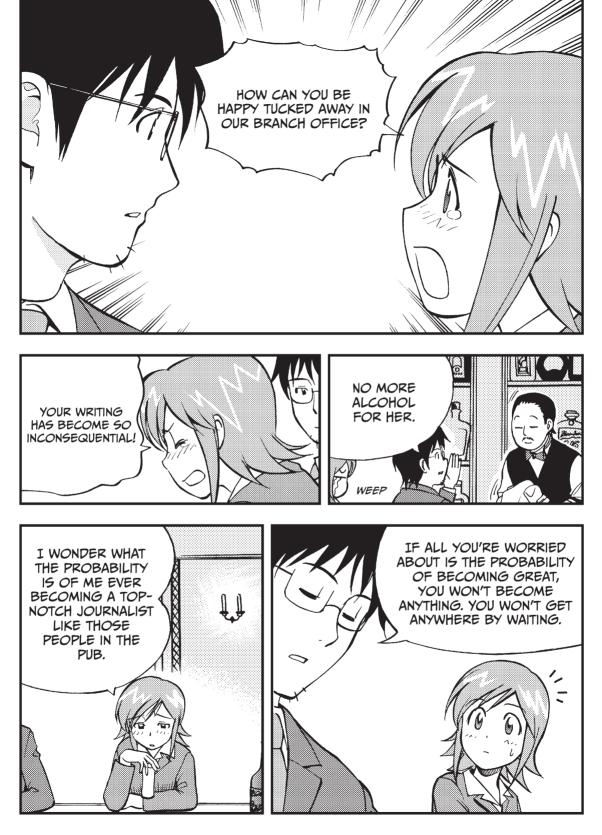
Similarly,

$$\sin x = x - \frac{1}{3!}x^3 + \frac{1}{5!}x^5 + \dots + (-1)^{n-1}\frac{1}{(2n-1)!}x^{2n-1} + \dots$$

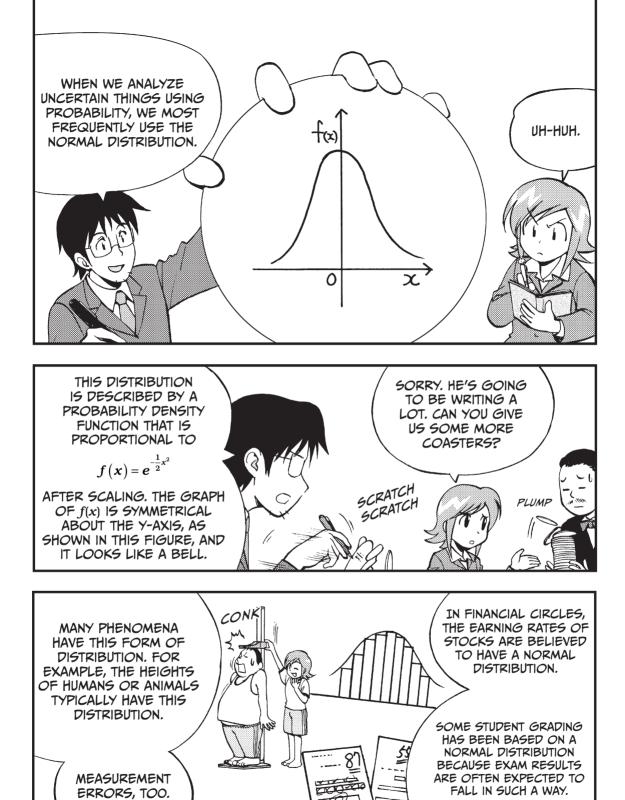




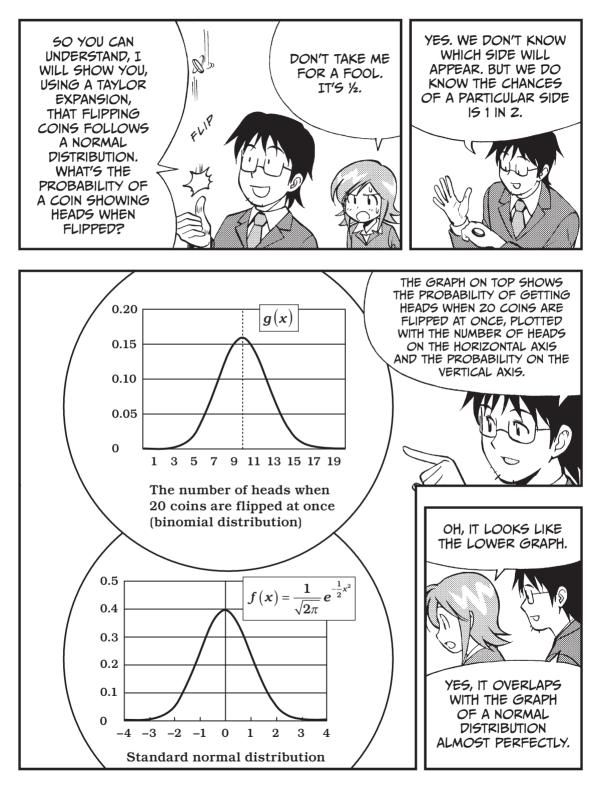


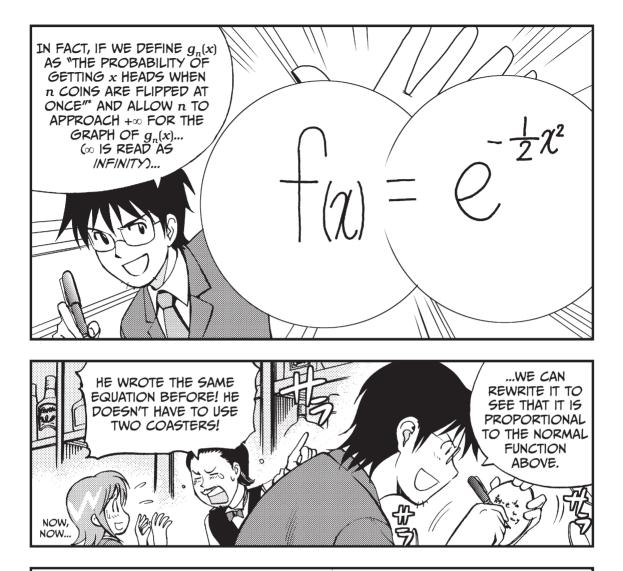






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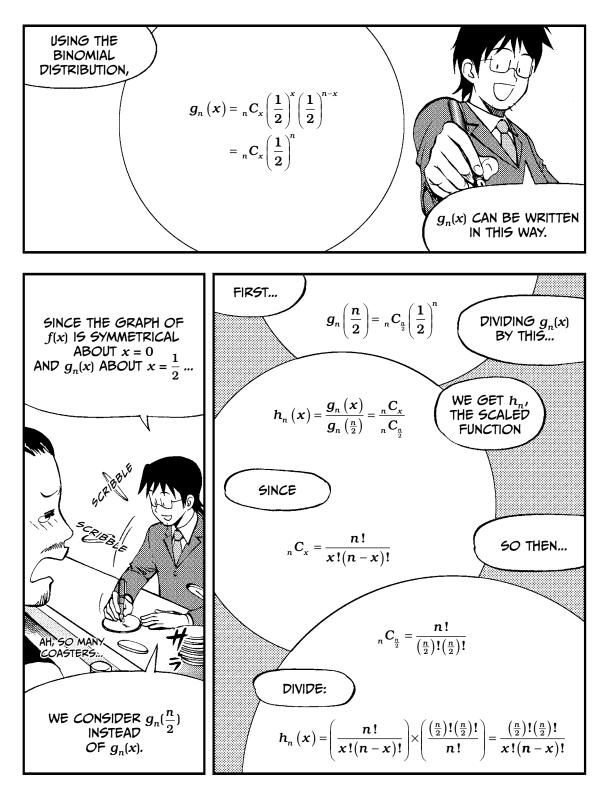


\* The distribution of such probabilities as that of getting x heads when n coins are flipped is generally called the *binomial distribution*.

For example, let's find the probability of getting 3 heads when 5 coins are flipped. The probability of getting HHTHT (H: heads, T: tails) is

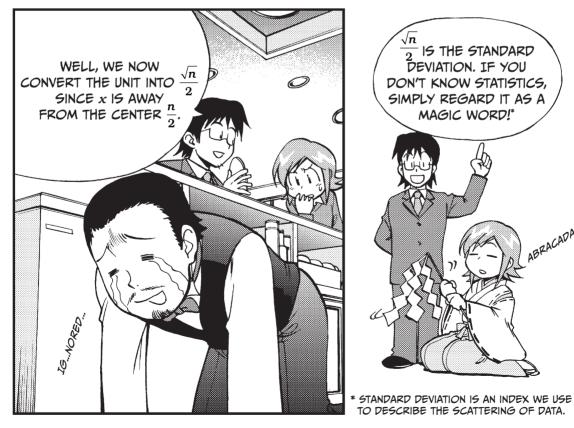
$$\frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = \left(\frac{1}{2}\right)^5$$

Since there are  ${}_{5}C_{3}$  ways of getting 3 heads and 2 tails, it is  ${}_{5}C_{3}\left(\frac{1}{2}\right)^{5}$ . The general expression is  ${}_{n}C_{x}\left(\frac{1}{2}\right)^{n}$ . We will show that if *n* is very large, the binomial distribution is the normal distribution.









ABRACADABRAI

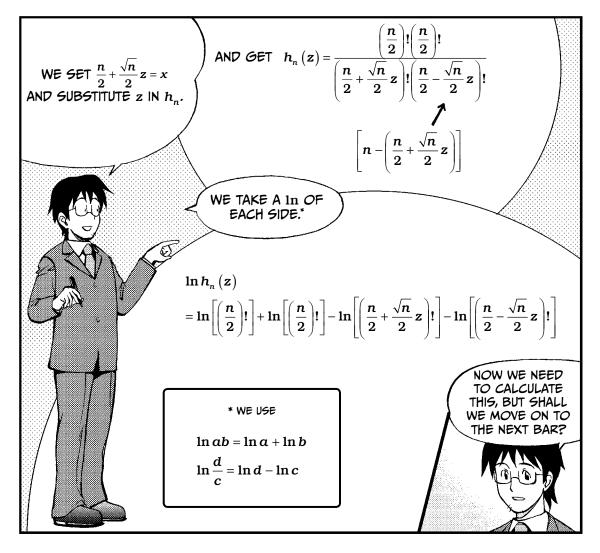
170 CHAPTER 5 LET'S LEARN ABOUT TAYLOR EXPANSIONS!

IN OTHER  
WORDS,  

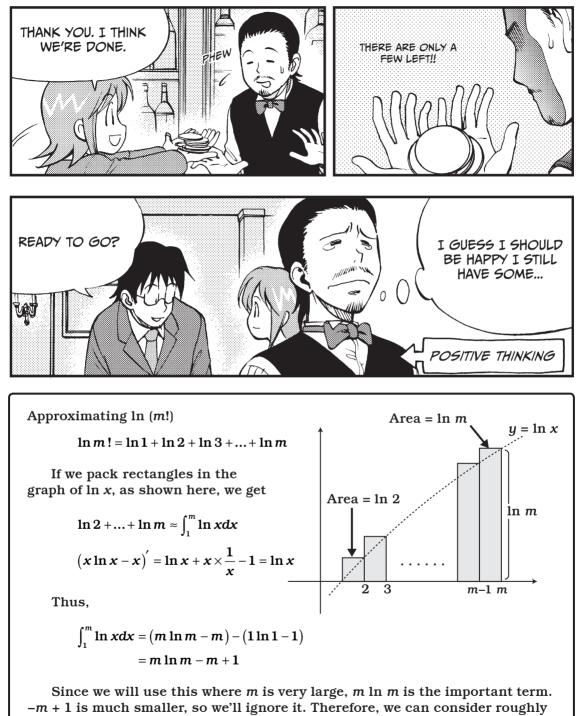
$$\chi = \frac{n}{2} + \frac{\sqrt{n}}{2} \times 1 \rightarrow Z = 1$$

$$\chi = \frac{n}{2} + \frac{\sqrt{n}}{2} \times 2 \rightarrow Z = 2$$

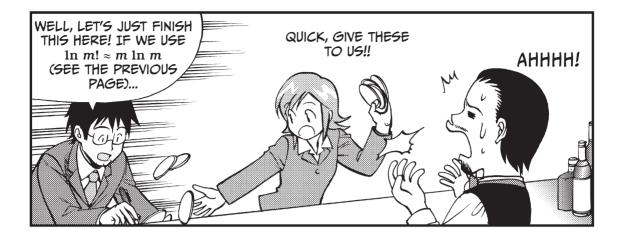
$$\chi = \frac{n}{2} + \frac{\sqrt{n}}{2} \times 3 \rightarrow Z = 3$$
IN THIS WAY, WE  
CHANGE THE VARIABLE.  
THE NEW ONE, z, IS THE  
NUMBER OF STANDARD  
DEVIATIONS AWAY  
FROM THE CENTER.



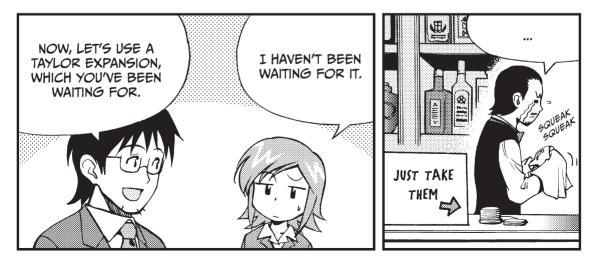
WHAT DOES TAYLOR EXPANSION TELL US? 171

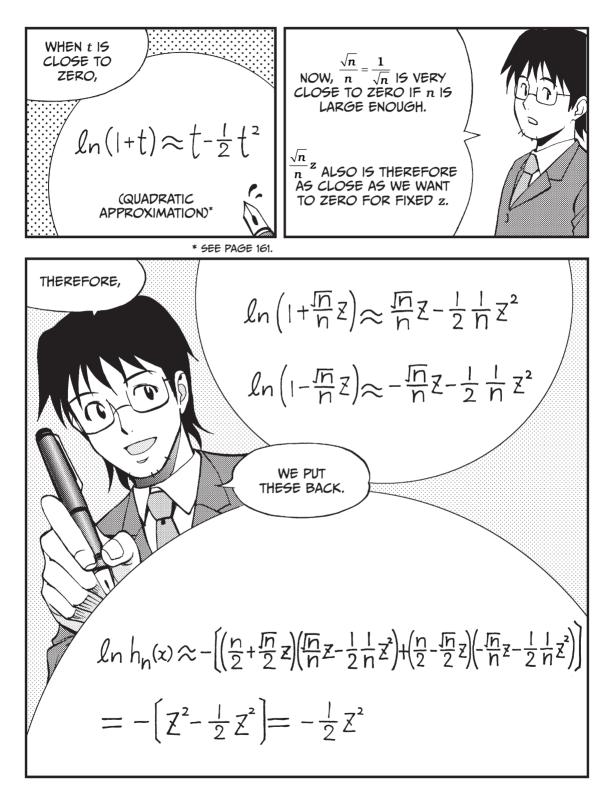


that  $\ln m! = m \ln m$ .



 $\ln h_{n}(x) \approx \frac{n}{2} \ln \frac{n}{2} + \frac{n}{2} \ln \frac{n}{2} - \left(\frac{n}{2} + \frac{\sqrt{n}}{2}z\right) \ln \left(\frac{n}{2} + \frac{\sqrt{n}}{2}z\right) - \left(\frac{n}{2} - \frac{\sqrt{n}}{2}z\right) \ln \left(\frac{n}{2} - \frac{\sqrt{n}}{2}z\right)$ AFTER A LOT OF ALGEBRA, WE GET  $\ln h_n(x) \approx -\left[\left(\frac{n}{2} + \frac{\sqrt{n}}{2}z\right) \ln \left(1 + \frac{\sqrt{n}}{2}z\right) + \left(\frac{n}{2} - \frac{\sqrt{n}}{2}z\right) \ln \left(1 - \frac{\sqrt{n}}{2}z\right)\right]$ WE USED, E.G.,  $\ln\left(\frac{n}{2} + \frac{\sqrt{n}}{2}z\right) = \ln\left\{\frac{n}{2}\left(1 + \frac{\sqrt{n}}{n}z\right)\right\} = \ln\frac{n}{2} + \ln\left(1 + \frac{\sqrt{n}}{n}z\right)$ 





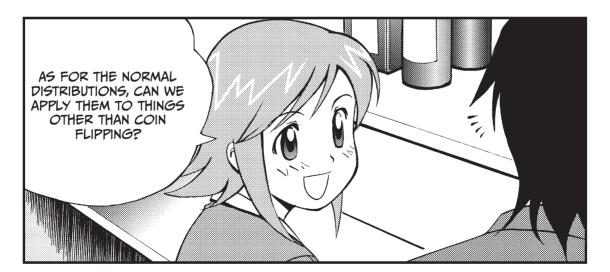


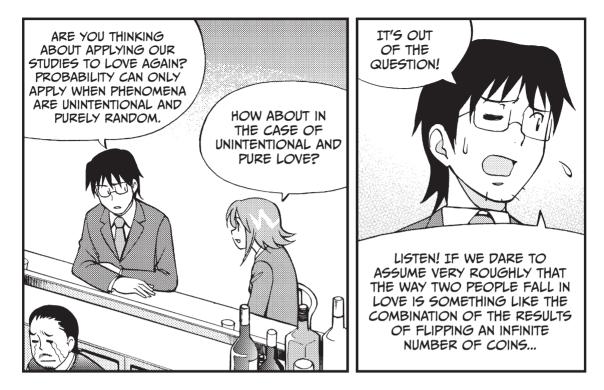
IF YOU ARE AFRAID THAT THE HIGHER-DEGREE TERMS OF  $x^3$  and more that appear in the taylor expansion of 1n might affect the shape of  $h_n(x)$  (n: large enough), actually calculate  $h_n(x)$ , using

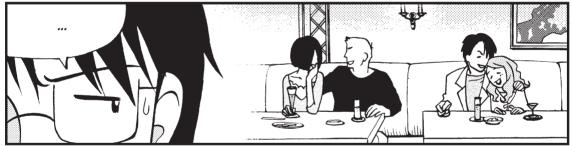
$$\ln\left(1+t\right)\approx t-\frac{1}{2}t^{2}+\frac{1}{3}t^{3}$$

 $_{n}(x)$ , USING HAS n IN THE CONVERGES TO  $n \rightarrow \infty$ .

YOU WILL FIND THAT THE TERM OF  $z^4$  has n in the denominator of its coefficient and converges to zero, or disappears, when  $n \to \infty$ .

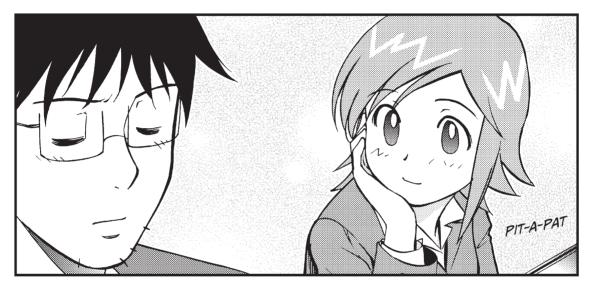






WELL, SINCE WE HAVE FOUND THAT THE DISTRIBUTION OF THE RESULTS OF COIN FLIPPING IS APPROXIMATELY A NORMAL DISTRIBUTION, IT WOULD NOT BE SURPRISING IF A NORMAL DISTRIBUTION COULD BE CALCULATED FOR LOVE.







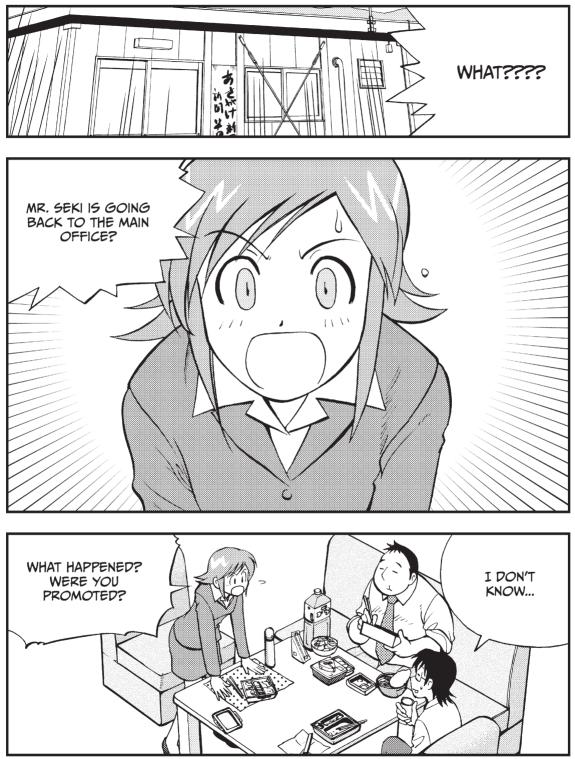
## EXERCISES

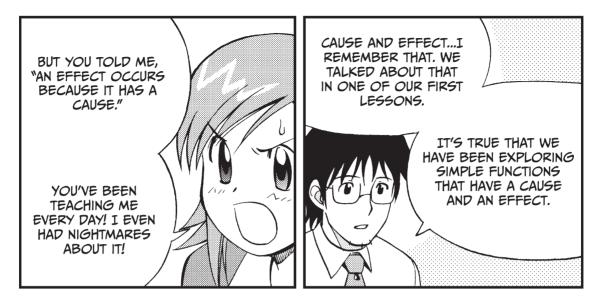
- 1. Obtain the Taylor expansion of  $f(x) = e^{-x}$  at x = 0.
- 2. Obtain the quadratic approximation of  $f(x) = \frac{1}{\cos x}$  at x = 0.
- 3. Derive for yourself the formula for the Taylor expansion of f(x) centered at x = 1, which is given on page 159. In other words, work out what  $c_n$  must be in the equation:

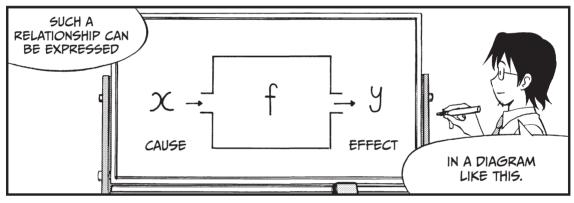
$$f(x) = c_0 + c_1(x-a) + c_2(x-a)^2 + ... + c_n(x-a)^n$$

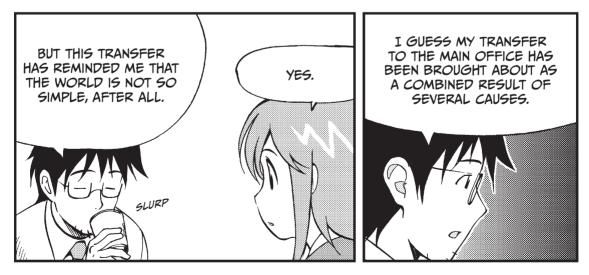


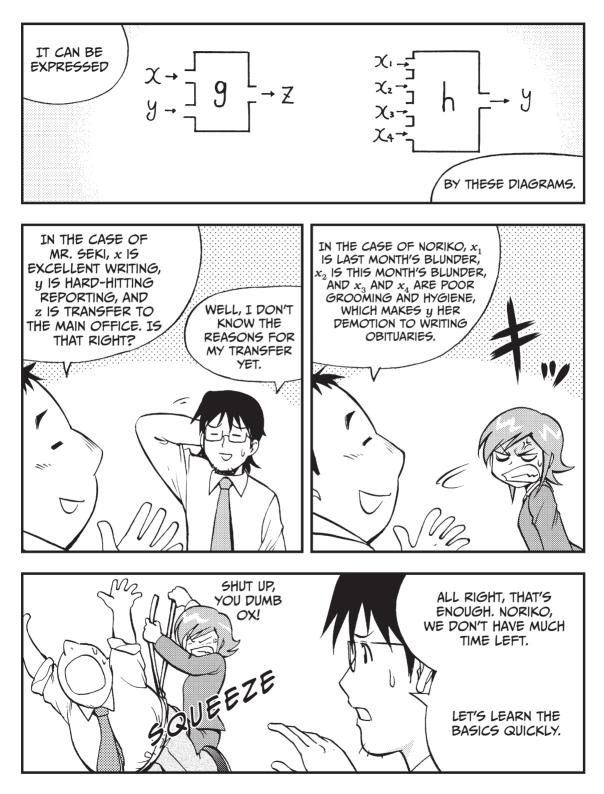
# WHAT ARE MULTIVARIABLE FUNCTIONS?













EXAMPLE 1

Assume that an object is at height h(v, t) in meters after t seconds when it is thrown vertically upward from the ground with velocity v. Then, h(v, t)is given by

 $h(v,t) = vt - 4.9t^2$ 

EXAMPLE 2

The concentration f(x, y) of sugar syrup obtained by dissolving y grams of sugar in x grams of water is given by

$$f(\mathbf{x},\mathbf{y}) = \frac{\mathbf{y}}{\mathbf{x}+\mathbf{y}} \square \mathbf{100}$$

EXAMPLE 3

When the amount of equipment and machinery (called *capital*) in a nation is represented with K and the amount of labor by L, we assume that the total production of commodities (GDP: Gross Domestic Product) is given by Y(L, K).



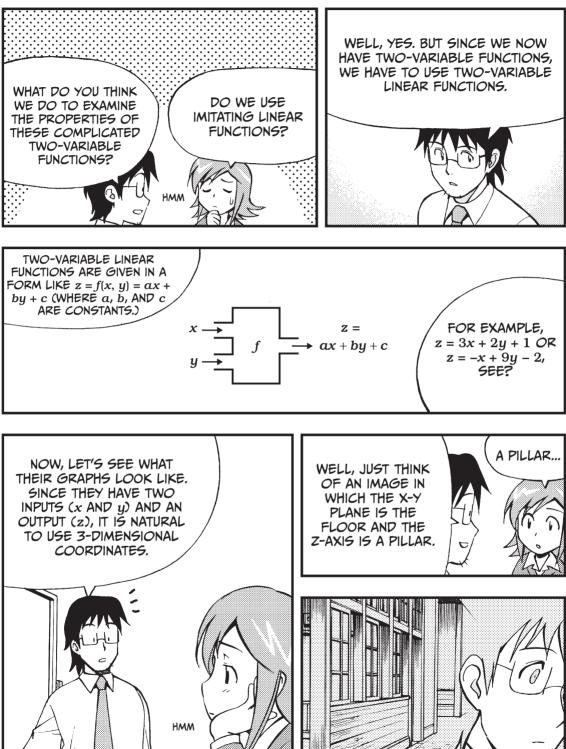
IN ECONOMICS,  $Y(L, K) = \beta L^{\alpha} K^{1-\alpha}$  (Called the COBB-DOUGLAS FUNCTION) (WHERE  $\alpha$  AND  $\beta$  Are CONSTANTS) IS USED AS AN APPROXIMATE FUNCTION OF Y(L, K). SEE PAGE 203.

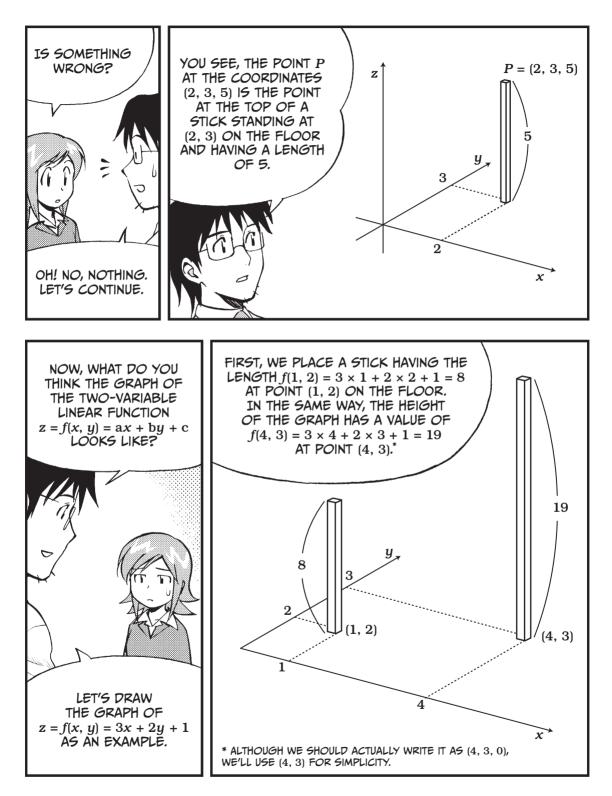
EXAMPLE 4

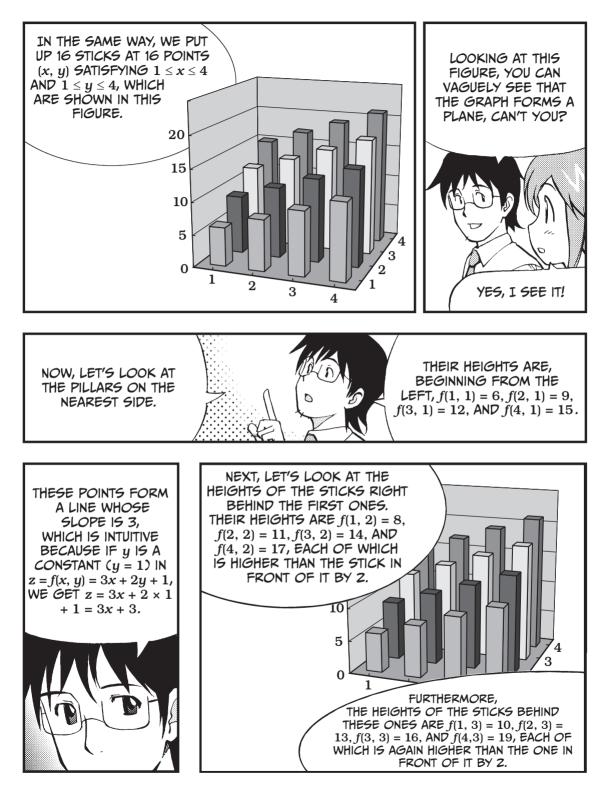
In physics, when the pressure of an ideal gas is given by P and its volume by V, its temperature T is known to be a function of P and V as T(P, V). And it is given by

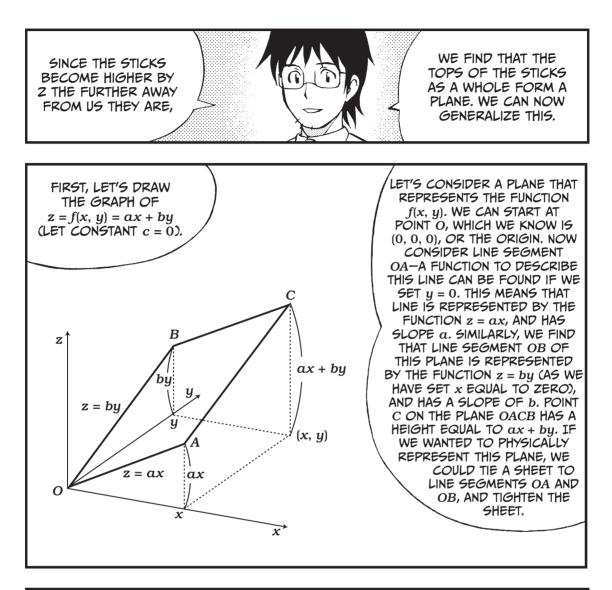
 $T(P, V) = \gamma P V$ 

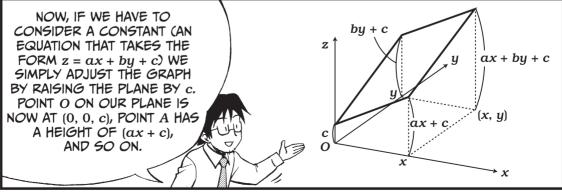
### THE BASICS OF VARIABLE LINEAR FUNCTIONS

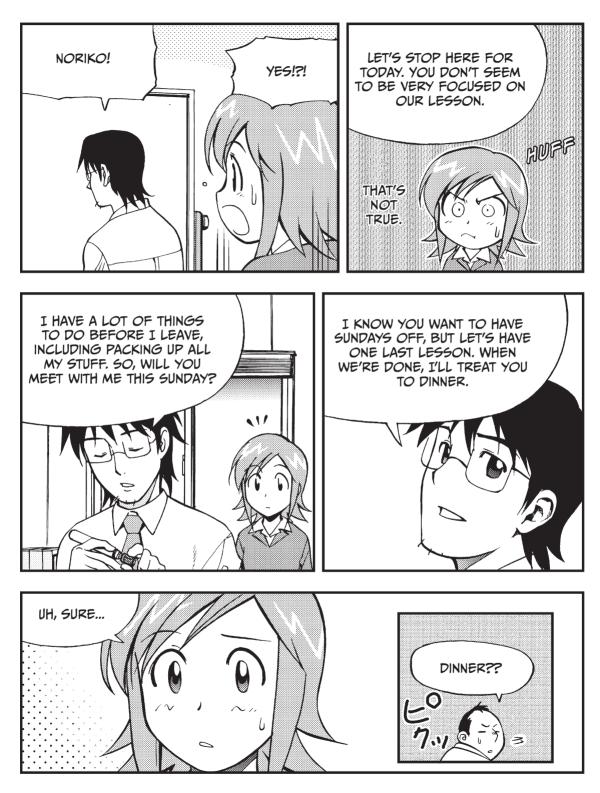




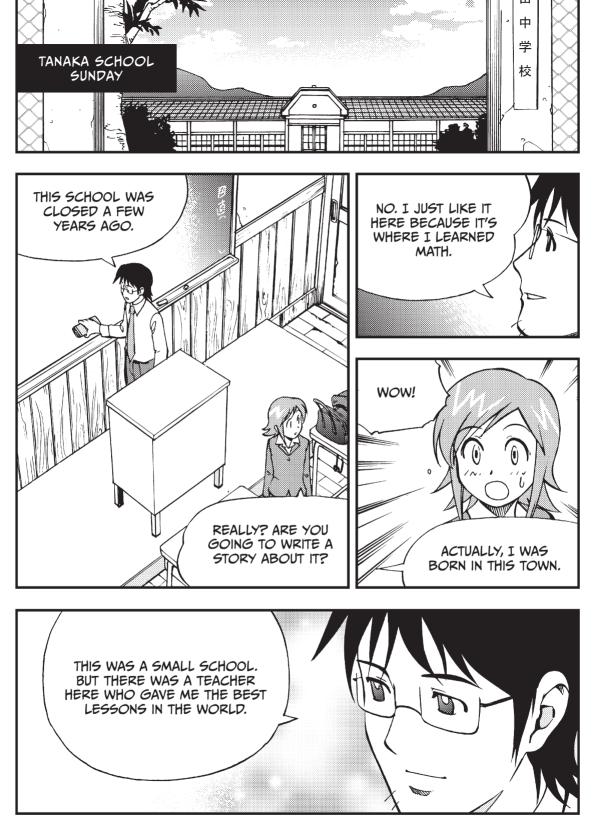






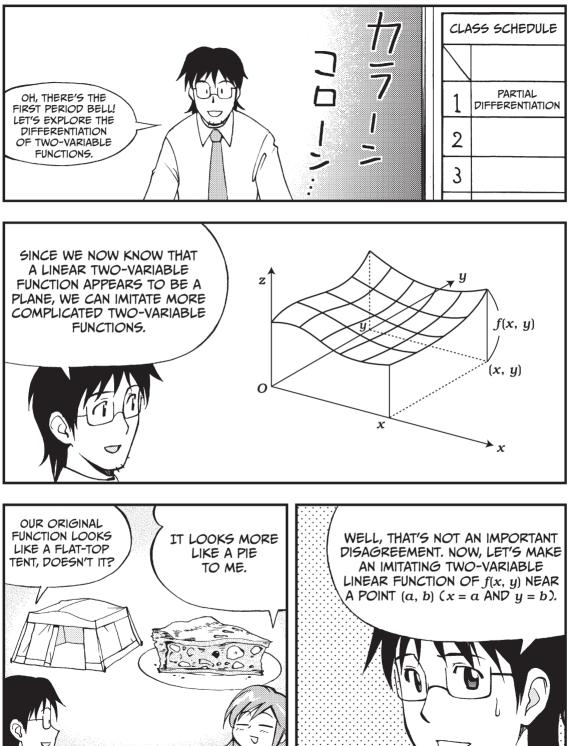


188 CHAPTER 6 LET'S LEARN ABOUT PARTIAL DIFFERENTIATION!

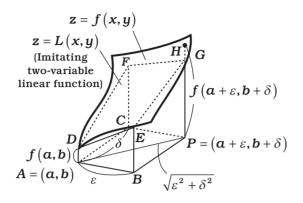




### PARTIAL DIFFERENTIATION



We make a two-variable linear function that has the same height as f(a, b) at the point (a, b). The formula is L(x, y) = p(x - a) + q(y - b) + f(a, b). Substituting a for x and b for y, we get L(a, b) = f(a, b).



While the graph of z = f(x, y) and that of z = L(x, y) pass through the same point above the point A = (a, b), they differ in height at the point  $P = (a + \varepsilon, b + \delta)$ . The error in this case is  $f(a + \varepsilon, b + \delta) - L(a + \varepsilon, b + \delta) = f(a + \varepsilon, b + \delta) - f(a, b) - (p\varepsilon + q\delta)$ , and the relative error expresses the ratio of the error to the distance *AP*.

Relative error =  $\frac{\text{difference between } f \text{ and } L}{\text{distance } AP}$  $\bullet = \frac{f(a + \varepsilon, b + \delta) - f(a, b) - (p\varepsilon + q\delta)}{\sqrt{\varepsilon^2 + \delta^2}}$ 

We consider L(x, y) as the difference between it and f becomes infinitely close to zero (when P is infinitely close to A) as the imitating linear function. For that case, we obtain p and q. p is the slope of DE and q that of DFin the figure. Since  $\varepsilon$  and  $\delta$  are arbitrary, we first let  $\delta = 0$  and analyze **0**. **0** becomes

Relative error = 
$$\frac{f(a + \varepsilon, b + 0) - f(a, b) - (p\varepsilon + q \times 0)}{\sqrt{\varepsilon^2 + 0^2}}$$
$$= \frac{f(a + \varepsilon, b) - f(a, b)}{\varepsilon} - p$$

Thus, the statement "the relative error  $\rightarrow 0$  when  $\varepsilon \rightarrow 0$ " means the following:

This is the slope of *DE*.

Here, we should realize that the left side of this expression is the same as single-variable differentiation. In other words, if we substitute b for y and keep it constant, we obtain f(x, b), which is a function of x only. The left side of  $\Theta$  is then the calculation of finding the derivative of this function at x = a.

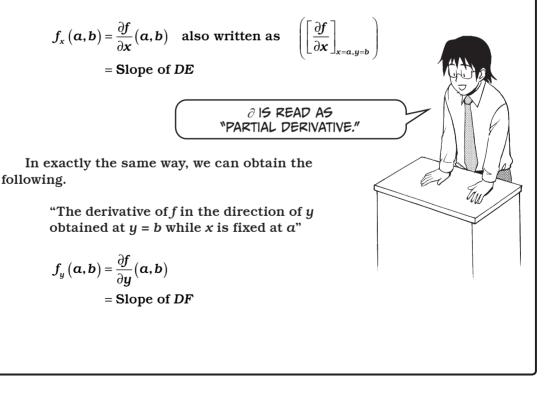
Although we are very much tempted to write the left side as f'(a, b) since it is a derivative, it would then be impossible to tell with respect to which, xor y, we differentiated it.

So, we write "the derivative of f obtained at x = a while y is fixed at b" as  $f_x(a, b)$ .

This  $f_x$  is called "the partial derivative of f in the direction of x". This is the notation corresponding to the "prime" in single-variable differentiation.

The notation  $\frac{df}{dx}(a, b)$ , that corresponds to  $\frac{\partial f}{\partial x}$ , is also used. In short, we have the following:

"The derivative of f in the direction of x obtained at x = a while y is fixed at b"

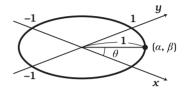


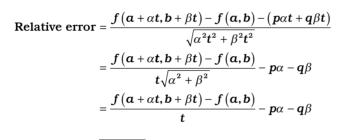
We have now found the following.

If z = f(x, y) has an imitating linear function near (x, y) = (a, b), it is given by

$$\mathbf{S} \quad \mathbf{z} = f_x(\mathbf{a}, \mathbf{b})(\mathbf{x} - \mathbf{a}) + f_y(\mathbf{a}, \mathbf{b})(\mathbf{y} - \mathbf{b}) + f(\mathbf{a}, \mathbf{b})$$
  
or<sup>\*</sup> 
$$\mathbf{z} = \frac{\partial f}{\partial \mathbf{x}}(\mathbf{a}, \mathbf{b})(\mathbf{x} - \mathbf{a}) + \frac{\partial f}{\partial \mathbf{y}}(\mathbf{a}, \mathbf{b})(\mathbf{y} - \mathbf{b}) + f(\mathbf{a}, \mathbf{b})$$

Consider a point  $(\alpha, \beta)$  on a circle with radius 1 centered at the origin of the x - y plane (the floor). We have  $\alpha^2 + \beta^2 = 1$  (or  $\alpha = \cos \theta$  and  $\beta = \sin \theta$ ). We now calculate the derivative in the direction from (0, 0) to  $(\alpha, \beta)$ . A displacement of distance t in this direction is expressed as  $(a, b) \rightarrow (a + \alpha t, b + \beta t)$ . If we set  $\varepsilon = \alpha t$  and  $\delta = \beta t$ in **0**, we get







Assuming  $p = f_x(a, b)$  and  $q = f_u(a, b)$ , we modify **3** as follows:

Since the derivative of  $f(x, b + \beta t)$ , a function of x only, at x = a is

$$f_x(a, b + \beta t)$$

we get, from the imitating single-variable linear function,

$$f(\mathbf{a} + \alpha t, \mathbf{b} + \beta t) - f(\mathbf{a}, \mathbf{b} + \beta t) \approx f_x(\mathbf{a}, \mathbf{b} + \beta t) \alpha t$$

<sup>\*</sup> We have calculated the imitating linear function in such a way that its relative error approaches 0 when  $AP \rightarrow 0$  in the x or y direction. It is not apparent, however, if the relative error  $\rightarrow 0$  when  $AP \rightarrow 0$  in any direction for the linear function that is made up of the derivatives  $f_x(a, b)$  and  $f_y(a, b)$ . We'll now look into this in detail, although the discussion here will not be so strict.

Similarly, for y we get

$$f(\mathbf{a}, \mathbf{b} + \beta \mathbf{t}) - f(\mathbf{a}, \mathbf{b}) \approx f_{\mathbf{u}}(\mathbf{a}, \mathbf{b}) \beta \mathbf{t}$$

Substituting this in **9**,

$$\boldsymbol{\Theta} \approx f_{x} \left( \boldsymbol{a}, \boldsymbol{b} + \beta t \right) \alpha + f_{y} \left( \boldsymbol{a}, \boldsymbol{b} \right) \beta - f_{x} \left( \boldsymbol{a}, \boldsymbol{b} \right) \alpha - f_{y} \left( \boldsymbol{a}, \boldsymbol{b} \right) \beta$$
$$= \left( f_{x} \left( \boldsymbol{a}, \boldsymbol{b} + \beta t \right) - f_{x} \left( \boldsymbol{a}, \boldsymbol{b} \right) \right) \alpha$$

Since  $f_x(a, b + \beta t) - f_x(a, b) \approx 0$  if t is close enough to 0, the relative error =  $\mathbf{\Theta} \approx 0$ . Thus, we have shown "the relative error  $\rightarrow 0$  when  $AP \rightarrow 0$  in any direction."

It should be noted that  $f_x$  must be continuous to say  $f_x(a, b + \beta t) - f_x(a, b) \approx 0$  ( $t \approx 0$ ). Unless it is continuous, we don't know whether the derivative exists in every direction, even though  $f_x$  and  $f_y$  exist. Since such functions are rather exceptional, however, we won't cover them in this book.

EXAMPLES (FUNCTION OF EXAMPLE 1 FROM PAGE 183)

Let's find the partial derivatives of  $h(v, t) = vt - 4.9t^2$  at (v, t) = (100, 5). In the v direction, we differentiate h(v, 5) = 5v - 122.5 and get

$$\frac{\partial h}{\partial v}(v,5)=5$$

Thus,

$$\frac{\partial h}{\partial v}(100,5) = h_v(100,5) = 5$$

In the *t* direction, we differentiate  $h(100, t) = 100t - 4.9t^2$  and get

$$\frac{\partial h}{\partial t}(100,t) = 100 - 9.8t$$

$$\frac{\partial h}{\partial t}(100,5) = h_t(100,5) = 100 - 9.8 \times 5 = 51$$

And the imitating linear function is

$$L(x,y) = 5(v-100) + 51(t-5) - 377.5$$



In general,

$$\frac{\partial h}{\partial v} = t, \frac{\partial h}{\partial v} = v - 9.8t$$

Therefore, from **③** on page 194, near  $(v, t) = (v_0, t_0)$ ,

$$\boldsymbol{h}(\boldsymbol{v},\boldsymbol{t}) \approx \boldsymbol{t}_{0} \left(\boldsymbol{v} - \boldsymbol{v}_{0}\right) + \left(\boldsymbol{v}_{0} - \boldsymbol{9.8t}_{0}\right) \left(\boldsymbol{t} - \boldsymbol{t}_{0}\right) + \boldsymbol{h}\left(\boldsymbol{v}_{0},\boldsymbol{t}_{0}\right)$$

Next, we'll try imitating the concentration of sugar syrup given y grams of sugar in x grams of water.

$$f(x,y) = \frac{100y}{x+y}$$
$$\frac{\partial f}{\partial x} = f_x = -\frac{100y}{(x+y)^2}$$
$$\frac{\partial f}{\partial y} = f_y = \frac{100(x+y) - 100y \times 1}{(x+y)^2} = \frac{100x}{(x+y)^2}$$

Thus, near (x, y) = (a, b), we have

$$f(\mathbf{x}, \mathbf{y}) \approx -\frac{100b}{(\mathbf{a}+\mathbf{b})^2}(\mathbf{x}-\mathbf{a}) + \frac{100a}{(\mathbf{a}+\mathbf{b})^2}(\mathbf{y}-\mathbf{b}) + \frac{100b}{\mathbf{a}+\mathbf{b}}$$

#### DEFINITION OF PARTIAL DIFFERENTIATION

When z = f(x, y) is partially differentiable with respect to x for every point (x, y) in a region, the function  $(x, y) \rightarrow f_x(x, y)$ , which relates (x, y) to  $f_x(x, y)$ , the partial derivative at that point with respect to x, is called the partial differential function of z = f(x, y) with respect to x and can be expressed by any of the following:

$$f_x, f_x(x, y), \frac{\partial f}{\partial x}, \frac{\partial z}{\partial x}$$

Similarly, when z = f(x, y) is partially differentiable with respect to y for every point (x, y) in the region, the function

$$(\mathbf{x},\mathbf{y}) \rightarrow f_{\mathbf{y}}(\mathbf{x},\mathbf{y})$$

is called the partial differential function of z = f(x, y) with respect to y and is expressed by any of the following:

$$f_{y}, f_{y}(x, y), \frac{\partial f}{\partial y}, \frac{\partial z}{\partial y}$$

Obtaining the partial derivatives of a function is called *partially differentiating* it.

### TOTAL DIFFERENTIALS



From the imitating linear function of z = f(x, y) at (x, y) = (a, b), we have found

$$f(\mathbf{x},\mathbf{y}) \approx f_x(\mathbf{a},\mathbf{b})(\mathbf{x}-\mathbf{a}) + f_y(\mathbf{a},\mathbf{b})(\mathbf{x}-\mathbf{b}) + f(\mathbf{a},\mathbf{b})$$

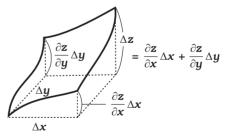
We now modify this as

**6** 
$$f(x,y) - f(a,b) \approx \frac{\partial f}{\partial x}(a,b)(x-a) + \frac{\partial f}{\partial y}(a,b)(y-b)$$

Since f(x, y) - f(a, b) means the increment of z = f(x, y) when a point moves from (a, b) to (x, y), we write this as  $\Delta z$ , as we did for the single-variable functions.

Also, (x - a) is  $\Delta x$  and (y - b) is  $\Delta y$ . Then, expression **(b)** can be written as

$$\mathbf{\Theta} \quad \Delta \mathbf{z} \approx \frac{\partial \mathbf{z}}{\partial \mathbf{x}} \Delta \mathbf{x} + \frac{\partial \mathbf{z}}{\partial \mathbf{y}} \Delta \mathbf{y}$$



This expression means, "If x increases from a by  $\Delta x$  and y from b by  $\Delta y$  in z = f(x, y), z increases by

$$\frac{\partial \boldsymbol{z}}{\partial \boldsymbol{x}} \Delta \boldsymbol{x} + \frac{\partial \boldsymbol{z}}{\partial \boldsymbol{y}} \Delta \boldsymbol{y}$$

Since  $\frac{\partial z}{\partial x} \Delta x$  is "the increment of z in the x direction when y is fixed at b" and  $\frac{\partial z}{\partial y} \Delta y$  is "the increment in the y direction when x is fixed at a," expression **2** also means "the increment of z = f(x, y) is the sum of the increment in the x direction and that in the y direction."

When expression  $\boldsymbol{\Theta}$  is idealized (made instantaneous), we have

or

( $\Delta$  has been changed to d.)

The meaning of the formula is as follows.

Increment of height of a curved surface =

Partial derivative	Increment in	Partial derivative	Increment in
in the x direction	the x direction	in the y direction $^{\star}$	the y direction

EXPRESSION O OR O IS CALLED THE FORMULA OF

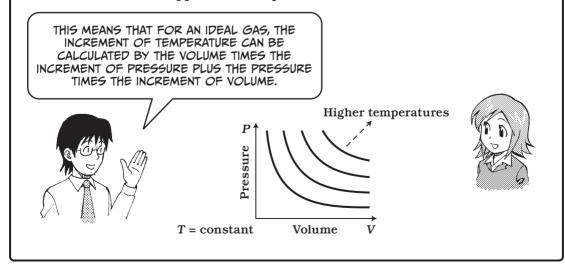
THE TOTAL DIFFERENTIAL.

Now, let's look at the expression of a total differential from Example 4 (page 183).

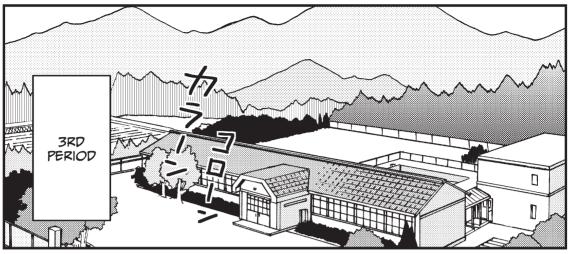
By converting the unit properly, we rewrite the equation of temperature as T = PV.

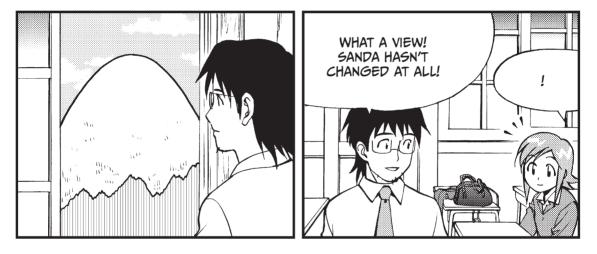
$$\frac{\partial T}{\partial P} = \frac{\partial (PV)}{\partial P} = V$$
 and  $\frac{\partial T}{\partial V} = \frac{\partial (PV)}{\partial P} = P$ 

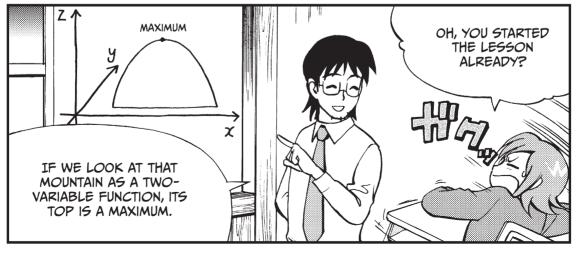
Thus, the total differential can be written as dT = VdP + PdV. In the form of an approximate expression, this is  $\Delta T \approx V \Delta P + P \Delta V$ .



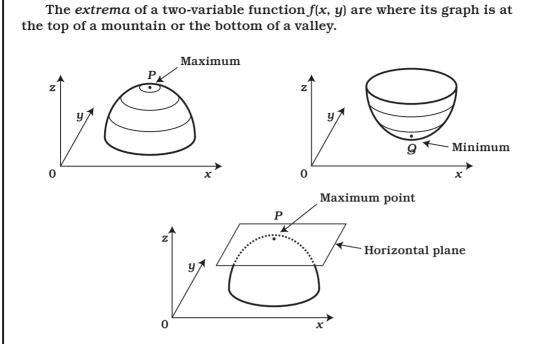
### CONDITIONS FOR EXTREMA







CONDITIONS FOR EXTREMA 199



Since the plane tangent to the graph at point P or Q is parallel to the x-y plane, we should have

$$f(x,y) \approx p(x-a) + q(y-b) + f(a,b)$$

with p = q = 0 in the imitating linear function.

Since

$$\boldsymbol{p} = \frac{\partial \boldsymbol{f}}{\partial \boldsymbol{x}} (= \boldsymbol{f}_x) \quad \boldsymbol{q} = \frac{\partial \boldsymbol{f}}{\partial \boldsymbol{y}} (= \boldsymbol{f}_y)$$

the condition for extrema<sup>\*</sup> is, if f(x, y) has an extremum at (x, y) = (a, b),

$$f_{x}(a,b) = f_{y}(a,b) = 0$$

or

$$\frac{\partial f}{\partial x}(a,b) = \frac{\partial f}{\partial y}(a,b) = 0$$

<sup>\*</sup> The opposite of this is not true. In other words, even if  $f_x(a, b) = f_y(a, b) = 0$ , f will not always have an extremum at (x, y) = (a, b). Thus, this condition only picks up the candidates for extrema.



AT THE EXTREMA OF A TWO-VARIABLE FUNCTION, THE PARTIAL DERIVATIVES IN BOTH THE *x* AND *y* DIRECTIONS ARE ZERO.

EXAMPLE

Let's find the minimum of  $f(x, y) = (x - y)^2 + (y - 2)^2$ . First, we'll find it algebraically.

Since

$$(x-y)^2 \ge 0$$
  $(y-2)^2 \ge 0$   
 $f(x,y) = (x-y)^2 + (y-2)^2 \ge 0$ 

If we substitute x = y = 2 here,

 $f(2,2) = (2-2)^2 + (2-2)^2 = 0$ 

From this,  $f(x, y) \ge f(2, 2)$  for all (x, y). In other words, f(x, y) has a minimum of zero at (x, y) = (2, 2).

On the other hand,  $\frac{\partial f}{\partial x} = 2(x-y)$  and  $\frac{\partial f}{\partial y} = 2(x-y)(-1) + 2(y-2) = -2x + 4y - 4$ . If we set

> THE SOLUTIONS ARE THE SAME!

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial y} = \mathbf{0}$$

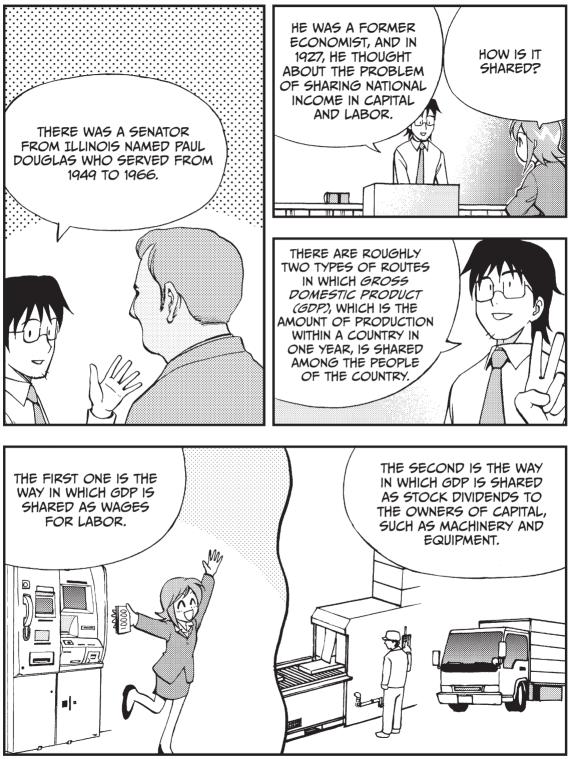
and solve these simultaneous equations,

$$\begin{cases} 2x - 2y = 0 \\ -2x + 4y - 4 = 0 \end{cases}$$

we find that (x, y) = (2, 2), just as we found above.



## APPLYING PARTIAL DIFFERENTIATION TO ECONOMICS





First, let's suppose that wages are measured in units of w, and capital is measured in units of r. We'll consider the production of the entire country to be given by the function f(L, K) and assume the country is acting as a profit-maximizing business. The profit P is given by the equation:

$$P = f(L, K) - wL - rK$$

Because we know that a business chooses values of L and K to maximize profit (P), we get the following condition for extrema:

$$\frac{\partial P}{\partial L} = \frac{\partial P}{\partial K} = \mathbf{0}$$

$$\mathbf{0} = \frac{\partial P}{\partial L} = \frac{\partial f}{\partial L} - \frac{\partial (wL)}{\partial L} - \frac{\partial (rK)}{\partial L} = \frac{\partial f}{\partial L} - w \Rightarrow w = \frac{\partial f}{\partial L}$$

$$\mathbf{0} = \frac{\partial P}{\partial K} = \frac{\partial f}{\partial K} - \frac{\partial (wL)}{\partial K} - \frac{\partial (rK)}{\partial K} = \frac{\partial f}{\partial K} - r \Rightarrow r = \frac{\partial f}{\partial K}$$

The relations far to the right mean the following.

Wages = Partial derivative of the production function with respect to L

Capital share = Partial derivative of the production function with respect to K

Now, the reward the people of the country receive for labor is Wage  $\times$  Labor = wL. When this is 70 percent of GDP, we have

wL = 0.7 f(L, K)

Similarly, the reward the capital owners receive is

$$rK = 0.3 f(L, K)$$

From **0** and **0**,

From **2** and **3**,

$$\mathbf{\Theta} \quad \frac{\partial f}{\partial \mathbf{K}} \times \mathbf{K} = \mathbf{0.3} f(\mathbf{L}, \mathbf{K})$$



Cobb found f(L, K) that satisfies these equations. It is

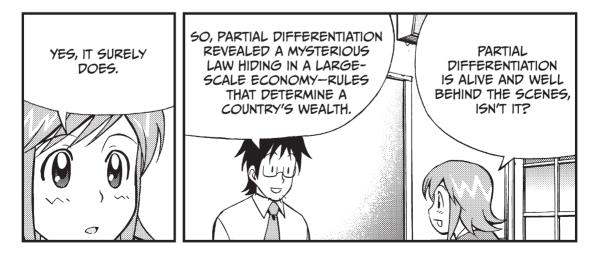
$$f(L,K) = \beta L^{0.7} K^{0.3}$$

where  $\beta$  is a positive parameter meaning the level of technology. Let's check if this satisfies the above conditions.

$$\begin{aligned} \frac{\partial f}{\partial L} \times L &= \frac{\partial \left(\beta L^{0.7} K^{0.3}\right)}{\partial L} \times L = \mathbf{0.7} \beta L^{(-0.3)} K^{0.3} \times L^{1} \\ &= \mathbf{0.7} \beta L^{0.7} K^{0.3} \\ &= \mathbf{0.7} f \left(L, K\right) \end{aligned}$$

$$\frac{\partial f}{\partial \mathbf{K}} \times \mathbf{K} = \frac{\partial \left(\beta L^{0.7} \mathbf{K}^{0.3}\right)}{\partial \mathbf{K}} \times \mathbf{K} = \mathbf{0.3} \beta L^{0.7} \mathbf{K}^{(-0.7)} \times \mathbf{K}^{1}$$
$$= \mathbf{0.3} \beta L^{0.7} \mathbf{K}^{0.3}$$
$$= \mathbf{0.3} f \left( L, \mathbf{K} \right)$$





## THE CHAIN RULE

We have seen single-variable composite functions before (page 14).

$$y = f(x), \ z = g(y), \ z = g(f(x)),$$

$$g(f(x))' = g'(f(x))f'(x)$$
HERE, LET'S DERIVE THE FORMULA OF
PARTIAL DIFFERENTIATION (THE CHAIN RULE)
FOR MULTIVARIABLE COMPOSITE FUNCTIONS

We assume that z is a two-variable function of x and y, expressed as z = f(x, y), and that x and y are both single-variable functions of t, expressed as x = a(t) and y = b(t), respectively. Then, z can be expressed as a function of t only, as shown below.

$$t \xrightarrow{a} x \xrightarrow{} f \xrightarrow{} z$$

This relationship can be written as

$$z = f(x, y) = f(a(t), b(t))$$

What is the form of  $\frac{dz}{dt}$  then?

We assume  $a(t_0) = x_0$ ,  $b(t_0) = y_0$  and  $f(x_0, y_0) = f(a(t_0), b(t_0)) = z_0$  when  $t = t_0$ , and consider only the vicinities of  $t_0$ ,  $x_0$ ,  $y_0$ , and  $z_0$ .

If we obtain an  $\alpha$  that satisfies

$$\mathbf{0} \quad \mathbf{z} - \mathbf{z}_0 \approx \alpha \times (\mathbf{t} - \mathbf{t}_0)$$

it is  $\frac{dz}{dt}(t_0)$ .

First, from the approximation of x = a(t),

$$\Theta \quad x - x_0 \approx \frac{da}{dt} (t_0) (t - t_0)$$

Similarly, from the approximation of y = b(t),

$$\bullet \quad y-y_0 \approx \frac{db}{dt} (t_0) (t-t_0)$$

Next, from the formula of total differential for a two-variable function f(x, y),

Substituting 2 and 3 in 4,

$$\mathbf{G} \quad \mathbf{z} - \mathbf{z}_{0} \approx \frac{\partial f}{\partial \mathbf{x}} (\mathbf{x}_{0}, \mathbf{y}_{0}) \frac{d\mathbf{a}}{dt} (t_{0}) (t - t_{0}) + \frac{\partial f}{\partial \mathbf{y}} (\mathbf{x}_{0}, \mathbf{y}_{0}) \frac{d\mathbf{b}}{dt} (t_{0}) (t - t_{0})$$
$$= \left( \frac{\partial f}{\partial \mathbf{x}} (\mathbf{x}_{0}, \mathbf{y}_{0}) \frac{d\mathbf{a}}{dt} (t_{0}) + \frac{\partial f}{\partial \mathbf{y}} (\mathbf{x}_{0}, \mathbf{y}_{0}) \frac{d\mathbf{b}}{dt} (t_{0}) \right) (t - t_{0})$$

Comparing  $\mathbf{0}$  and  $\mathbf{0}$ , we get

$$\alpha = \frac{\partial f}{\partial x}(x_0, y_0) \frac{da}{dt}(t_0) + \frac{\partial f}{\partial y}(x_0, y_0) \frac{db}{dt}(t_0)$$

This is what we wanted, and we now have the following formula!

#### FORMULA 6-1: THE CHAIN RULE

When  $\mathbf{z} = f(\mathbf{x}, \mathbf{y}), \mathbf{x} = \mathbf{a}(t), \mathbf{y} = \mathbf{b}(t)$ 

$$\frac{dz}{dt} = \frac{\partial f}{\partial x}\frac{da}{dt} + \frac{\partial f}{\partial y}\frac{db}{dt}$$



We assume that the catch of fish can be expressed as a two-variable function g(y, b) of the amount of labor y and the amount of waste b.

(The catch g(y, b) decreases as b increases. Thus,  $\frac{\partial g}{\partial b}$  is negative.)

Since the variable x is contained in g(y, b) = g(y, b(f(x))), production at the factory influences fisheries without going through the market. This is an externality.

First, let's see what happens if the factory and the fishery each act (selfishly) only for their own benefit. If the wage is w for both of them, the price of a commodity produced at the factory p and the price of a fish q, the profit for the factory is given by

Thus, the factory wants to maximize this, and the condition for extrema is

$$(2) \quad \frac{dP_1}{dx} = pf'(x) - w = 0 \Leftrightarrow pf'(x) = w$$

Let s be such x that satisfies this condition. Thus, we have

$$\bigcirc pf'(s) = w$$

This s is the amount of labor employed by the factory, the amount of production is f(s), and the amount of waste is given by

$$b^* = b(f(s))$$

Next, the profit  $P_2$  for the fishery is given by

$$P_2 = qg(y, b) - wy$$

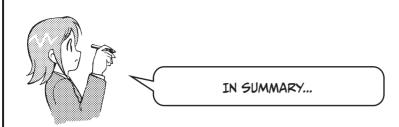
Since the amount of waste from the factory is given by  $b^* = b(f(s))$ ,

 $P_2 = qg(y, b^*) - wy$ 

which is practically a single-variable function of y. To maximize  $P_2$ , we use only the condition about y for extrema of a two-variable function.

(5) 
$$\frac{\partial P_2}{\partial y} = q \frac{\partial g}{\partial y} (y, b^*) - w = 0 \Leftrightarrow q \frac{\partial g}{\partial y} (y, b^*) = w$$

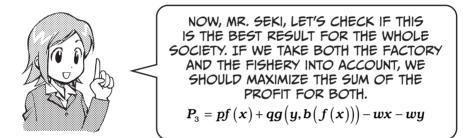
Therefore, the optimum amount of labor t to be input satisfies



The production at the factory and the catch in the fishery when they act freely in this model are given by f(s) and  $g(t, b^*)$ , respectively, where s and t satisfy the following.

3 
$$pf'(s) = w$$
  
6  $h^* = h(f(s)) = a^{\partial g}(t, h^*)$ 

(6) 
$$b^* = b(f(s)), q \frac{\partial g}{\partial y}(t, b^*) = w$$



Since  $P_3$  is a two-variable function of x and y, the condition for extrema is given by

$$\frac{\partial \boldsymbol{P}_3}{\partial \boldsymbol{x}} = \frac{\partial \boldsymbol{P}_3}{\partial \boldsymbol{y}} = \boldsymbol{0}$$

The first partial derivative is obtained as follows.

$$\frac{\partial P_{3}}{\partial x} = pf'(x) + q \frac{\partial g(y, b(f(x)))}{\partial x} - w$$
$$= pf'(x) + q \frac{\partial g}{\partial b}(y, b(f(x)))b'(f(x))f'(x) - w$$

(Here, we used the chain rule.)

Thus,

$$\frac{\partial P_{3}}{\partial x} = \mathbf{0} \Leftrightarrow \left( p + q \frac{\partial g}{\partial b} (y, b(f(x))) b'(f(x)) \right) f'(x) = w$$

Similarly,

Thus, if the optimum amount of labor is S for the factory and T for the fishery, they satisfy

(9) 
$$\left(p+q\frac{\partial g}{\partial b}(T,b(f(\mathbf{S})))b'(f(\mathbf{S}))\right)f'(\mathbf{S}) = w$$
  
(10)  $q\frac{\partial g}{\partial y}(T,b(f(\mathbf{S}))) = w$ 

Although these equations look complicated, they are really just twovariable simultaneous equations.

If we compare these equations with equations 3 and 6, we find that 3 and 9 are different while 6 and 10 are the same. Then, how do they differ?

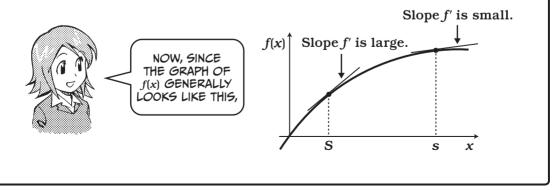
$$\textbf{3} \quad \boldsymbol{p} \times \boldsymbol{f}'(\boldsymbol{s}) = \boldsymbol{w}$$

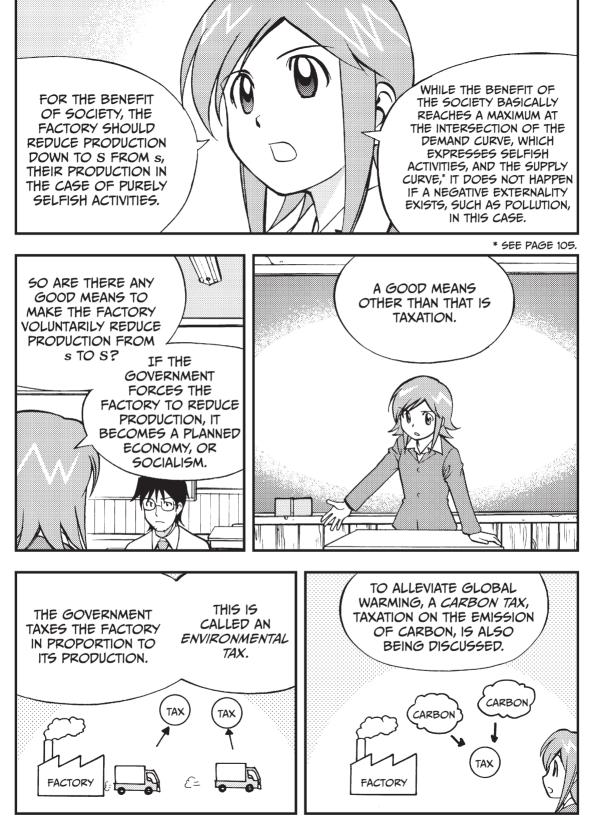
(i) 
$$(p + \Psi) \times f'(\mathbf{S}) = w$$

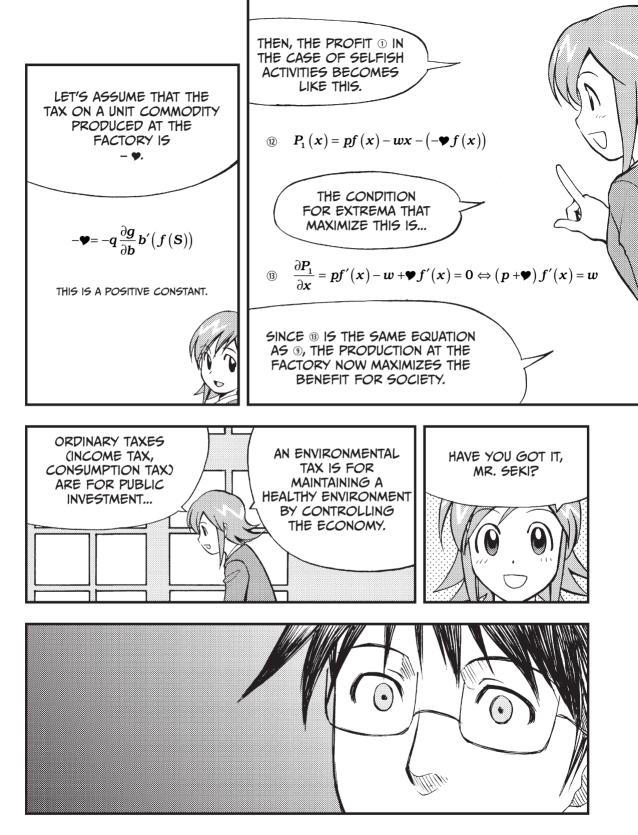
As you see here,  $\Psi$  has appeared in the expression.

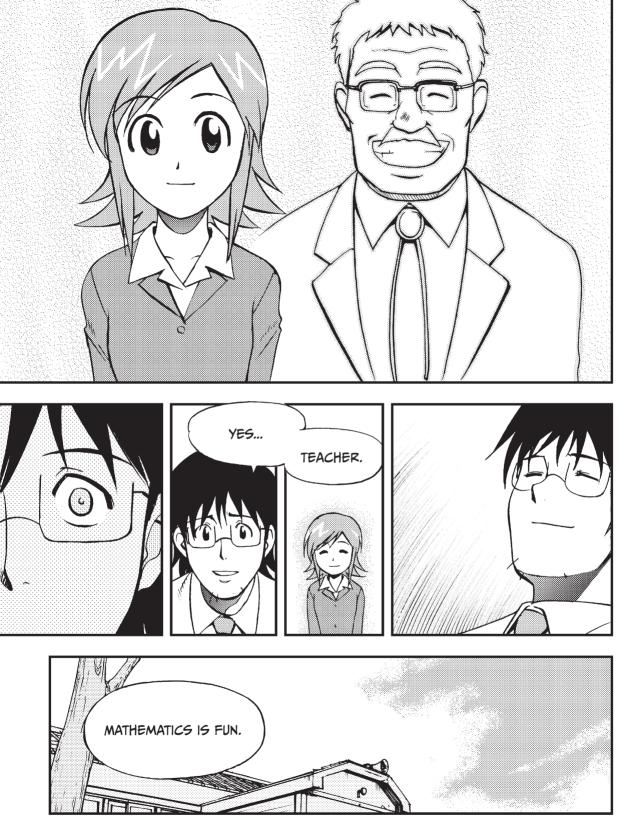
Since 
$$\left( \Psi = q \frac{\partial g}{\partial b} b'(f(\mathbf{S})) \right)$$
 is negative,  $p + \Psi$  is smaller than  $p$ .

Since f'(S) or f'(s) is multiplied to the first part to give the same value w, f'(S) must be larger than f'(s).

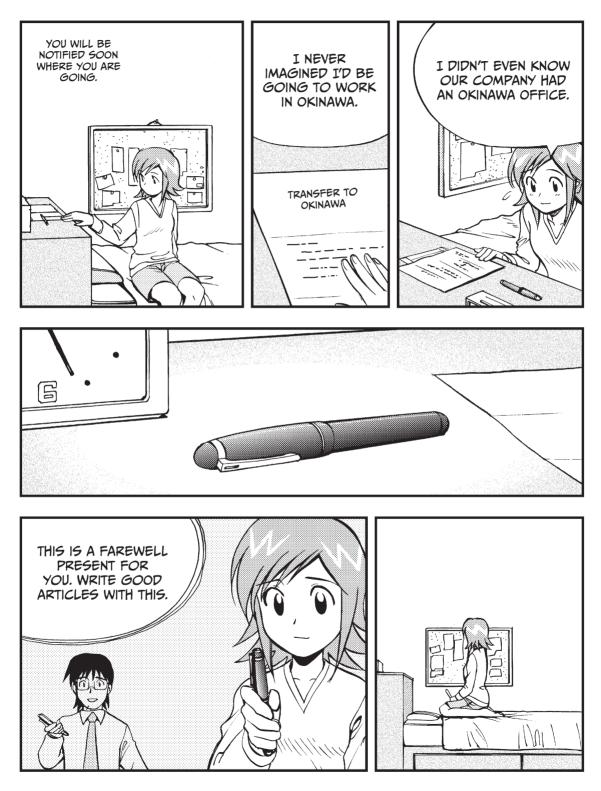




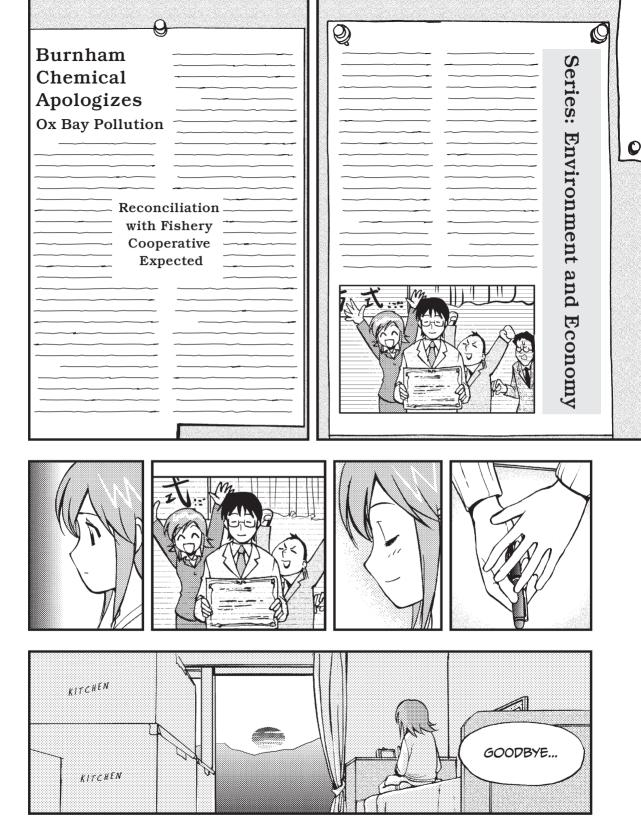








216 CHAPTER 6 LET'S LEARN ABOUT PARTIAL DIFFERENTIATION!



## DERIVATIVES OF IMPLICIT FUNCTIONS

A point (x, y) for which a two-variable function f(x, y) is equal to constant c describes a graph given by f(x, y) = c. When a part of the graph is viewed as a single-variable function y = h(x), it is called an *implicit function*. An implicit function h(x) satisfies f(x, h(x)) = c for all x defined. We are going to obtain h(x) here.

When z = f(x, y), the formula of total differentials is written as  $dz = f_x dx + f_y dy$ . If (x, y) moves on the graph of f(x, y) = c, the value of the function f(x, y) does not change, and the increment of z is 0, that is, dz = 0. Then, we get  $0 = f_x dx + f_y dy$ . Assuming  $f_y \neq 0$  and modifying this, we get

$$\frac{dy}{dx} = -\frac{f_x}{f_y}$$

The left side of this equation is the ideal expression of the increment of y divided by the increment of x at a point on the graph. It is exactly the derivative of h(x). Thus,

$$h'(x) = -\frac{f_x}{f_y}$$

EXAMPLE

 $f(x, y) = r^2$ , where  $f(x, y) = x^2 + y^2$ , describes a circle of radius *r* centered at the origin. Near a point that satisfies  $x^2 \neq r^2$ , we can solve  $f(x, y) = x^2 + y^2 = r^2$  to find the implicit function  $y = h(x) = r^2 - x^2$  or  $y = h(x) = -\sqrt{r^2 - x^2}$ . Then, from the formula, the derivative of these functions is given by

$$h'(x) = -\frac{f_x}{f_y} = -\frac{x}{y}$$

# EXERCISES

- 1. Obtain  $f_x$  and  $f_y$  for  $f(x, y) = x^2 + 2xy + 3y^2$ .
- 2. Under the gravitational acceleration g, the period T of a pendulum having length L is given by

$$T = 2\pi \sqrt{rac{L}{g}}$$

(the gravitational acceleration g is known to vary depending on the height from the ground).

Obtain the expression for total differential of T.

If L is elongated by 1 percent and g decreases by 2 percent, about what percentage does T increase?

3. Using the chain rule, calculate the differential formula of the implicit function h(x) of f(x, y) = c in a different way than above.

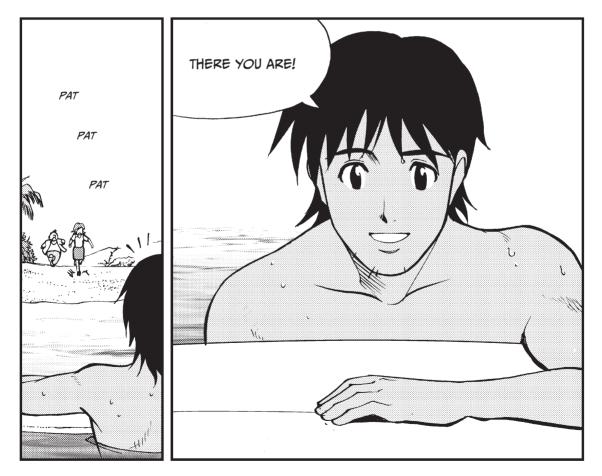




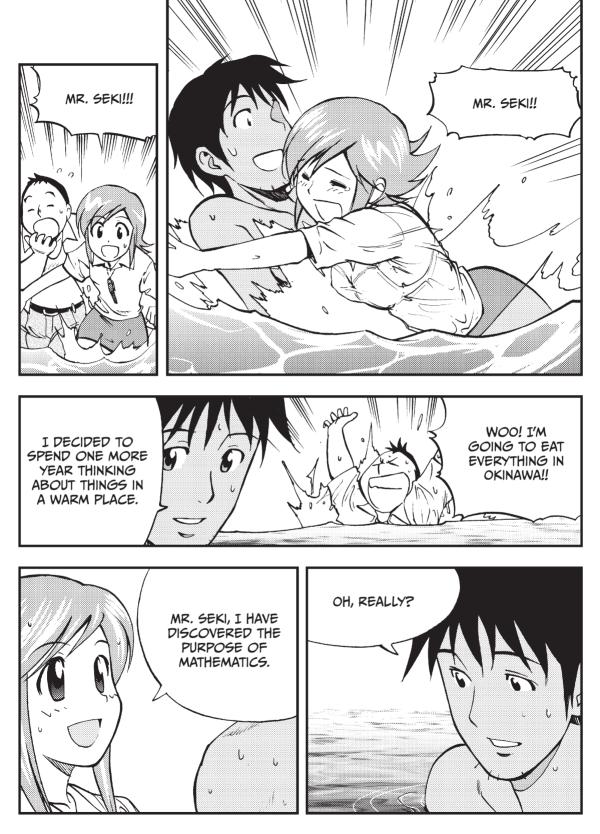








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# A SOLUTIONS TO EXERCISES

# PROLOGUE

1. Substituting

$$y = \frac{5}{9}(x - 32)$$
 in  $z = 7y - 30, z = \frac{35}{9}(x - 32) - 30$ 

## CHAPTER 1

1. A. 
$$f(5) = g(5) = 50$$
  
B.  $f'(5) = 8$ 

2. 
$$\lim_{\varepsilon \to 0} \frac{f(a+\varepsilon) - f(a)}{\varepsilon} = \lim_{\varepsilon \to 0} \frac{(a+\varepsilon)^3 - a^3}{\varepsilon} = \lim_{\varepsilon \to 0} \frac{3a^2\varepsilon + 3a\varepsilon^2 + \varepsilon^3}{\varepsilon}$$
$$= \lim_{\varepsilon \to 0} (3a^2 + 3a\varepsilon + \varepsilon^2) = 3a^2$$

Thus, the derivative of f(x) is  $f'(x) = 3x^2$ .

# CHAPTER 2

1. The solution is

$$f'(x) = -\frac{(x^{n})'}{(x^{n})^{2}} = -\frac{nx^{n-1}}{x^{2n}} = -\frac{n}{x^{n+1}}$$

2.  $f'(x) = 3x^2 - 12 = 3(x-2)(x+2)$ 

When x < -2, f'(x) > 0, when -2 < x < 2, f'(x) < 0, and when x > 2, f'(x) > 0. Thus at x = -2, we have a maximum with f(-2) = 16, and at x = 2, we have a maximum with f(2) = -16.

3. Since  $f(x) = (1 - x)^3$  is a function g(h(x)) combining  $g(x) = x^3$  and h(x) = 1 - x.

$$f'(x) = g'(h(x))h'(x) = 3(1-x)^2(-1) = -3(1-x)^2$$

4. Differentiating  $g(x) = x^2(1-x)^3$  gives

$$g'(x) = (x^{2})'(1-x)^{3} + x^{2}((1-x)^{3})'$$
  
=  $2x(1-x)^{3} + x^{2}(-3(1-x)^{2})$   
=  $x(1-x)^{2}(2(1-x)-3x)$   
=  $x(1-x)^{2}(2-5x)$   
 $g'(x) = 0$  when  $x = \frac{2}{5}$  or  $x = 1$ , and  $g(1) = 0$ .  
Thus it has the maximum  $g(\frac{2}{5}) = \frac{108}{3125}$  at  $x = \frac{2}{5}$ 

## CHAPTER 3

1. The solutions are

$$\int_{1}^{3} 3x^{2} dx = x^{3} \Big|_{1}^{3} = 3^{3} - 1^{3} = 26$$

$$\int_{2}^{4} \frac{x^{3} + 1}{x^{2}} dx = \int_{2}^{4} \left( x + \frac{1}{x^{2}} \right) dx = \int_{2}^{4} x dx + \int_{2}^{4} \frac{1}{x^{2}} dx$$

$$= \frac{1}{2} \left( 4^{2} - 2^{2} \right) - \left( \frac{1}{4} - \frac{2}{4} \right) = \frac{25}{4}$$

$$\int_{0}^{5} x + \left( 1 + x^{2} \right)^{7} dx + \int_{0}^{5} x - \left( 1 + x^{2} \right)^{7} dx = \int_{0}^{5} 2x dx = 5^{2} - 0^{2} = 25$$

2. A. The area between the graph of 
$$y = f(x) = x^2 - 3x$$
 and the x-axis equals  
 $-\int_0^3 x^2 - 3x dx$   
B.  $-\int_0^3 x^2 - 3x dx = -\left(\frac{1}{3}x^3 - \frac{3}{2}x^2\right)\Big|_0^3 = -\frac{1}{3}(3^3 - 0^3) + \frac{3}{2}(3^2 - 0^2) = \frac{9}{2}$ 

# CHAPTER 4

1. The solution is

$$(\tan x)' = \left(\frac{\sin x}{\cos x}\right)' = \frac{(\sin x)'\cos x - \sin x(\cos x)'}{\cos^2 x}$$
$$= \frac{\cos^2 x + \sin^2 x}{\cos^2 x} = \frac{1}{\cos^2 x}$$

z. Since

$$(\tan x)' = \frac{1}{\cos^2 x}$$
$$\int_0^{\frac{\pi}{4}} \frac{1}{\cos^2 x} \, dx = \tan \frac{\pi}{4} - \tan 0 = 1$$

3. From

$$f'(x) = (x)'e^{x} + x(e^{x})' = e^{x} + xe^{x} = (1+x)e^{x}$$

the minimum is

$$f(-1) = -\frac{1}{e}$$

4. Setting  $f(x) = x^2$  and  $g(x) = \ln x$ , integrate by parts.

$$\int_{1}^{e} (x^{2})^{'} \ln x dx + \int_{1}^{e} x^{2} (\ln x)^{'} dx = e^{2} \ln e - \ln 1$$

Thus,

$$\int_{1}^{e} 2x \ln x dx + \int_{1}^{e} x^{2} \frac{1}{x} dx = e^{2}$$
$$\int_{1}^{e} 2x \ln x dx = -\int_{1}^{e} x dx + e^{2} = -\frac{1}{2} (e^{2} - 1)^{2} + e^{2}$$
$$= \frac{1}{2} e^{2} + \frac{1}{2}$$

# CHAPTER 5

1. For

$$f(x) = e^{-x}, f'(x) = -e^{-x}, f''(x) = e^{-x}, f'''(x) = -e^{-x}$$
  

$$f(0) = 1, f'(0) = -1, f''(0) = 1, f'''(0) = -1...$$
  

$$f(x) = 1 - x + \frac{1}{2!}x^2 - \frac{1}{3!}x^3 + ...$$

2. Differentiate

$$f(x) = (\cos x)^{-1}, f'(x) = (\cos x)^{-2} \sin x$$
$$f''(x) = 2(\cos x)^{-3} (\sin x)^{2} + (\cos x)^{-2} \cos x$$
$$= 2(\cos x)^{-3} (\sin x)^{2} + (\cos x)^{-1}$$

from f(0) = 1, f'(0) = 0, f''(0) = 1

3. Proceed in exactly the same way as on page 155 by differentiating f(x) repeatedly. Since you are centering the expansion around x = a, plugging in a will let you work out the  $c_n$ s. You should get  $c_n = 1/n! f^{(n)}(a)$ , as shown in the formula on page 159.

# CHAPTER 6

- 1. For  $f(x, y) = x^2 + 2xy + 3y^2$ ,  $f_x = 2x + 2y$ , and  $f_y = 2x + 6y$ .
- 2. The total differential of

$$T = 2\pi \sqrt{\frac{L}{g}} = 2\pi g^{-\frac{1}{2}} L^{\frac{1}{2}}$$

is given by

$$dT = \frac{\partial T}{\partial g} dg + \frac{\partial T}{\partial L} dL = -\pi g^{-\frac{3}{2}} L^{\frac{1}{2}} dg + \pi g^{-\frac{1}{2}} L^{-\frac{1}{2}} dL$$

Thus,

$$\Delta \boldsymbol{T} \approx -\pi \boldsymbol{g}^{-\frac{3}{2}} \boldsymbol{L}^{\frac{1}{2}} \Delta \boldsymbol{g} + \pi \boldsymbol{g}^{-\frac{1}{2}} \boldsymbol{L}^{-\frac{1}{2}} \Delta \boldsymbol{L}$$

Substituting  $\Delta g = -0.02g$ ,  $\Delta L = 0.01L$ , we get

$$\Delta T \approx 0.02\pi g^{-\frac{3}{2}} L^{\frac{1}{2}} g + 0.01\pi g^{-\frac{1}{2}} L^{-\frac{1}{2}} L$$
$$= 0.03\pi g^{-\frac{1}{2}} L^{\frac{1}{2}} = 0.03 \frac{T}{2} = 0.015T$$

So T increases by 1.5%.

3. If we suppose y = h(x) is the implicit function of f(x, y) = c. Thus, since the left side is a constant in this region, f(x, h(x)) = c

near x.

From the chain rule formula

$$\frac{df}{dx} = 0, \frac{df}{dx} = f_x + f_y h'(x) = 0$$

Therefore

$$h'(\boldsymbol{x}) = -\frac{f_x}{f_y}$$

# B

# MAIN FORMULAS, THEOREMS, AND FUNCTIONS COVERED IN THIS BOOK

# LINEAR EQUATIONS (LINEAR FUNCTIONS)

The equation of a line that has slope m and passes through a point (a, b):

$$y = m(x - a) + b$$

### DIFFERENTIATION

DIFFERENTIAL COEFFICIENTS

$$f'(a) = \lim_{h \to 0} \frac{f(a+h) - f(a)}{h}$$

DERIVATIVES

$$f'(\mathbf{x}) = \lim_{h \to 0} \frac{f(\mathbf{x} + \mathbf{h}) - f(\mathbf{x})}{\mathbf{h}}$$

Other notations for derivatives

$$\frac{dy}{dx}, \frac{df}{dx}, \frac{d}{dx}f(x)$$

CONSTANT MULTIPLES

$$\left\{ \alpha f(\mathbf{x}) \right\}' = \alpha f'(\mathbf{x})$$

DERIVATIVES OF NTH-DEGREE FUNCTIONS

$$\left\{\boldsymbol{x}^{n}\right\}' = \boldsymbol{n}\boldsymbol{x}^{n-1}$$

SUM RULE OF DIFFERENTIATION

PRODUCT RULE OF DIFFERENTIATION

QUOTIENT RULE OF DIFFERENTIATION

$$\left\{f(x)+g(x)\right\}'=f'(x)+g'(x)$$

D

$$\left\{\frac{g(x)}{f(x)}\right\}' = \frac{g'(x)f(x) - g(x)f'(x)}{\left\{f(x)\right\}^2}$$

 $\left\{f(x)g(x)\right\}' = f'(x)g(x) + f(x)g'(x)$ 

$$\left\{\frac{g(x)}{f(x)}\right\} = \frac{g'(x)f(x) - g(x)f'(x)}{\left\{f(x)\right\}^2}$$

$$\left\{ \boldsymbol{g}(\boldsymbol{f}(\boldsymbol{x})) \right\}' = \boldsymbol{g}'(\boldsymbol{f}(\boldsymbol{x})) \boldsymbol{f}'(\boldsymbol{x})$$

$$\left\{ \boldsymbol{g}(\boldsymbol{f}(\boldsymbol{x})) \right\} = \boldsymbol{g}'(\boldsymbol{f}(\boldsymbol{x})) \boldsymbol{f}'$$

When 
$$y = f(x)$$
 and  $x = g(y)$ 

When 
$$y = f(x)$$
 and  $x = q(y)$ 

vnen 
$$g = f(x)$$
 and  $x =$ 

$$g'(y) = rac{1}{f'(x)}$$

EXTREMA

If y = f(x) has a maximum or a minimum at x = a, f'(a) = 0. y = f(x) is increasing around x = a, if f'(a) > 0. y = f(x) is decreasing around x = a, if f'(a) < 0.

THE MEAN VALUE THEOREM

For a, b (a < b), there is a c with a < c < b, so that

$$f(b) = f'(c)(b-a) + f(a)$$

# DERIVATIVES OF POPULAR FUNCTIONS

TRIGONOMETRIC FUNCTIONS

$$\left\{\cos\theta\right\}' = -\sin\theta, \left\{\sin\theta\right\}' = \cos\theta$$

EXPONENTIAL FUNCTIONS

$$\left\{ \boldsymbol{e}^{x}\right\} ^{\prime}=\boldsymbol{e}^{x}$$

LOGARITHMIC FUNCTIONS

$$\left\{\log x\right\}' = \frac{1}{x}$$

## INTEGRALS

DEFINITE INTEGRALS When F'(x) = f(x)

$$\int_{a}^{b} f(\boldsymbol{x}) d\boldsymbol{x} = \boldsymbol{F}(\boldsymbol{b}) - \boldsymbol{F}(\boldsymbol{a})$$

CONNECTION OF INTERVALS OF DEFINITE INTEGRALS

$$\int_{a}^{b} f(x) dx + \int_{b}^{c} f(x) dx = \int_{a}^{c} f(x) dx$$

SUM OF DEFINITE INTEGRALS

$$\int_{a}^{b} \left\{ f(x) + g(x) \right\} dx = \int_{a}^{b} f(x) dx + \int_{a}^{b} g(x) dx$$

CONSTANT MULTIPLES OF DEFINITE INTEGRALS

$$\int_{a}^{b} \alpha f(\mathbf{x}) d\mathbf{x} = \alpha \int_{a}^{b} f(\mathbf{x}) d\mathbf{x}$$

SUBSTITUTION OF INTEGRALS

When x = g(y),  $b = g(\beta)$ ,  $a = g(\alpha)$ 

$$\int_{a}^{b} f(x) dx = \int_{a}^{\beta} f(g(y)) g'(y) dy$$

INTEGRATION BY PARTS

$$\int_{a}^{b} f'(x)g(x)dx + \int_{a}^{b} f(x)g'(x)dx = f(b)g(b) - f(a)g(a)$$

# TAYLOR EXPANSION

When f(x) has a Taylor expansion near x = a,

$$f(x) = f(a) + \frac{1}{1!} f'(a)(x-a) + \frac{1}{2!} f''(a)(x-a)^{2} + \frac{1}{3!} f'''(a)(x-a)^{3} + \dots + \frac{1}{n!} f^{(n)}(a)(x-a)^{(n)} + \dots$$

TAYLOR EXPANSIONS OF VARIOUS FUNCTIONS

$$\cos x = 1 - \frac{1}{2!}x^{2} + \frac{1}{4!}x^{4} + \dots + (-1)^{n}\frac{1}{(2n)!}x^{2n} + \dots$$
$$\sin x = x - \frac{1}{3!}x^{3} + \frac{1}{5!}x^{5} + \dots + (-1)^{n-1}\frac{1}{(2n-1)!}x^{2n-1} + \dots$$
$$e^{x} = 1 + \frac{1}{1!}x + \frac{1}{2!}x^{2} + \frac{1}{3!}x^{3} + \frac{1}{4!}x^{4} + \dots + \frac{1}{n!}x^{n} + \dots$$
$$\ln(1+x) = x - \frac{1}{2}x^{2} + \frac{1}{3}x^{3} - \frac{1}{4}x^{4} + \dots + (-1)^{n+1}\frac{1}{n}x^{n} + \dots$$

# PARTIAL DERIVATIVES

PARTIAL DERIVATIVES

$$\frac{\partial f}{\partial x} = \lim_{h \to 0} \frac{f(x+h, y) - f(x, y)}{h}$$
$$\frac{\partial f}{\partial y} = \lim_{k \to 0} \frac{f(x, y+k) - f(x, y)}{k}$$

TOTAL DIFFERENTIALS

$$dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$$

FORMULA OF CHAIN RULE

When z = f(x, y), x = a(t), y = b(t)

$$\frac{dz}{dt} = \frac{\partial f}{\partial x}\frac{da}{dt} + \frac{\partial f}{\partial y}\frac{db}{dt}$$

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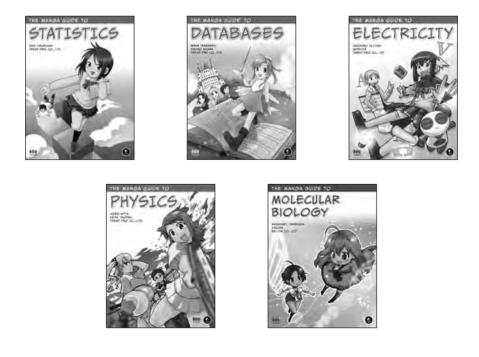
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