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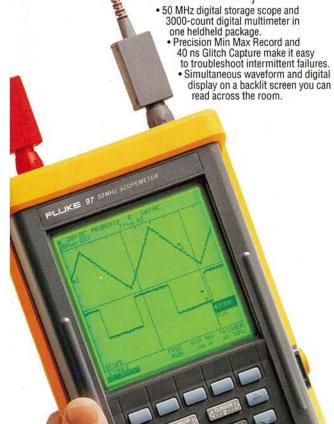
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Vol. 63 No. 2

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# WHAT'S NEWS

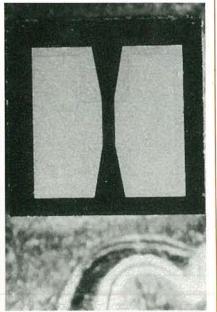
A review of the latest happenings in electronics.

Device for multiple automobile air bags

Researchers at Sandia National Laboratories (Albuquerque, NM) have invented a low-energy explosive igniter that could make it easier for automobile manufacturers to install multiple air bags in their vehicles. The device, called a semiconductor bridge or SCB, requires much less energy than the hot-wire igniters that are traditionally used in air-bag systems.

During the rapid deceleration caused by a crash, air bags are electrically ignited by a hot-wire device in an explosive cartridge. As the device heats, the sensitive explosive material burns. A hot gas is produced that enters the stowed air bag and ignites a gas-generating propellant, which then releases a burst of nitrogen gas that quickly inflates the bag. That entire process takes place in just thousandths of a second.

When designing air-bag systems, a worst-case scenario of an almost



SANDIA'S SEMICONDUCTOR BRIDGE, which could be used in multiple air-bag systems, is shown resting on a penny. The penny's "C" letter give an indication of the device's size.

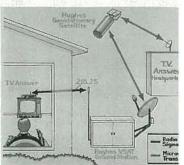
depleted battery is used. In such a case, one hot-wire igniter would consume nearly all of the battery's remaining voltage output—which means trouble for systems incorporating several air bags and explosively activated seat belts.

The semiconductor bridge is about one one-hundredth the volume of a conventional hot wire, and can be heated much faster and with much less energy. Because SCB's are processed on a silicon wafer, the chip can incorporate extra circuitry for logic, timing, and safety.

# Multimillion dollar interactive TV/satellite contract

The introduction of nationwide interactive television is a step closer with the signing of a multimillion contract between TV Answer, a pioneer in real-time wireless Interactive Video Data Service (IVDS) technology, and Hughes Network Systems, Inc. (HNS), manufacturer of interactive Very Small Aperture Terminals (VSAT's). Pending FCC approval, the TV Answer system would allow television viewer to use their TV's as communication devices to pay bills, order take-out food, shop for groceries, do banking transactions, and respond in real time to game shows, TV shopping shows, advertisements, polls, and interactive news and educational programs. In addition, it would serve as a universal remote control, and would provide on-screen TV schedules and VCR programming. The system would work with cable, satellite, and roof-top antenna systems and is expected to cost about \$12.95 a month.

Similar in structure to a cellular phone network, the TV Answer network relies on individual cell sites to provide service to a market area consisting of a maximum of 10,000 households. Each cell site includes a VSAT two-way satellite dish earthstation that communicates with TV



TV ANSWER'S INTERACTIVE VII DATA SERVICE would use Hughes work Systems' satellite personal e stations to provide direct transmis paths between remote cell sites and hub station.

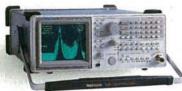
Answer Headquarters via a Hug satellite, and a TV Answer radic ceiver/transmitter that comm cates with TV Answer home ur The data received via satellit transformed at the cell site int radio signal that is transmitted each home unit. Viewer respon are relayed to the cell site and t back to headquarters in the saway. There the responses are cessed and appropriate collect billing, and ordering activities performed.

The January 10, 1991 FCC No of Proposed Rulemaking proposed Rulemaking proposed Rulemaking proposed for the allocation of ½-MHz of the respectrum—between 218.00 219.00 MHz, which is the freque on which TV Answer's system of ates—for an Interactive Video I Service. The action is expected be finalized, and technical sedards and licensing procedures sued, by mid-1992.

Under the initial phase of the tract between HNS and TV Ans HNS will build and install 1 VSAT units for use in cell site enough to meet the projected 1 year requirement. The initial pl includes a \$2.1 million hub and work control system at TV Ans headquarters in Reston, VA. TV swer estimates that a minimul 10,000 VAST units will be needed provide nationwide coverage for technology.

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# **VIDEO NEWS**

What's new in the fast-changing video industry.

### DAVID LACHENBRUCH

# Compact Disc-Interactive.

Philips has launched its CD-I interactive audio-video multimedia system through 5000 stores, and first reports indicated that the players and discs were selling well. Philips changed its mind about brand name, and its first products were issued under the "Philips" instead of the "Magnavox" brand. The list price of the player was dropped to \$1000 from \$1400, but for all practical purposes, players are selling at about \$800, and discs from \$20 to \$40. Using the theme, "the Imagination Machine," Philips plans maior advertising campaigns for the system throughout 1992. This is the second multimedia CD system aimed at the general public via attachments to TV sets, the first being Commodore's CDTV (which stands for Commodore Dynamic Total Vision). Other manufacturers are competing with video and audio CD-ROM systems designed as computer peripherals.

• Zenith moves TV. The last major American-owned TV manufacturer will end color-TV manufacture in the United States sometime this year. Zenith Electronics announced that it will start phasing out final assembly of sets in its Springfield, MO plant when its union contract expires on March 22. The company, which has been losing money, explained that price erosion has continued in the TV industry and cost-cutting efforts haven't been sufficient, despite wage concessions by its union in Springfield.

Zenith will move final assembly of large-screen TV sets to its cabinet plant in Juarez, Mexico. Its 19- and 20-inch sets are already being assembled in Reynosa, Mexico. Some plastic molding and distribution operations will continue in Springfield. Zenith will continue to operate its large-picture-tube plant and headquarters in the Chicago. The only other American-owned TV assembler, Curtis Mathis Corpora-

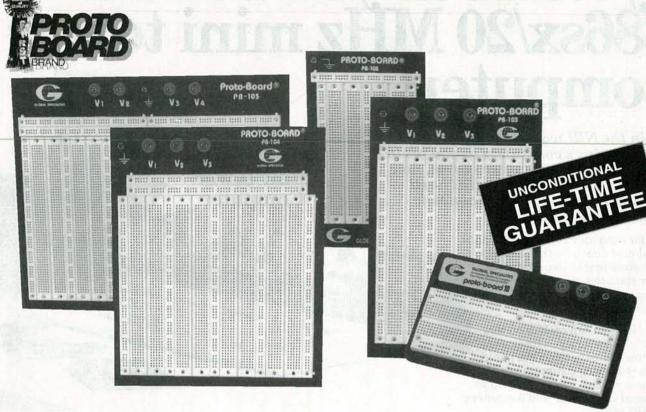
tion, has a final assembly plant in Athens, TX. Although the remainder of TV manufacturers are foreignowned, many of them continue to assemble their large-screen color TV's in the United States. The leaders are Thomson Consumer Electronics (French-owned), which assembles RCA and GE sets in Bloomington, IN, and Philips (Dutch), which produces Magnavox. Sylvania, and Philips sets in Greeneville, TN. Other final TV assembly is done in Huntsville, AL, by Goldstar (Korean); by Japanese manufacturers in Anaheim, CA; JVC in Elmwood Park, NJ; Mitsubishi in Santa Ana, CA and Braselton, GA; Orion in Princeton, IN; Sanyo in Forrest City, AR; Sharp in Memphis; Toshiba in Lebanon, TN; and Sony in San Diego and soon in New Stanton, PA.

• "Stereo" TV debate. As it promised more than a year ago (Radio-Electronics, March 1991), a company called dbx Technology Licensing has started a public-relations campaign to inform the public that if a television set doesn't conform with the FCC-backed stereo-TV system, it shouldn't be called 'stereo TV." However, Thomson Consumer Electronics, manufacturer of RCA and GE brand sets, has challenged dbx, saying that some of its sets contain a new system called "XS" and qualify as stereo even though they don't use the dbx noise-reduction decoding technology that is officially part of the Multichannel TV System (MTS) stereo standard.

Although Thomson's higherpriced sets do use dbx decoding, Thomson says that the XS sound system, which uses phase shift to process the sound, qualifies as "stereo" even though little separation between left and right channels shows up in tests. dbx demonstrated test results that it says shows that some RCA and GE sets don't reconstruct the true sound transmitted by the TV static Thomson retorts that its XS svs sounds better than dbx in lo priced sets. In addition to Thom dbx Technology found that so Philips and some Sharp sets c use dbx decoding in their ste systems. Both of those compar which use dbx in some of their s say they plan to add dbx across board to all of their sets later year. Since there is no official de tion of "stereo," the dispute is pected to continue for some t Stereo systems using various ty of phase-shift techniques to hance the "presence" effec clude Q sound and SRS, the la developed by Hughes Aircraft being used tin some high-end by Sony and Thomson as an adj to MTS stereo. dbx says that's c some people may prefer proces sound, but officially MTS soun cludes dbx encoding and decor therefore, saying that a set inclu "broadcast TV stereo" or "I stereo" is misleading.

• TV for computers. For y we've heard about the upcor merger of TV and the computer CD-I system is one aspect of adding computer functions to TV set. Moving in the opposit rection, IBM and others are ac TV functions to the compute March, IBM will offer a TV acce ry for its PS/2 computers. That adaptor that permits the compu keyboard to be used to select among 70 TV channels as we the other normal TV functions course, other video devices ma input as well, including lase players or VCR's. The TV pi may be viewed full-screen or i ted in a window—there's no like watching MTV while workir a spreadsheet! The IBM acces will carry a list price of \$495, v may be cheap for a computer on. But in TV-land, the same an will be a 25-inch color TV set v remote control.

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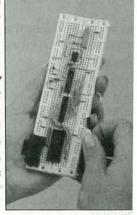
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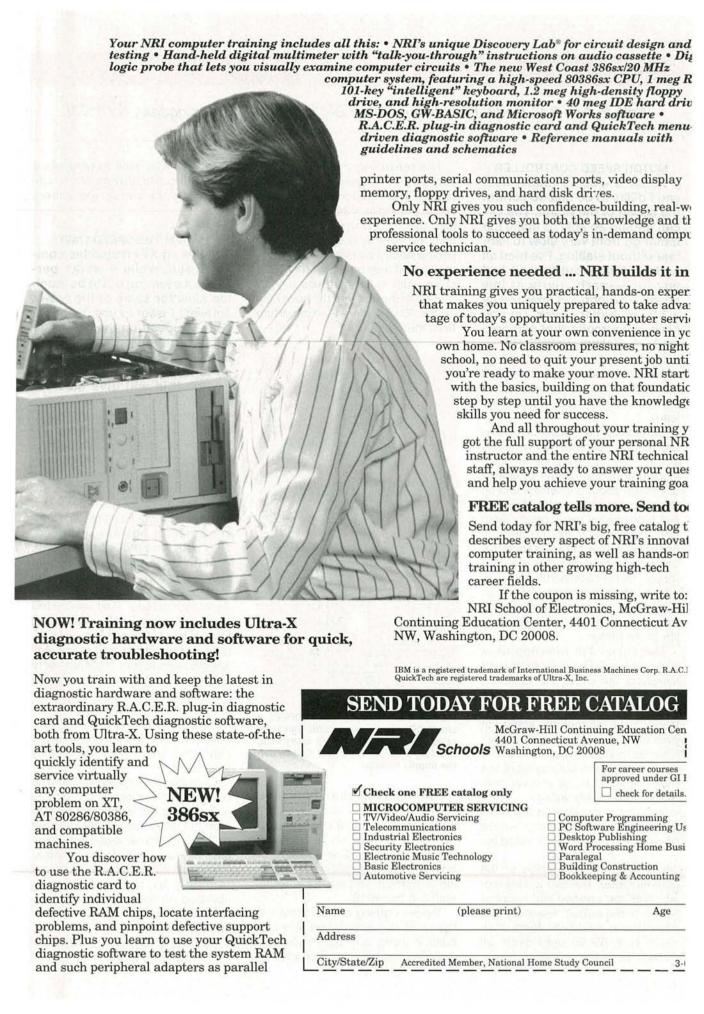
You assemble and test your computer's "intelligent" keyboard, install the power supply and 1.2 meg, high-density floppy disk drive, then interface the high-resolution monitor.

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# **ASK R-E**

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### MOTOR SPEED CONTROLLER

I have a electric model boat and I'd like to be able to control the speed of the motor. The circuit should be able to make the motor go from very slow to very fast without stalling. I've tried all sorts of things but haven't had any luck—particularly at low speed. The motor is powered by a 7.2-volt battery pack. Do you have any circuits that can help me?—A. Balsys, Howell, NJ

Electric boats aren't my thing but I would have imagined that they all had some way to vary the speed of the motors. Oh well, you live and learn.

Controlling the speed of a small DC motor is something I've talked about several times before but, judging from the number of times I get asked about it in letters and on the phone, it seems a lot of people are interested in the subject. There are several ways to get the job done and even some fairly inexpensive commercial products that will do it for you. In this case, particularly with such a low-voltage motor, there's an easy circuit you can build that will do the job and operate reliably for the life of the motor.

The circuit I'm referring to is shown in Fig. 1. Despite its apparent simplicity, the circuit will drive the motor over a range of speeds from dead slow to full ahead (that's boat talk, I think), without any stalling at even the lowest speeds. The reason it can do this is that the circuit works by controlling the duty cycle of the motor rather than, as in other controllers, the supply voltage.

Two of the inverters in the 4049 are set up as an oscillator whose frequency is roughly determined by: F = 1/1.4RC

where R is the total value of the potentiometer. The two diodes isolate both the positive and negative halves of the output frequency and make the output waveform stick close to a 50-50 duty cycle all through its entire operating range.

The remaining inverters in the package are all ganged together in parallel to increase the output drive to the transistor. While you can use just about any inverter for the circuit, the 4049 is probably the best choice since it can handle more output current than other inverting gate chips. Just make sure you pay attention to the fact that the power pin on the 4049 is pin #1—a departure from the other IC's.

FIG. 1—THIS CIRCUIT WILL DRIVE a small DC motor over a wide range of speeds without stalling by controlling the duty cycle of the motor rather than the supply voltage.

Even though the schematic shows the supply voltage to the motor and the circuit on two separate lines, there's no reason why you can't use the 7.2-volt battery for both of them. The battery is supplying a perfect voltage for CMOS stuff like the 4049.

There's nothing critical about the layout of the circuit and you can build it using any technique you want. In actual fact, it's such a handy

circuit you may want to general printed circuit board for it so you easily use the circuit somewhelse.

WATCH THE SPEED LIMIT
I have an XT-compatible coputer and, while it works prectly, it's turning out to be mitton slow for some of the nesoftware I want to use. Is it pushed to speed up the compute pushed up the compute pushed up the compute pushed

Before we get into this, I war make sure you understand that increase in speed you can get this is going to be far outweighethe amount of brain damage it to do it. The theory is great but maximum speed of a motherbolike an automotive engine, is a sequence of how it's design.

At the most basic level, the pon your motherboard were cho to match the computer's origina sign specifications. The memory, controller, interrupt controller, DMA (Direct Memory Access) troller have maximum speed rat and the ones in your computer vpic sed to match the speed of board. The faster any chip's sprating, the more expensive it don't know who made your morboard but it's a safe bet that parts on it are only as fast as have to be.

Changing the crystal changes board's master clock and the r you step on the electronic acc ator, the closer you're going to to the point where these chips get flaky and finally fail comple. The point where that happens is termined by the speed ra stamped on the chips and the tails of the design of your mo board.

Memory chips have a maxir speed rating as well and it's us

stamped on the top of the IC right after the chip number. A suffix of 20 means 200 nanoseconds, 15 means 150 nanoseconds, and so on. If the only crystal on your motherboard is a 14.31818-MHz one, it's more than likely that your computer is running, like the original IBM PC, at a speed of 4.77 MHz. This means that your motherboard can operate with memory as slow as 200 nanoseconds. If that's what you have in your machine, you don't have much of a chance of upping the system speed and still maintain much in the way of reliability.

It's possible you can overcome these problems if the design of your motherboard incorporates enough wait states to do things like memory refresh and other housekeeping chores at an increased speed. But there's still another problem that has to be considered.

There are two clock frequencies at the expansion slots and most of the cards you plug into the mother-board are designed to expect the two clocks to be in a particular frequency range. Pin #B20 is known as the CLK and on your motherboard it's probably a buffered version of the 8088's clock frequency—4.77 MHz. That frequency can be higher, and you'll frequently find that it's as high up as 8 MHz.

The second frequency is the one that can cause you a problem. In the original PC (of which yours is a clone), pin #B30 was a buffered version of the crystal frequency—14.31818 MHz. That has remained a standard, even up to this day. Measure the frequency at that pin on the latest 33-MHz 486 motherboard and you'll find 14.31818 MHz. When you change the crystal on the board, you'll also be changing both frequencies at the expansion slots which can cause a problem with some cards that use the two clocks.

The biggest problem will come with floppy-disk controllers since they use those clocks for writing to the disk. Even if you somehow avoid the problem, it's a guaranteed fact that you'll have problems formatting disks.

Keeping all this stuff in mind, you can start experimenting with higher-frequency crystals to see how far you can go before you have major

problems. My guess is that the most you'll be able to get is a 50% increase in speed. If you want to be able to format disks, you have to supply the computer with the original frequencies so don't get rid of the original crystal. Probably the easiest way to do that is to have both the crystals on the mother-board and use a switch to select one or the other.

We're talking about doing a good deal of work here and the possible rewards are really minimal. A 50% increase in speed may sound like a lot but you'll find that the practical effects are just not all that noticeable. A much better solution to the whole problem is to buy a new motherboard that's been designed from the ground up to run faster than the one you have now.



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# LETTERS

Write to Letters, Radio-Electronics, 500-B Bi-County Blvd., Farmingdale, NY 11735

# VEHICLE GENERATORS AND REGULATORS

Radio-Electronics and its predecessor, Radio-Craft, have given me much pleasure for 50 years. Robert Grossblatt's articles have been favorites, but he fell off the track with his comment, "... (vehicle) generators and the regulators that control the current they produce are a really stupid charging system ..." (Drawing Board, Radio-Electronics, December 1991).

Low-cost, high-current silicon rectifiers that made the superior alternator available were not developed until after the transistor was invented in 1947. There happened to be a lot of high technology before that. Radio, TV, computers, and automobiles all pre-date the benefits brought by advanced solidstate devices. As I recall, submarines, Rolls Royce automobiles, and high-speed aircraft all used generators, and the electromechanical voltage regulators they required. I don't believe the word "stupid" characterizes that use.

I suspect the author was just trying to interject some lightness which is all right with me—but his description of the operation of the older voltage regulator is incorrect.

The generator's field current was modulated by a voltage-sensing relay that inserted various values of resistance in the field circuit, not the output lead. The varying field current would then cause the output voltage to remain at the desired value. The relay was also designed to sense the ambient temperature and change the generator-charging voltage accordingly. The voltage regulator case usually contained a current-limiting relay to protect the generator from over-load, and a reverse-current relay to prevent the battery from discharging through the generator windings when the engine was not running.

These latter two functions were

not needed in the alternator, but when they were first installed in new cars, there were no low-cost, high-current transistors developed that could operate at the high-temperatures in the engine compartment. So the same old electromechanical voltage regulator that had been used for 40 years was used again with the new alternator!

The rest of Mr. Grossblatt's article was well done and informative, as usual. I just didn't want to read your fine magazine for the next 50 years without contributing to its technical excellence!

GEORGE W. HAILS

Arlington Heights, IL

# **TESLA COIL IMPOSTORS**

I have been tempted several times in the past to write to various magazines after the appearance of certain articles on the construction of Tesla coils. Don Lancaster's comments on the Tesla coil (*Hardware Hacker*, **Radio-Electronics**, October 1991) finally pushed me to fire up the word processor.

I agree that many "Tesla" coils are essentially nothing more than glorified step-up transformers. The Tesla coil, however, is meant to generate its high-frequency high voltage by taking advantage of the special properties of the resonant (quarter wavelength) transmission line (also known, somewhat esoterically, as the Ferranti effect). It can be shown that the voltage amplitude V, at the unloaded end of an ideal (i.e., lossless, uniform, etc.) quarter wavelength transmission line driven by a source of resonant voltage of amplitude V<sub>S</sub>, and of impedance Zs at the resonant frequency (assumed real for notational simplicity) is  $V = (Z_O/Z_S)V_S$ , where Zo is the characteristic impedance of the line. This is different in numerous ways from the standard voltage multiplication of a transformer, as it should be; these are quite distinct physical phenomena.

Although the physics of the t former is pretty amazing, wh more impressive is that a wire more properly, a transmission may itself act as a "transforme great experiment that shows the construction of a mock t mission line using discrete conents to model (mock) distributed parameters of a transmission line.

In reality, a Tesla coil impospretty easy to spot. It will suffer a variety of maladies, some of v include improper magnetic cou (making it a transformer instead propagating transmission line) marked insensitivity to resonar quency tuning. Generally, ever most heinously constructed " coils" will generate hefty atter grabbing sparks, but they are missing the "magic and myster the physics of the resonant line makes it a true Tesla coil. MATTHEW KLEJWA Schaumburg, IL

### HERE'S TO HOW-TO ARTICL

I'm writing in response to Funk's letter (Radio-El tronics, April 1991) titled "I Hack Attack." It might be true t you add up all the component quired for a home-built comp system, the final price tag will c close to a dealer-bought sys However, there are quite a few ple in this world who cannot a to shell out over \$1000 at one but who can afford to do it piec piece. It's a lot easier to spend or \$50 at a time than it is to s \$1000.

And how can you put a pric your time when you are learning to build something as useful computer system? How must your time worth when you sit watch television?

Please keep publishing the how-to articles!

JOHN CULLIVAN

Niles, OH



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# **EQUIPMENT REPORTS**

# The Kelvin 100K Digital Multimeter

Most multimeters are ready to use right out of the boxbut not the Kelvin 100K.



f we were to tell you that this review is about an inexpensive multimeter, you'd probably be inclined to turn to the next page. After all, multimeters are as common today as silicon chips, and the features found on inexpensive ones have been around for years. So what can we tell you about the Kelvin 100K digital multimeter that you couldn't already guess? The answer is that it's available as a kit.

The Kelvin 100K (Kelvin Electronics, 7 Fairchild Ave., Plainview, NY 11803) comes with a PC board and all parts that mount on it, a case with a backstand (that's always handy), a pair of test leads, an owner's manual, an assembly manual, an extra fuse, and even a 9-volt battery, all for \$29.95. The 100K's features include a 31/2-digit LCD; DC ranges of 2, 20, 200, and 1000 volts; AC ranges of 200 and 500 volts; resistance ranges of 200 ohms, 2K, 20K, 200K, and 2 megohms; and DC current ranges of 2 mA, 20 mA, 200 mA, and 10 amps. There's no provision for measuring AC current.

The 100K also hosts a diode test, a low-battery indicator, and a battery test-a handy feature for a generalpurpose multimeter. In the "battery test" mode, the meter will display the voltage of any 1.5-volt battery under a 100-mA load or the voltage of any 9-volt battery under a 6-mA load.

It's likely that not too many experi-

enced kit builders will be interested in building the 100K, mainly because they almost certainly already own a multimeter. However, the 100K kit is perfect for any beginner in electronics or a child who's old enough to attempt soldering-especially a kid who's always playing with his dad's multimeter!

The assembly manual is particularly well-suited for a classroom environment, as it reads like an electronics lab manual; parts are installed a small group at a time, alternating with precautionary circuit checks, explanations of how each section of the circuit works. troubleshooting tips, and various quizzes on what has been covered so far.

Experienced kit builders may actually find the assembly manual somewhat irritating, because the sections in which components are installed are scattered throughout a lot of other explanatory paperwork. Remember though, that the kit is aimed at beginners. But this is where the kit's one flaw emerges: the assembly manual contains more than just a few typographical errors. A seasoned kit builder should be able to overcome these problems but they may be very confusing to the beginner. Let's go over the assembly manual and point out any problems we encountered.

The manual starts out with an introduction to the meter and a table listing all of its specifications. A schematic of the meter's circ and a parts list follows. Diagrar all of the parts are provided to you quickly identify everythin parts-placement diagram is ne: though the PC board silkscreened with all of the co nent designations as well. Als cluded are charts to help identify resistor values by their codes and capacitor values by numbering. Pinout diagrams provided, of the 31/2-digit LCD 7106 A/D converter, and the c XOR gate used in the meter. The brief discussion on proper sold techniques and the proper har of IC's. A list of all tools need build the meter is also given. C theory is the last thing to be co before the actual assembly c board begins.

In the first assembly proce certain resistors and capac must be soldered to the PC b and some might find this step fusing. You are instructed to i C14, 10 nF, and C16, 0.01 µFthe two capacitors are actuall same value. And the fact tha parts list shows capacitors C1. C16 to be "0.0 µF" only adds t

confusion.

Next you have to install the 4 7106 IC so that the A/D cin can be tested out, which als quires the temporary installati the battery clip, the LCD, an rotary knob. The LCD and kno guire a bit of sub-assembling b attaching them to the meter, ar some reason the sub-assemb structions are found much fa on in the manual. The assemt agram shows the back of the i knob as having six plastic tabs which you are to snap on six contact clips-but the knob came with our kit had seven After putting the clips on th outermost tabs, the A/D se seemed to work just fine.

For the voltage-reference c continued on pag

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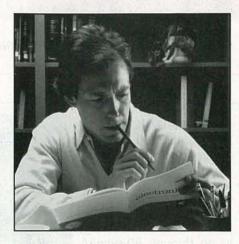
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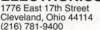
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gram with a twist, the Cartoon-A-Day Calendar Plus from Individual Software offers DOS and Windows users a daily dose of whimsical humor in the form of the farcical drawing of nationally syndicated "Inside Out" cartoonist Kevin Pope. The daily cartoon can be added to personal calendars, printed correspondence, daily todo lists, or schedules. The program displays (and

prints) personal schedule information by the day, week, month, or year, and even keeps track of vacation time, personal plans. travel time, and holidays. It can also be used to create or update to-do lists. Both versions feature digital and analog clocks; the Windows version also features time-saving "Quick Memo" and "Quick Fax" functions that generate a memo or fax cover sheet that incorporates the daily computer right from their computer. The DOS version runs on any IBM-compatible PC with DOS 3.3 or higher and 512K of memory. The Windows version requires Windows 3.0 software.

The Cartoon-A-Day Calendar Plus program (for DOS or Windows) costs \$29.95.—Individual Software, 5870 Stoneric Drive, #1, Pleasonton, 94588 Phor 1-800-822-3522

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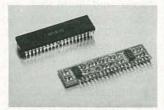
7128 Mirama Suite 15L, San Diego, CA mount devices. According to Huntron Instruments. the robotic probe can set up and test any kind of component on a printedcircuit board faster than using a conventional "bedof-nails" test system.

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The Prober RP388 costs \$23,000; the 5100DS system required to operate it starts at \$10,000.-Huntron Instruments Inc., 15720 Mill Creek Blvd., Mill Creek, WA 98012; Phone: 800-426-2965 206-743-3171: Fax: 206-743-1360.

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The VCS-1870 digital voice chip set costs \$16 in quantities of 1000.-Electech Electronics, 1262 East Katella Avenue, Anaheim, CA 92805; Phone: 714-385-1707: Fax: 714-385-1708.

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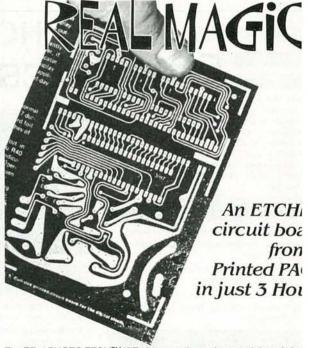
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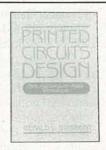
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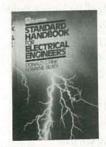


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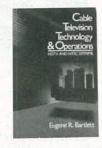


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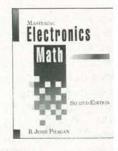
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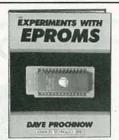


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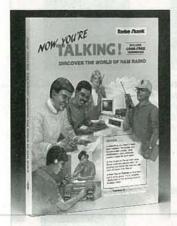
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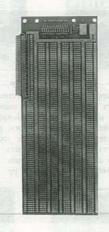
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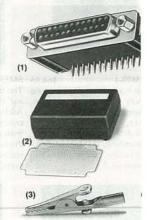
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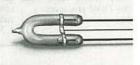
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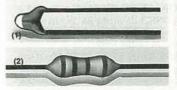


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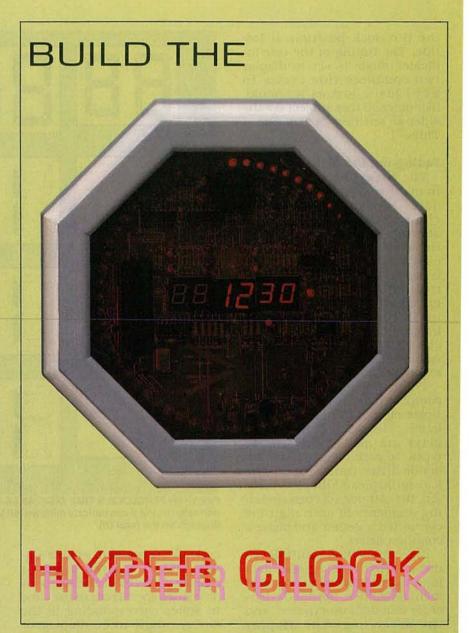
THE TECHNOLOGY TO PRODUCE low-cost digital clocks has existed for years. Unfortunately, the style in which these clocks have displayed the time has been mostly limited to four digits (representing hours and minutes). Few digital clocks, if any, have taken full advantage of the great capabilities of today's microprocessors to provide a more novel display . . . that is until the HyperClock.

The HyperClock has a custom-programmed microcontroller that generates all the signals necessary to display time in eight eye-catching (yet easily readable) modes. Among its features are the ability to simulate a sweep second hand with a ring of 60 LED's; it can graphically display the level of ocean tides; it has a "fading" display mode that causes the LED's to gradually change when updated; it has a hourly chime/ alarm output; supports 50- or 60-Hz powerline operation; it has a battery backup; and an intelligent date display that knows the last day of each month. Let's take a look at those features in greater depth.

The digital display

In four of the HyperClock's eight modes it can display time with a clever twist that those of you that grew up before the "digital-clock revolution" will appreciate. You may recall that it was fairly common for folks to speak of how many minutes it was till the next hour. For example, people would say "it's ten before five" rather than "it's four-fifty." Well, the HyperClock can actually "display" the time in that manner.

To help explain how that is done, take a look at Fig. 1-a; it shows the six seven-segment LED displays that are used to form the clock's digital display. During the first 30 minutes of each hour, the two middle digits signify the hour and the rightmost digits indicate minutes past the hour (like most digital clocks), and the two digits on the left are blank. Figure 1-b shows how eleven fourteen (or literally "fourteen after eleven") would look in this mode.



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LEON W. SCHMIDT

However, once the clock advances to beyond half-past the hour, the right digits go blank, the middle display would increment to display the next hour, and the left two digits would indicate how many minutes are left until that hour. For example, if it was thirteen minutes to twelve (or 11:47), the display would look like Fig. 1-c. You could read that literally as "thirteen before twelve."

On the hour, the clock just

displays the hour, so the left and right minute displays remain blank (see the display for 12 o'clock shown in Fig. 1-d).

As mentioned earlier, there are 60 LED's arranged in a circle to display seconds or an approximation of the current tide level in your locale. The LED's act as a light chaser sweeping through the seconds of a minute. They can also show the relative tide level by moving from the 12 o'clock position at high tide to

the 6 o'clock position at low tide. The timing of the tide-indicator mode is set to display two complete tide cycles in 24.51 hours just as it should. (For more on this subject see the sidebar entitled "A Bit About Tides.")

Fading-out the digits

The HyperClock also differs from other clocks in how it updates its display. In typical clocks, the display digits abruptly change as time passes. However, in four of HyperClock's eight modes when a digit must be updated, the LED segments representing its old value are dimmed as the segments for the new value become brighter. Likewise, each LED in the light chaser fades off rather than turns off. This animation is rather relaxing to watch.

These display effects are accomplished by a mixture of multiplexing and duty-cycle modulation. The seven-segment displays are all common-anode types, so each digit has its own anode-driver transistor. In typical multiplexed-display fashion, the cathodes of corresponding segments of each digit are connected together and share a

common driver.

Like any other multiplexed display when the segment data for a digit is placed on the segment data lines, the anode driver for that digit is activated, and the seven-segment display lights to exhibit the appropriate digit. All the other digits are off at this time. After a short period of time (1.83 ms) the segments are turned off via the segment lines and the anode driver is deactivated. The anode driver for the next digit is then activated, the segment data for that digit is placed on the segment lines, and the process continues until all the digits have been lit. Since the human eye is too slow to see the digits turn on and off, it appears as though they are all on simultaneously. Multiplexing the digits in this fashion reduces the number of pins on the microcontroller needed to control the LED displays.

HyperClock's fading effect is created by modulating the duty

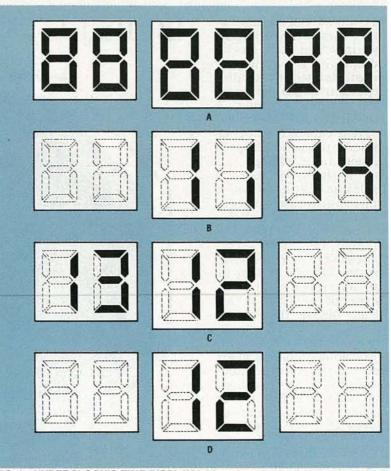


FIG. 1—HYPERCLOCK'S TIME DISPLAY (a) is unique in that it not only displays normally (b), but it can indicate minutes left to the next hour (c), and blanks the m displays on the hour (d).

cycle of the segment enable signals. When a seven-segment display is enabled, the segment data lines spend part of the time in states corresponding to the current digit to be displayed, and the rest of the time in states corresponding to the next or "future" digit that will be displayed. Each time the digit is enabled, the duty cycle will favor the future-digit data more and more, until only the new digit is displayed, and the process repeats each time the display must be updated.

### The microcontroller

At the heart of the HyperClock is an Intel 8749 microcontroller. It is programmed to perform a variety of functions, namely: display multiplexing, timekeeping, receiving switch input, coordinating the hour and alarm chime, and initiating a power-fail mode that permits the time-keeping functions to

continue while blanking display to conserve backup

tery power.

The 8749 has 2K of EPR 128 bytes of RAM, 24 I/O pii programmable 8-bit timer, an interrupt-control struct The custom-program place the processor to create Hy Clock's special effects ex sively exercises all of the c features; Fig. 2 contains a plified flow chart for the Hy Clock program. The progra shown divided into two tions: an interrupt routine a main loop.

The interrupt routin mainly responsible for tal the segment data from the ment-data buffer in the m controller and placing it or display-control lines in a m plexed fashion. The inter that initiates the routine co from the 8749's internal ti which has been programme execute the interrupt every

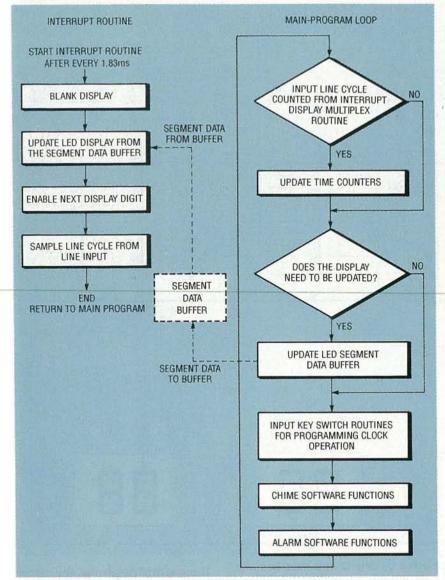


FIG. 2—HYPERCLOCK'S SOFTWARE can be broken down into two distinct code segments: a clock-scheduled interrupt routine, and a main-program loop.

ms. Using an interrupt-program segment in this way allows the display's fading effect to appear gradual because the process of updating the display occurs at regular intervals. This routine is also responsible for checking a powerline-frequency input on the microcontroller to determine if a powerline cycle has passed. If so, it informs the main loop of the program.

The main loop keeps track of the number of cycles that pass so it knows when to update the segment-data buffer or initiate the alarm or chime. If no powerline cycles are detected, the main loop assumes AC power has been terminated and puts the clock in power-fail mode. In that mode it shuts off the display and allows the microcontroller to "invisibly" keep track of time via a 6-MHz crystal. The main loop also processes input from the clock's switches (we'll talk more about that later).

For all that goes on inside the microcontroller, the functions assigned to its pins by the HyperClock program (see Fig. 3) are relatively easy to understand. Let's take them one group at a time.

The pins labeled A through G and DP (pins 12–19) in Fig. 3 are the outputs for the display-segment data. They indirectly control the cathode drivers for the multiplexed display. Similarly,

2	X1		
3	X2	A	12
4	RESET	В	13
5,26,40	+5 VOLTS	C	14
1	50/60	D	15
6	LINE	E	16
27	CIMI	F	17
28	SW1 8749 SW2	G	18
29	SW3	DP	19
30	SW4	DEO	21
31	1 man 11/2		22
32	SW5	DE1	23
33	SW6	DE2	24
34	SW7	DE3	35
7,20	CHIME	DE4	00
1,20	GROUND	0.0	

FIG. 3—THE PINS ON THE 8749 microcontroller are assigned various functions by the HyperClock program.

the outputs labeled DEO-DE4 (pins 21–24 and 35) control the anode drivers for the display via demultiplexer chips, which we'll discuss later.

The pins labeled \$1-\$7 (pins 27-34) are used as function-switch inputs. The switches connected to those inputs (DISPLAY MODE, DISPLAY DATE, DISPLAY ALARM, INCREMENT HOUR/MONTH/MODE, INCREMENT MINUTE/DAY, SNOOZE/TIDE ADVANCE, and ALARM TOGGLE, respectively) activate various chip functions by grounding those pins. A complete explanation of the switches' functions will be presented later.

Low-going pulses from the pin labeled CHIME (pin 34) activate the chime circuit, which is composed of discrete components. The microcontroller triggers the chime circuit with a 12.8-ms wide low-going pulse at one-second intervals. When not in alarm mode, the chime signals the hour by chiming an appropriate number of times, and signals each half-hour by chiming once.

When the microcontroller is in the "alarm" mode, the chime circuitry is used as an alarm annunciator. In this mode the clock does not chime on the hour and half hour. That permits you to use the HyperClock as an alarm clock without the chimes disturbing you until the appointed time.

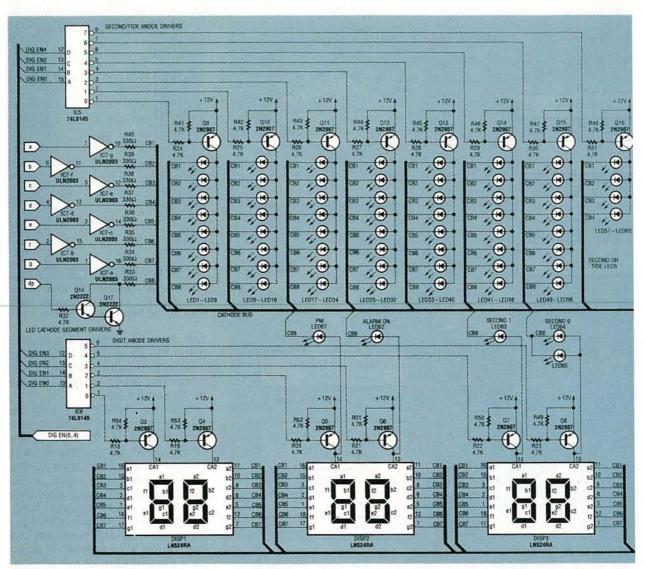


FIG. 4—THE HYPERCLOCK DISPLAY is controlled by only 13 data lines from the microcontroller.

The LINE input (pin 6) is used by the IC to accept a 50- or 60-Hz square wave. The square wave is used for time keeping and to detect AC-power failure as mentioned earlier. The 50Hz/60Hz input (pin 1), tells the 8749 what frequency to expect at the line input. If pin 6 is low, the 8749 assumes the line signal is at 60 Hz, but if that pin is high the 8749 prepares for 50-Hz operation.

As its name implies, the RESET input (pin 4) initializes the microcontroller. A low at that input will erase all modes and settings previously entered.

The x<sub>1</sub> and x<sub>2</sub> inputs (pins 2 and 3) need to be connected to the 6-MHz crystal, XTAL1, mentioned previously. Last, but cer-

tainly not least, are the 5-volt power inputs (pins 5, 26, and 40) and the grounds (pins 7 and 20). Those inputs of course, are self explanatory.

The display circuit

While the microcontroller does a great deal, the Hyper-Clock requires some additional circuitry to make it a complete timepiece. For example, the microcontroller cannot provide nearly enough current to drive the LED display. For that reason additional anode and cathode drivers were included in the design. They are shown along with the other display components in Fig. 4.

The control signals for the LED cathodes originate from

the A-G and DP pins of the micontroller. The A-G signals sent to a ULN2003 buffer/dr (IC7) which contains serbigh-current drivers. Each oput is capable of providing! mA of peak drive current. Si the ULN2003 contains o seven of the eight cathode ders required, a Darlington der was made out of two 2N2: transistors to drive the DP li

The DEO through DE4 outp generated by the mic controller are decoded by 74LS145 decoder/driver I (IC5 and IC6). Only one deco output is driven low at any ti Each 74LS145 output supp current to a 2N2907 drive tr sistor that sources current the anodes of a group of LE or a display digit.

Note that there are additic LED's to provide an AM/PM

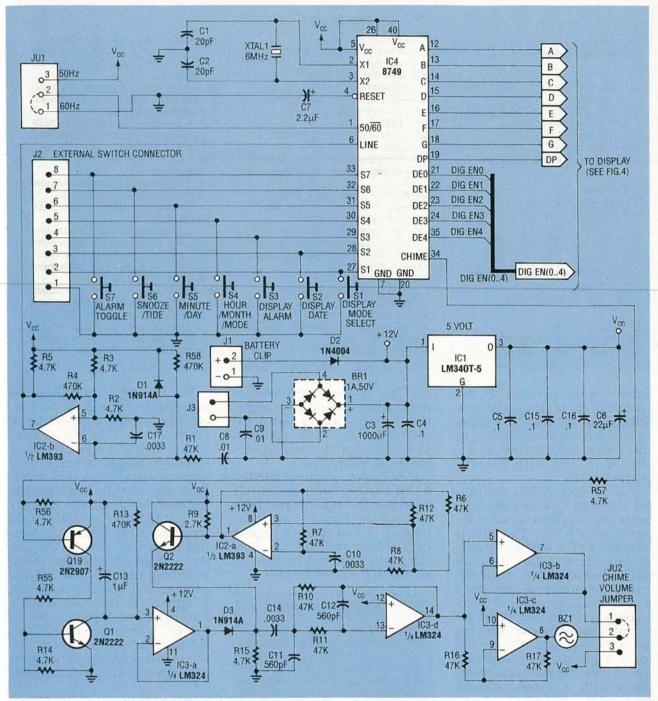


FIG. 5—THIS SCHEMATIC DIAGRAM FOR THE HYPERCLOCK circuit (less the display components) shows the support circuitry required by the microcontroller.

dication (LED61), tell you if the alarm-mode is active (LED62), and provide a winking second display (LED63 to LED65). That's all there is to the display circuit.

### The remainder

The most noteworthy of the clock's remaining circuitry (shown in Fig. 5) is the chime circuit. When the micro-

controller generates a low-going pulse on pin 34, it activates Q19. That transistor then provides sufficient current to drive Q1 into saturation.

With Q1 on, the negative side of C13 is effectively grounded, which causes it to charge. When Q1 is turned off, C13 discharges through a 470K resistor (R13). The resistor/capacitor combination has a time constant of

0.47 seconds. The exponentially decaying signal produced by the discharge is buffered through a unity-gain amplifier (IC3-a) to a 1N914 diode (D3).

The cathode of D3 is connected to the output of a 50% duty cycle 5-kHz square-wave oscillator consisting of IC2-a, R7, C10, and Q2. Transistor Q2 serves to provide a dynamic pull-up for that oscillator since the LM393 is an open-collector type comparator. The 5-kHz

# PARTS LIST

All resistors are ¼-watt, 5%, unless otherwise indicated.

R1, R6–R8, R10–R12, R16, R17— 47,000 ohms R2, R3, R5, R14, R15, R18–R32, R41–R57—4700 ohms R4, R13, R58—470,000 ohms R9—2700 ohms R33–R40—330 ohms, ½-watt, 5%

Capacitors

C1, C2—20 pF ceramic C3—1000  $\mu$ F, 16 volts, electrolytic C4, C5, C15, C16—0.1  $\mu$ F, ceramic C6—22  $\mu$ F, 16 volts, electrolytic C7—2.2  $\mu$ F, 16 volts, electrolytic C8, C9—0.01  $\mu$ F, ceramic C10, C14, C17—0.0033  $\mu$ F, ceramic C11, C12—560 pF, ceramic C13—1  $\mu$ F, 16 volts, tantalum

Semiconductors

IC1—LM340T-5 5-volt regulator IC2—LM393 dual-comparator IC3—LM324 quad-op-amp IC4—8749 microcontroller with Hyper-Clock program

IC5, IC6—74LS145 1-of-8 decoder/driver

IC7—ICLN2003 high-current driver

D1, D3—1N914A diode

D2-1N4001 diode

Q1, Q2, Q17, Q18—2N2222 NPN transistor

Q3-Q16, Q19-2N2907 PNP transistor BR1-1-amp, 50 volts PIV bridge rectifier

DISP1, DISP3—Panasonic LN524RA or similar 7-segment display (for the smaller digits)

DISP2—Panasonic LN526RA or similar 7-segment display (for the larger digit) LED1–LED65—light-emitting diodes

Other components

XTAL1—6-MHz crystal

T1—9-VAC 500-mA wall-mount

transformer

BZ1—piezo transducer

S1-S7-miniature momentary-contact

pushbutton switch

B1—9-volt battery

Miscellanious: T-220 style heatsink, PC board or perforated construction board, battery clip, shorting blocks, solder, etc.

Note: The following items are available from SkiTronix, P.O. 9685, Spokane, WA 99209:

 A pre-programmed HyperClock 8749 microcontroller with firmware license—\$10.00.

 An etched and drilled PC board—\$25.00.

 The foil pattern artwork suitable for conversion to film—\$3.00.

Software on floppy disk—\$5.00 postpaid

 A complete kit of parts including the PC board, programmed 8749 IC, LED's, displays, electronic components, and the wall-mount transformer—\$70.00.

A detailed drawing of the HyperClock wood case, will be supplied with all orders. Please include \$3.00 for shipping and handling. Washington residents must include an additional 7.9% sales tax.

square wave present at the emitter of Q2 is clamped in amplitude by the buffered exponential waveform from IC3-a, so the 5-kHz signal decays in amplitude in step with the discharge of C13.

The decaying 5-kHz signal is fed through C14 to a secondorder low-pass filter tuned to approximately 5 kHz. The filter is composed of a LM324 op-amp (IC3-d), C11, C12, C14, R10, and R11. It removes the high-frequency components contained in the decaying square wave to smooth it out. From there the signal is passed to two more opamps (IC3-b and IC3-c) that form a push-pull amplifier, which provides the piezo transducer with a 10-volt peak-topeak drive signal.

While the output signal is not exactly a pure sine wave, the audible result sounds pretty much like a small bell. If you feel the chime is too loud, you can eliminate half of the push-pull amplifier by jumpering one side of the transducer to the 5-volt supply, which is available via JU2.

The entire circuit receives power from a 9-VAC wall-mount transformer. The 9-VAC supply is fed to a full-wave bridge rectifier and filtered by C3 to act as an unregulated 12-volt DC supply. The 12-volt supply powers the display circuitry, op-amps, the comparators, and an LM340-5 (IC1) 5-volt regulator. The regulator in turn powers the 5-volt supply line.

If AC power is interrupted, a 9-volt battery connected to J1 sources current to the regulator to keep the HyperClock functioning. If you plan to unplug the clock for any length of time, the battery should be disconnected to conserve its life.

# A BIT ABOUT TIDES

Predicting the tides in any given locale is not a simple job. Tides are affected by many cyclic astronomical forces: the declination in the orbits of the moon and sun relative to a point on the Earth, and the local geography of the coast line in the area in which you live, to name a few. HyperClock predicts the tidal levels from the most predominate of these forces, the moon. The moon requires 29.53 days to orbit Earth, and that combined with the 24-hour solar day causes a high and low tide in every 12 hour and 25.5 minute interval. HyperClock tracks the moons primary affect on the tide. You can find out about the level of local tides in your area from your newspaper or library. The information can be used to initially set the tide indication on your HyperClock to a low or high point. From then on the graphic display will be an aid in the determination of the relative level of the tides in your locality.

The line input (pin 6) of t microcontroller cannot be di en directly from the 12-VAC w transformer. So the trar former signal is conditioned a Schmitt-trigger circuit to ge erate a suitable square wa First the signal's amplitude reduced by a voltage divic consisting of R1 and R58, a its positive excursions are li ited to about 5 volts by D1. T limited signal is then sent to t inverting input of the LM3 comparator. Positive feedba is applied to the comparate non-inverting input by R4 prevent it from generating fa signals. The comparator driv the microcontroller's line int with the resulting square wa

### Construction

In order to build a Hyp Clock, you'll need a prigrammed 8749 microcontrol. A preprogrammed and test microcontroller is availal from the supplier mentioned the parts list. The executal code to program an 8749 available from the RE-B. (516-293-2283, 1200/2408N1), as a file call HYPER.HEX. The file is suplied in Intel's Hex form which is directly compatil with most EPROM progra

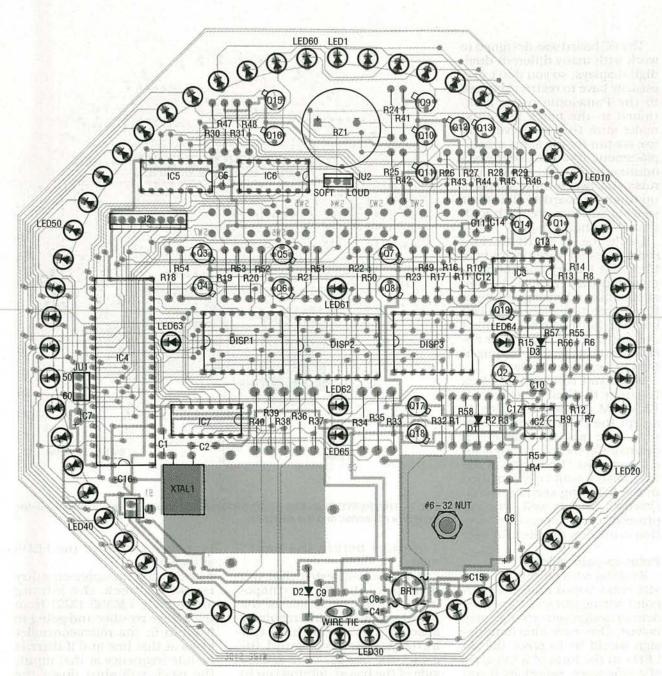


FIG. 6—DISPLAY-SIDE PARTS-PLACEMENT diagram can be used to locate most of the HyperClock's components.

mers. The software is also available on floppy disk from the source mentioned in the parts list.

A 6.5- × 6.5-inch octagonshaped PC board is also available from that supplier to help you assemble a HyperClock of your own. If you wish, you can make your own double-sided printed-circuit board from the foil patterns included in this article or using artwork from the supplier listed in the parts list. Of course, you could even use a point-to-point wiring technique, so we'll discuss that briefly later on.

Figures 6 and 7 show the parts-placement diagrams for the HyperClock (6 shows the display side and 7 shows the solder side) for those of you that will use a PC board. All components, except for the wall-mount transformer, are shown mounted on the circuit board. Note that the switches can be placed on either side of the board, depending on the cabinet you wish to place the clock in. There are some additional

connector pads on the board so you can run wires to the switches should your cabinet design require that they be located off the PC board. Figure 8 shows a completed HyperClock board.

The design readily lends itself to many different project cases. However, make sure that the cabinet you choose has some openings in the back to allow a little cool air to flow around the clock's 5-volt regulator and heat sink. If you like the case used for the prototype, you can build one out of a length of wood molding as the author did.

The PC board was designed to work with many different dual-digit displays, so you don't necessarily have to restrict yourself to the Panasonic units mentioned in the parts list. Just make sure that whatever you use is a pin-for-pin same-size replacement. If you do use the recommended units, be sure to raise the two minute displays up from the board so that their viewing surfaces are flush with that of the hour display.

Lastly, the PC board provides some holes for wire ties to hold the 9-volt battery and the wall-mount transformer leads. You should take advantage of them. Remember to install the 9-volt backup battery and connect JU1 and JU2 to select 50- or 60-Hz operation and the volume of the chime, respectively.

When you connect the clock to power it should come up at 12:30 AM and will be ready to accept the current time, alarm time, date, and the tide level if desired. If you run into any difficulty, you may find some of the troubleshooting tips provided in the following section useful. However, if all is well, you can proceed to the "operating" sec-

tion to prepare the clock for use.

Point-to-point wiring

Working with perforated construction board and point-to-point wiring gives you the freedom to design your own display layout. One nice alternate design would be to place the 60 LED's in the form of a full cycle of a sine wave, especially if you set the clock to display the tide level.

An early prototype of the clock was built using wire wrap. Regardless of the wiring technique, you should invest in a large enough piece of perforated construction board (at least  $6 \times 6$  inches) so that you can make your custom display with plenty of room to spare for all the support electronics.

Furthermore, when you are shopping for the hour and minute displays, select minute displays that are somehow distinctly different than the hour display. That will make the display more easily readable in the

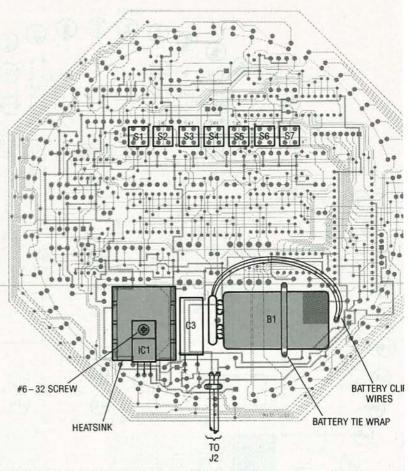


FIG. 7—THIS PARTS-PLACEMENT DIAGRAM should be used to position the regula battery, a capacitor, and the switches.

"minutes before the hour" mode.

It is also suggested that you don't place the display components on the same side of the board as the heatsink/regulator assembly, C3, and the 9-volt battery. Doing so would increase the profile of the display side of the board, forcing you to place the LED lens at an undesirable distance from the display components.

Aside from those suggestions, layout is not critical, so if you observe good construction and wiring techniques you should not have any problem getting the clock to function. However, if you should encounter some difficulty, the following

hints ought to help:

• If no LED's are illuminated when you apply power, first check the unregulated supply for a minimum of 10 volts DC. While only 2 to 3 volts of overhead are required to operate the 5-volt regulator, at least 10 volts

is required to drive the LE sufficiently.

• If the power-supply circui is okay, check the wiri around the LM393 (IC2) for the bridge rectifier and going IC4 pin 6; the microcontrol looks at that line and if there no line frequency at that inp the clock will shut down t LED drivers (as we explain earlier).

Since most of the wiring the clock runs between the L drivers and the LED's, it is lik that you could have made an ror in one or more of those co nections. If you observe that a active LED segments do r form numbers, then you show check the connections from I to IC7 and the correspondi connections to the cathodes the LED displays. A mistake tween IC4 to IC5 and IC6 v make the displayed digits at or seconds appear out of orc An error in wiring from the o puts of the 74LS145's to 1

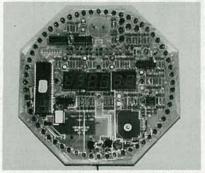
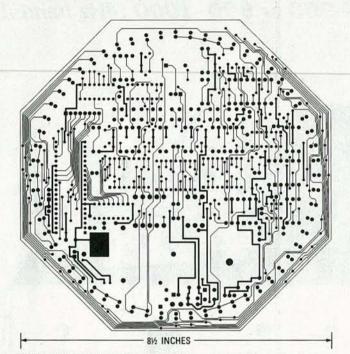


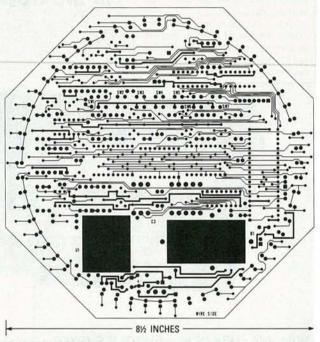
FIG. 8—A FINISHED HYPERCLOCK. The PC board makes assembly neat and straightforward.

### TABLE 1-MODES AND THEIR FEATURES

Facture		Mode						
Feature	0	1	2	3	4	5	6	7
Fading Updates		•		•		•		•
Plain Updates	•		•	100	•		•	
Before-The-Hour Display			•	•			•	•
Plain Display	•	•			•	•		
Tide Light Chaser					•	•	•	•
Seconds Light Chaser		•	•	•				



THE DISPLAY-SIDE FOIL PATTERN can be used to generate one side of the clock's PC board.



THIS FOIL PATTERN can be used to generate the solder side of the clock's PC board.

driver transistors, which connect to the LED anodes, will cause the same effect.

### Operation

The functions performed by S4 and S5 in the HyperClock depend on the state of the three display switches (S1 through S3). If none of the display switches are depressed, pressing S4 advances the current hour displayed and pressing S5 advances the minute display. That is how you set the time.

Pressing and holding down S1 (the Display-Mode button) causes the clock to display the number of the current operating mode, which can be altered by pressing S4 (S5 will do nothing). The various operating

modes and the features they support are listed in Table 1.

If you depress and hold switch S2 (the Display-Date button) the current month and day are displayed. With that switch depressed, the month and day can be advanced by pressing S4 and S5, respectively.

Activating switch S3 will cause the clock to display the time the alarm is set for. By pressing S3 along with S4 you can alter the hour setting, and by pressing S3 and S5 simultaneously you can change the minute setting.

Moving on to the last two switches, the Alarm Toggle switch (S7) determines the state of the alarm and the hour chime of the clock. For example, on power-up the hour chime is enabled and the alarm is disabled. If S7 is pressed once, the alarm is turned on and the hour chime is disabled. Depressing the switch again will turn off both the alarm and the hourly chime.

The Snooze/Tide Switch (S6) has a dual purpose. If the Hyper-Clock's alarm was armed and goes off, that button will silence the alarm for an additional ten minutes. You can forestall the alarm in this way as many times as you like. If the alarm is disabled, and the clock is in a mode that supports the tide-level display (modes 4 through 7), pressing S6 will advance the tide indication on the 60-LED display to set its position.

### WARNING!

Please note that unauthorized wire and electronic communications interception and interception of oral communications is illegal under Federal and State Law. In addition Federal Law renders illegal the intentional manufacturing, assembling, possessing, or selling any electronic, mechanical, or other device, knowing or having reason to know that the design of such device renders it primarily useful for the purpose of surreptitious interception or wire, oral, or electronic communications. Federal law imposes both civil and criminal penalties for violations of the applicable statutes. Thus, the use of the Scanner Converter described in this article is intended for and should be restricted to educational, scientific, and/or informational purposes. This is not intended to constitute legal advice and readers are advised to obtain independent advice as to the propriety of their use thereof based upon their individual circumstances and jurisdictions.

# SCANNER CONVERTE

Upgrade your scanner to receive signals in the 800–900 or 900–1000 MHz band



THE 800-1000 MHZ BAND OF FREquencies, lying in the portion of the radio spectrum known as the UHF band, has recently become populated with many signals of interest to the shortwave listener (SWL) and scanner hobbyist. Originally, the 800-890 MHz portion was allocated to UHF TV broadcasting. Lack of interest in these frequencies (formerly TV channels 70-83) and a pressing need for spectrum space was largely responsible for re-allocation. The portion of spectrum now includes business radio, public safety (police, fire, etc.) and general-purpose two-way radio. The lower portion is largely used by cellular mobile radio telephone services. The upper portion (above 900 MHz) is used for two-way radio, industrial radio, amateur radio, and miscellaneous purposes, such as wireless video and audio links, studio to transmitter (STL) links, and various Part 15 applications (low-power licensefree uses), and even more! Figure 1 summarizes the current frequency allocations.

The frequencies are almost in the microwave region. Until recently, receivers for this band were scarce and usually special-purpose types. In the past few years, a number of communications receivers have been made available, covering from around 25 MHz or so up to over 1000 MHz. Some of the more expensive scanners cover portions of

the 800-1000 MHz range, who thers block out the bands.

Now you can build a conver that will allow the reception signals from 800–1000 MHz any scanner that covers f quencies in the 400–500 M range. The availability of his performance transistors a Monolithic Microwave In grated Circuits (MMIC's), gether with very small compents such as chip capacity and prepackaged mixer asserblies, have made this feasible

The antenna shown in topening photograph is cut so cifically for the 800-MHz bar It's available from the Cellu Security Group, 4 Gerri Road, Gloucester, MA 0198 Contact them directly for inf

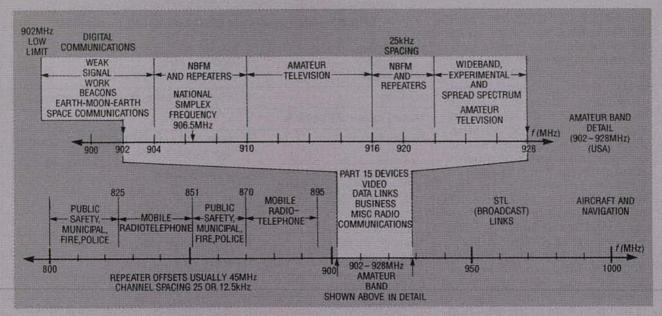


FIG. 1—THE 800–1000 MHZ UHF BAND has many signals of interest to the shortwave listener. Here is a summary of the current frequency allocations.

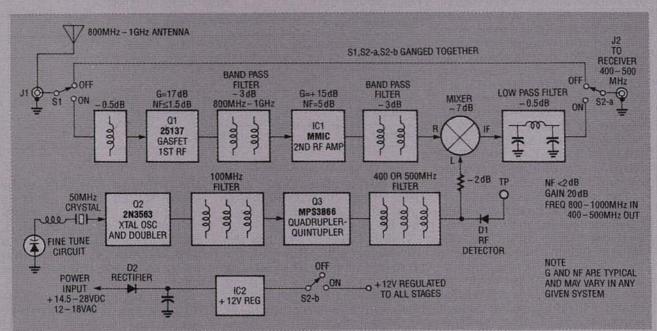


FIG. 2—BLOCK DIAGRAM. A GaASFET feeds a double-tuned filter and a MMIC RF amplifier that feeds a second double-tuned filter. That feeds a double balanced mixer, or DBM. The DBM is also fed with a local oscillator signal of either 400-MHz or 500-MHz.

mation on that and other various UHF antennas.

The converter described in this article offers excellent performance (about 0.15 μV/12dB SINAD—signal-to-noise-and-distortion-ratio—sensitivity for standard 5-kHz FM), having an NF (noise figure) of about 2 dB, a gain of 20–25 dB, and an output frequency of 400–500 MHz. By simple tuning adjustment it

can be set up for 800–900 or 900–1000 MHz ranges and optimized for any 30–40 MHz segment in the range. It will work well over the entire 100-MHz range if circuits are staggertuned, with only slightly reduced sensitivity. Applications of the converter are as follows:

1. Monitoring 800–900 or

1. Monitoring 800–900 of 900–1000 MHz ranges.

2. Amateur use for reception of

902–928 MHz band, downconverting to the 420–450 MHz range.

3. Reception of 902–928 MHz Amateur TV, using a standard TV receiver that covers UHF channels 20–23, and reception of wireless TV links operating in the 900-MHz range.

4. In conjunction with a 500-MHz counter, the measurement of frequencies in the 800-1000 MHz range.

Referring to the block diagram (Fig. 2), the converter uses a low-noise dual-gate

GaAsFET (gallium-arsenide field-effect transistor) as an RF preamplifier. That feeds a double-tuned filter and a second RF amplifier using a MMIC. The MMIC feeds a second doubletuned filter. The overall RF gain is about +27 to 30 dB and the bandwidth is around 30 MHz. That provides good rejection of out-of-band signals and helps minimize the feedthrough of unwanted signals in the 400-500 MHz range. The RF amplifier feeds a double balanced mixer, or DBM. The DBM is also fed with a local-oscillator signal of either 400-MHz (for 800-900 MHz conversion) or 500-MHz (for 900-1000 MHz conversion). The mixer output is therefore kept in the 400–500 MHz range covered by most scanners. The receiver should be suitable for the type of transmission to be received. A scanner is generally set to receive narrowband frequency modulation (NBFM) signals commonly used in this range in steps of 12.5 kHz, 25 kHz, etc. A TV receiver tuned to the lower UHF channels (14-23) can be used to receive TV signals in the 900-MHz range, such as amateur TV (ATV) and the new 900-MHz wireless video links. Converter output is at 50-75 ohms.

The local oscillator (LO) is a 50-MHz crystal-based overtone oscillator. The second harmonic of the oscillator circuit (at 100 MHz) is used. A fine-tuning control is provided to compensate for any 800-1000 MHz signals not fitting the popular 12.5-kHz channel spacing used by many scanners. The LO can be shifted at least  $\pm 6$  kHz to act as a fine-tuning control, if needed. Normally, the fine tuning is left set to center position.

The 100-MHz oscillator signal is fed to a multiplier stage using a UHF large-signal transistor as a quadrupler (×4) or a quintupler (×5) stage. The appropri-

ate harmonic (4th or 5th) is selected by a triple tuned filter and the signal at 400 or 500 MHz is delivered to the mixer. The filter can select either signal depending on the setting of three variable capacitors. A di-

ode detector samples the output

TABLE 1-800 TO 100-MHz CONVERTER SPECIFICATION

Freq Range RF Input IF Output	400-500 MHz 800-900 or 900-1000 MHz	
LO Freq	400 or 500 MHz, internally selectable	
Noise Figure <2dB typical		
Sensitivity	gives 0.15 $\mu$ /12dBSINAD, 5 kHz deviation with typical scanner	
Power Gain, RF to IF $f^{\rm IN}=900~{\it fout}=500~{\rm MHz}$ ${\rm R_S}={\rm R_L}=50~{\rm \Omega}$	+ 22 dB typical	
RF Bandwidth	40 MHz @ 3dB typical @ 900 MHz	
Maximum Input Level	-40 dbm @ 1dB compression	
Tuning Range	800-1000 MHz	
Dynamic Range	Approx 90 dB (0.1 μc to 3000 μv)	
Voltage and Current	+ 15-25 VDC @ 100mA, Neg ground or 12-16 VAC @ 300 mA peak, can be modified for + 12 VDC regulated	
Freq Control of L O	XTAL controlled .005%	
Fine Tuning Range	±7 kHz typical	
PC Board (finished) size	3½" × 5" × 1" high	
RF to IF Feedthrough Isolation (IN-OUT) DB	>60 dB @ 400 MHz	
Insertion Loss in dB with converter off	- 1dB typical @ 400 MHz - 0.3 dB typical @ 30 MHz	
Switching	Built-in	

of the filter so that a VOM can be used to align the filter simply by "peaking" the trimmer capacitors for maximum output.

It is possible to just use the 400-MHz signal. However, for reception of 900–1000 MHz, a receiver capable of tuning 500–600 MHz would be needed. Most scanners cover only up to 512 MHz or thereabouts. Therefore, the 500-MHz signal is necessary with these scanners for reception of frequencies over 912 MHz.

The converter board contains a switching network for switching the converter in or out. In the "out" position, the input jack, J1, simply connects to the output jack, J2, and all frequencies from DC to 550 MHz are passed. In this position, the DC line to the converter circuitry is also opened, thus disabling the converter.

The converter board also contains a rectifier and a regulator

that delivers + 12 volts DC to converter circuitry. Eithe + 14.5- to + 24-volt DC, or volt AC supply can be us Suitable supplies are eithe wall transformer or one the mounts inside the convercase.

Referring to Fig. 3, let's over a detailed description the circuit. Signals enter from the antenna and : routed to S1, a DPDT swi with only one side used. With in the "off" position (conver off), signals from S1 are rou to S2-a, another DPDT swit (Slide switches S1 and S2, though mounted at different cations on the PC board, mechanically linked by an ac ator rod assembly, so that a rect switching is maintaine Next, signals are rout through S2-a to low-pass fi L16-C15, and then to J2. low-pass filter rejects sign above 600 MHz. A 50-ohm

### PARTS LIST

All resistors are 1/4-watt, 5%, unless otherwise noted.

R1—100,000 ohms, 1/8-watt R2—470,000 ohms, 1/8-watt

R3-180 ohms, 1/8-watt

R4-180 ohms

R5-390 ohms, 1/8-watt

R6-1000 ohms

R7—10,000 ohms, trimmer potentiometer with shaft

R8-10,000 ohms

R9-15,000 ohms

R10-3900 ohms

R11-330 ohms

R12-100 ohms

R13-15,000 ohms

R14-2200 ohms

R15-10 ohms, 1/a-watt

R16-47 ohms

R17—1 megohm

R18-15 ohms, 1/8-watt

R19-390 ohms, 1/8-watt

R20-10 ohms

Capacitors

C1, C8, C9, C13, C14-1-5 pF

trimmer

C2-C7, C10-C12, C16, C28, C31-

100 pF, 50 volts, chip

C15-5.6 pF NPO ± 0.25 pF

C17-100 pF NPO, 5%

C18-39 pF NPO, 5%

C19-22 pF NPO, 5%

C20-2.2 pF NPO, ± 0.25 pF

C21, C29—470 pF ±20%, disc C22, C30, C32, C35, C36—0.01

μF, 50 volts, GMV disc

C23-33 pF NPO ±5%

C24—56 pF NPO ±5%

C25-C27-2-10 pF trimmer

C33—10 µF/16 volts, electrolytic

C34-470 µF/25 volts, electrolytic

Semiconductors

IC1—MAR-1 UHF amplifier

IC2—7812 + 12-volt regulator

D1—MV2107 varactor diode

D2-HP5082-2800 hot carrier

diode

D3-1N4007 rectifier diode

Q1—25137 dual-gate GaAsFET

Q2—2N3563 VHF NPN transistor

Q3—MPS3866 VHF NPN transistor

LED1—green light-emitting diode

LED2—red light-emitting diode (optional)

Inductors

L1-L5, L10-L12-part of PC-board etching

L6, L15-ferrite bead

L7-0.2-0.32 μH (9½ turns #22 enameled wire)

L8-0.05-0.1 μH (3½ turns #22 enameled wire)

L9—0.05–0.1  $\mu \dot{H}$  (3½ turns #22 enameled wire)

L13-1.0 µH RF choke

L14-ferrite bead on R20

L16—½-turn #22 enameled wire, ¼
-inch diameter (see text)

Other components

J1, J2—female BNC connector MOD1—MCL SBL-IX mixer module S1, S2—DPDT PC-mount slide switch

XTAL1-50-MHz 3rd overtone

crystal

Miscellaneous: PC board, small-diameter 50-ohm coaxial cable, project case, 14.5–24-volt DC or 12-volt AC 350-mA transformer (see text), hardware as required, brass rod or wire, 21/4-inch rubber grommets, line cord if required, solder, etc.

Note: The following items are available from North Country Radio, PO Box 53, Wykagyl Station, New Rochelle, NY 10804:

 Converter kit including all parts except case and transformer —\$67.50 + \$3.50 S&H
 PC board only—

• PC board \$13.50 + \$3.50 S&H

• Transformer—\$9.50 + \$3.50 S&H

New York State residents must add appropriate sales tax.

pedance level is maintained through the converter in the "off" position to reduce VSWR (voltage standing-wave ratio) and line losses, so that a scanner connected to J2 has normal reception when the converter is switched off. Switch S2-b breaks the 12-volt supply line in this position to disable the converter circuitry.

In the converter "on" posi-

tion, signals from J1 in the 800–1000 MHz range are fed through S1 to L1 (an inductor that is incorporated in the PC board etching and acts as a short circuit to lower-frequency signals) and C1, which are resonant at 900 MHz.

For matching purposes, at 900 MHz, C1 and L1 must form a resonant circuit as well as an impedance transformer to step

up the 50-ohm impedance to somewhere between 800 and 1000 ohms. The input impedance of the gate of RF amplifier Q1 is about 1 to 2K or higher, and shunted by about 1 pF capacitance. The output impedance of Q1 is between 1000 and 2000 ohms with 0.5–1 pF shunt capacitance. The voltage gain of Q1 is about 7.5 from gate 1 to drain, or about 17.5 dB.

There is about 1.5 dB loss in the output-coupling network and about 0.5 dB loss in L1, so that a total of about 15 dB gain is observed. The device is rated at 1.1 dB noise figure, but allowing 1 dB (approximate) loss in L1 and S1, an actual NF of about 2 dB will be obtained. That is adequate since cable losses in the typical antenna system will be around 6 dB anyway.

Transistor Q1 is a dual-gate gallium arsenide field effect transistor (GaAsFET) biased to about 5–10 mA drain current; R3 provides a self bias for Q1. Chip capacitors C4 and C5 are RF-bypass capacitors soldered directly to the solder side of the PC board for low inductance. They are the only type of capacitor that provides reliable bypassing at 900 MHz. Resistors R1 and R2 bias gate 2 of Q1.

The drain of Q1 feeds doubletuned filter C8-L2 and C9-L3, and R4 feeds bias to the drain of Q1. Typically, the tuned circuits in this RF amplifier are tuned to 900 MHz with about 2.5 pF capacitance, and L1-L5 have an equivalent inductance of 0.012 microhenry, although these values are typical and cannot really be isolated or measured. Inductors L2 and L3 are printed on the PC board and are proportioned to give the desired coupling and inductance. Their layout is critical and cannot be changed.

The signal from L3 is coupled through chip-capacitor C10 to IC1, a monolithic microwave IC (MMIC) amplifier with 50-ohm input and output. Resistor R5 provides about 17 mA operating bias for IC1, which gives about 13 to 15 dB gain at 900 MHz. The output of IC1 is coupled via C12 to filter L4-C13 and L5-C14. The five tuned circuits in this

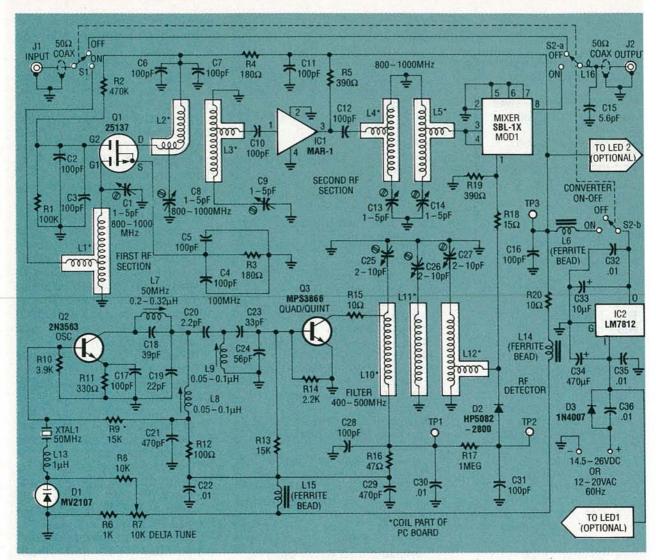


FIG. 3—CONVERTER SCHEMATIC. A 50-ohm impedance level is maintained through the converter with S1 in the "off" position so that a scanner connected to J2 still has normal reception. Switch S2-b breaks the 12-volt supply line in this position to disable the converter circuitry.

converter yield an overall RF bandwidth of 40 MHz at the 3 dB points. The signal from L5, about 28 to 30 dB stronger than the signal at J1, is applied to a mixer module (MOD1), an MCL SBL-IX, where it is mixed with the LO signal at 400–500 MHz. The IF output is then fed to S2-a, where it is connected to J2 via low-pass filter L16-C15.

An LO signal of either 400 or 500 MHz is required by mixer MOD1. It is generated as follows: Q2, a 2N3563, is configured as an overtone crystal oscillator. Emitter stabilization is provided by R11, and R9-R10 provide base bias. Resistor R12 supplies the collector voltage for

Q2 through L7 and L8. Components L7 and C18 are nominally tuned to 50 MHz, the frequency of XTAL1. Components C19 and L8 form a resonant circuit at 100 MHz and therefore have a low impedance to 50-MHz signals. Bypass capacitor C21 RF grounds the bottom (cold end) of L8.

There exists a feedback capacitance (about 3 pF) between the collector and emitter of Q2. That, in conjunction with C17, forms an oscillator; the oscillation of Q2 would tend to take place at the resonant frequency of C18 (plus strays) and L7 (L7 is variable by means of a ferrite slug). The base of Q2 must be

RF grounded, which can or occur at the series-resonant fi quency of XTAL1, L13, ai varactor-diode D1; D1 acts as capacitor whose value can varied via the applied DC vo age from potentiometer R7. F sistor R6 limits the lowe voltage to about 1 volt, and 1 provides RF isolation for I Varying R7 has the effect varying the effective frequen of the crystal plus and min 1000 Hz. When L7 is nomina tuned to 50 MHz, the crystal ( cillator circuit produces a sigr of 50.000 MHz. However, need 100 MHz.

Since Q2 operates as class and produces harmonics, file L8-C19 is tuned to 100 MF That transfers 2nd harmon energy (6–10 dB below the fu damental 50 MHz) via coupli capacitor C20 to a second 10 MHz tuned circuit (C23, C24, and L9). Capacitors C23 and C24 are chosen so as to match the oscillator to the base of frequency multiplier Q3, an MPS3866. That generates harmonics of 100 MHz in the base circuit of Q3. Capacitor C24 is chosen to have a low impedance at higher frequencies to encourage the flow of harmonic currents in the base circuit of Q3.

Inductors L10, L11, and L12 form a filter tuned to either 400 or 500 MHz by adjustment of C25, C26, and C27. There is sufficient tuning range to cover either 400 or 500 MHz. The filter is triple-tuned and L10, L11, L12, and their coupling coefficients are determined by the PC board layout which they are part of. RF energy at 400 (or 500) MHz is taken from a tap on L12 and fed to mixer MOD1.

Without the right test equipment, it would be difficult to align C25, C26 and C27. However, the problem is solved by diode detector D2, C31, and R17. Resistor R17 slightly forward biases D2 to produce about +0.2V at test point TP2.

When RF drive is applied from L12, a negative voltage is produced at TP2. When the tripletuned filter is correctly-tuned and Q3 is operating properly, about -0.3 volts is produced by D2, since about 300 millivolts of RF is present from L12. This, when added to the +0.2V bias on D2, produces -0.1V at TP2. Diode D2 is forward-biased to improve its sensitivity at low RF levels. Tuning of C25, C26, and C27 simply consists of monitoring the DC voltage at TP2, and obtaining the most negative voltage possible by peaking C25, C26, and C27.

Regulator IC2, a 7812, provides 12-volts DC power to the circuit; C32 and C33 and C34, C35 help stabilize IC2. Rectifier D3 acts as a protection device in case a negative DC voltage is applied to the circuit, and C36 reduces 60-Hz buzz caused by switching transients in D3. At least 14-volts DC is required across C34 for IC2 to function.

When we continue next time, we'll build the converter and show you how to align it. R-E

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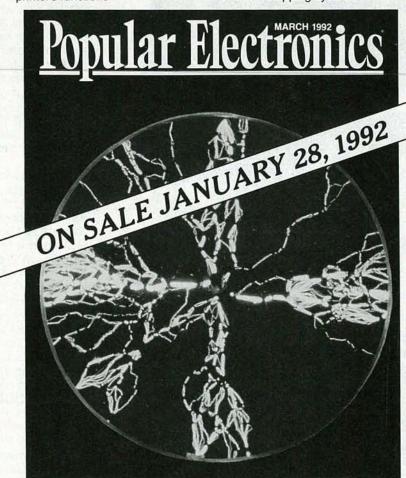
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Will new standards b

AM TRIES FO

us who pay little attention to AM radio that the oldest of all broadcast services is due for some uprading. After all, the FM radio service has been the preferred form of radio broadcasting in this country for at least two decades, now, and even FM radio may some day be obsoleted by digital audio broadcasting, or DAB. In fact, more than a dozen proposals for DAB are currently either on the drawit boards or have been demonstrated in prototype So why bother with AM radio at this late date?

### The AM stereo debacle

Back in the mid-1980's, the Federal Communic tions Commission considered several systems AM stereo broadcasting. Many AM broadcasters f then that the reason for the decline of AM rac audience was the fact that FM could offer ster whereas AM could not. Initially, the FCC select one of some six systems, the Magnavox proposal, a "standard." Faced with all sorts of threats of litig tion by other proponents, the FCC reversed its shortly thereafter and in effect, said, "let the m ketplace decide." Since then, the field of prop nents has narrowed down to two-the Motorola Quam system (by far the most popular) and t Kahn-Hazeltine system. Many experts mainta that by not coming down in favor of a specific sy tem, the FCC has discouraged both manufacture of receivers and AM radio broadcasters from mo ing to stereo.

With AM broadcasting audience on the decli for many years, manufacturers of high quality A FM tuners and receivers have paid little attention the AM circuitry that they incorporate in their pro

ucts. Figure 1 shows the actual frequency is sponse measured for the AM section of highly reputed AM/FM stereo receiver. No wo der listeners accustomed to playing digit compact discs and FM radios are "turned oby this kind of AM reception! This "after thought" approach by receiver manufacture further exacerbated the problem. Anoth problem of AM has been adjacent channel iterference—a problem that is particularly itense during evening listening. Many professionals blame the FCC for that problem well, maintaining that the granting of broad cast licenses by the FCC has been a poof administered "pork barrel" affair with lit



ply with the new standard.

The second part of the NRSC standard deals with harmonic distortion. It states that receivers designed to satisfy the standard shall not exhibit more than two percent (2.0%) total harmonic distortion plus noise (THD + N) at all measured frequencies between 50 Hz and 7500 Hz. Two percent distortion may sound like a high number to those of us accustomed to the distortion levels of modern audio amplifiers and FM tuners. but, in fact, many current nonconforming AM tuners exhibit far higher distortion levels than that!-particularly at higher audio frequencies.

A third recommendation of the standard involves the incorporation of circuitry into AM receivers that attenuates 10.0kHz adjacent-channel carrier frequencies by 30 dB, or 20 dB when the measurements are made with preemphasis characteristics inserted at the AM input of the RF test signal generator. To clarify that last point, we should note that in recent times, recognizing that AM radios had very poor highfrequency response, broadcasters began boosting the audio treble response of their transmission chains in an attempt to overcome the high frequency attenuation present in nearly all AM radios and tuners. Unfortunately, no two stations used the same boost of preemphasis characteristic. Furthermore, an overly extreme use of high-frequency preemphasis made the problems of interference between adjacent channels even worse. So, included in the NRSC-1 recommendation is a fixed preemphasis characteristic that AM radio broadcasters are required to use. The preemphasis characteristic. not unlike the one used by FM broadcasters in the U.S., is shown in Fig. 2.

Assuming that broadcasters conform (and as of this writing, well over half the AM broadcasters in the United States have embraced NRSC-1 standards), manufacturers of AM radios are expected to voluntarily incorporate standard, fixed

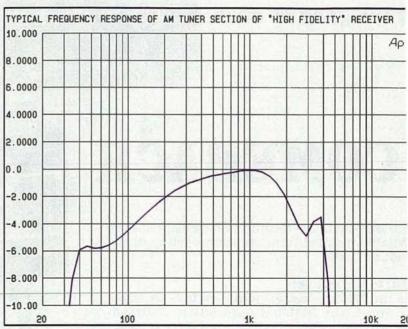


FIG. 1—AMPLITUDE VERSUS FREQUENCY. This is the response of the AM tu section of a "hi-fi" AM/FM stereo receiver!

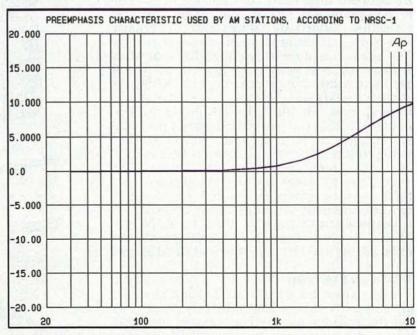


FIG. 2—BY STANDARDIZING THE PREEMPHASIS CHARACTERISTIC used by broadcasters, AM receiver manufacturers are able to incorporate standard deephasis networks in their products to achieve the desired flat response to 7.5 kHz better.

deemphasis networks. In measuring the frequency response of an AM radio conforming to the new standards, a laboratory would expect to obtain a frequency response such as that shown by the dashed line in Fig. 3. The solid lines represent the allowable deviation or tolerance over the range from 50 Hz to 7.5

kHz. Results shown in Fig. presuppose that the approp ate preemphasis network is stalled between the audio gen ator and the amplitude modu tion input terminals of the signal generator. If such a p emphasis network is not us in the test, results should be shown in Fig. 4.

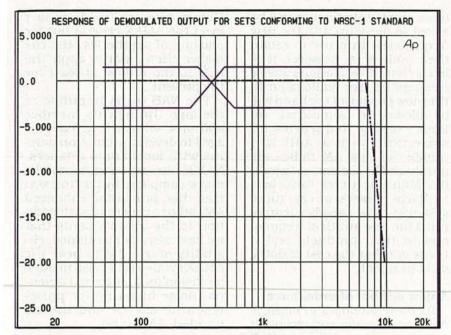


FIG. 3—FREQUENCY RESPONSE of AM circuitry that is required to conform to the NRSC-1 standard. The dashed line represents an ideal response, with the solid lines representing the tolerance limits. (Presumes preemphasis in the RF test generator.)

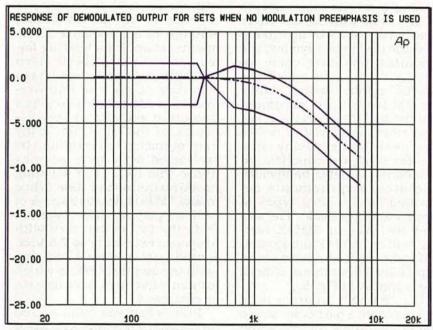


FIG. 4—FREQUENCY RESPONSE of AM circuitry that is required to conform to NRSC-1, with no preemphasis in the RF test generator.



FIG. 5—AMAX LOGOS will identify AM radios that meet the NRSC requirements.

NRSC-2 by 1994

During the interim period from June 1990 to June 1994. the FCC is going to presume that if a station conforms to NRSC-1, it is also in compliance with NRSC-2. The chief reason for the delay is the lack of appropriate, inexpensive test equipment needed to confirm compliance with all the provisions of NRSC-2. Those provisions mandate that. NRSC-2 deals primarily with attenuation of carrier emissions rather than indirectly with audio response and performance. According to the NRSC-2 rules, emissions between 10.2 kHz and 20 kHz removed from the carrier's fundamental RF frequency must be attenuated at least 25 dB below the unmodulated carrier level. Emissions between 20 kHz and 30 kHz away from the carrier frequency must be attenuated by at least 35 dB below the unmodulated carrier level. Emissions that are between 30 kHz and 60 kHz away from the carrier frequency must be attenuated by at least 5 + 1dB/kHz below the unmdodulated carrier level. (For example, emissions that are 50 kHz away from the carrier frequency would have to be attenuated by 5+50, or 55 dB relative to the level of the unmodulated carrier). Finally, emissions between 60 kHz and 75 kHz must be attenuated by at least 65 dB.

More breathing room

While the NRSC-1 and NRSC-2 provisions will certainly help alleviate some of the problems of interference between stations, it cannot do the whole job in view of the congestion of the AM band that now exists in some geographical areas. Accordingly, as of July 1, 1991, the FCC officially expanded the AM band by an additional 100 kHz. The band now extends from 535 kHz to 1705 kHz.

This additional spectrum space is expected to accommodate at least 200 AM stations, nationally. Rather than increase the number of licenses to broadcasters, however, it is expected that those stations causing the

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most severe interference will be asked to move up into the new frequencies. In order to retain their audiences, however, it is likely that those stations whose frequencies are reallocated to this new portion of the band will be allowed to "simulcast" on their existing frequencies for some time until a sufficient number of new AM radios are purchased by the listening public. Manufacturers (and particularly makers of car audio systems) have already incorporated the new swath of frequencies in their products and it turns out that the cost of doing so is minimal.

A new symbol of excellence

As these attempts to improve AM transmission and reception were being formulated, the NAB and the EIA came up with the idea that it would be nice to have some visible means of identification displayed on radios that meet the requirements of the new standards. After nearly two years of agonizing over the design of a symbol, the organizations have come up with a decal to be called the "AMAX" symbol, which stands for "AM Radio at its maximum potential." The certification logo could be affixed to radios that meet basic eligibility criteria including the equalization standards, variable bandwidth and other requirements described earlier. Two types of logos will be available. The second one, reading "AMAX Stereo," will be applied to improved AM radios that also have stereo capability. Illustrations of both logos appear in Fig. 5.

The "AMAX" program does not mandate a particular stereo AM format—only that the radio be capable of receiving and decoding some kind of AM stereo transmission. Of course, the decision to market AMAX certified radios is at the discretion of individual manufacturers, as is the decision to apply the "AMAX" or "AMAX Stereo" logo to the sets themselves. Interestingly, we recently learned that the latest Delco/Bose car audio radios, as installed in some 1992 model General Motors automobiles, do in fa meet the AMAX criteria but 1 reasons of aesthetics, the c maker elected not to apply t logo to the radios, at least f

the present.

The NAB plans to publici the logo through its memb stations, who will be encou aged to develop promotional to ins with local audio retailer NAB is also expected to unveil major campaign by the time ve read this, promoting enhance AM radio to consumers. In add tion to the improvements th we have already mentioned, e gibility of a radio to bear tl AMAX symbol must also include provision for an external ante na, noise blanking for puls type interference and the e panded AM band.

Will improvements help?

While both the EIA and th NAB are enthusiastic abou these attempts to improve All the question that remains whether or not AM can attra enough of an audience to r main a major broadcasting fc mat in the years ahead. Eve though it is still uncertai whether or not the improv ments in AM broadcasting ar reception will attract new li teners to the band, the mar improvements are certain to 1 welcomed with open arms t those who have been listenir to AM for quite some time. Whi many AM broadcasters speak a "level playing field" (again FM), the fact is that even wit response extending to 7.5 kH sound quality cannot compawith the quality of FM, to which so many listeners have becon accustomed.

Still, when you hear an A broadcast that has extende frequency response of this kinit's amazing how good it do sound when compared with th "typical" AM radio sound v have endured for many year Perhaps AM radio can be given new lease on life-even if it only a temporary reprieve un digital audio broadastin (which some now prefer to ca digital audio radio, or DAR) r places both of our currer modes of radio.

### MICHAEL A. LASHANSKY

to our professional-quality 2.5-MHz function generator and frequency counter that can read up to 150 MHz. This month we'll show you how to build, test, and properly use this essential test instrument.

### Construction

The function generator circuitry is mounted on three PC boards; the mother board, daughter board, and LED display board. The PC boards are available from the source mentioned in the parts list. Foil patterns are provided here if you wish to make your own boards, however the artwork was designed for nonplated holes. In places where it is impossible to solder both sides of a component, such as in the switch arrays, vias are provided for wire connections from one side of the board to the other. If you do make your own board, you'll have to solder some wires from the top of the switch arrays to points on the board. That is not necessary if you use the boards supplied with the kit.

Figures 6 and 7 show internal photographs of the author's prototype. Solder all diodes and resistors first, followed by the capacitors and then the IC's. IC sockets are not required, but they may make life a lot easier in

the event of trouble.

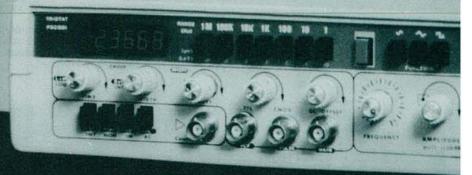
It's best to build and test functional blocks as you go rather than building the whole unit all at once. First, start by constructing all the cable assemblies as indicted in Fig. 8. Start with the power-supply section, and verify that the output voltages are correct. The AC power cord routes through a strain relief in the back panel, and one side is soldered to the top of switch S15 (pole a). The other AC lead is soldered to the pad connected to fuse F1.

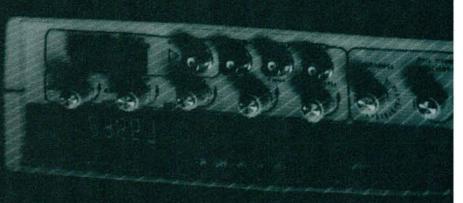
Next, build the triangle and square-wave generator sections. Those sections consist of components with the 1XX and 2XX component numbering scheme. A parts placement diagram of those sections, located

## SWEEP/FUNCTION

## GENERATOR

Let's build our benchtop function generator and frequency counter!

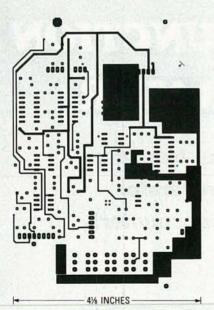




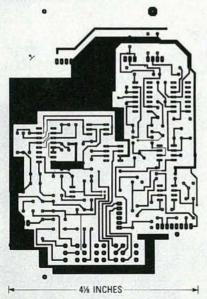
on the main board, is shown in Fig. 9. You will need an oscilloscope to verify that a triangle wave of about two volts peak-to-peak is present at the gate of Q5, and a one-volt peak-to-peak square wave is present at the collector of Q6. If those two waveforms are not present, go back and check your solder joints and component orientations.

Potentiometers R125 and R126 set the symmetry of the waveform and should be adjusted to give a triangle wave with equal slopes. R129 sets the upper frequency limit and

should be adjusted to give your desired high frequency for a given range. That is done with the course frequency-adjust potentiometer \$101 in its maximum position. As a general guide, set R129 for a maximum frequency of 2.5 MHz, with the 1-MHz range switch engaged. Potentiometer R223 sets the zero balance of the triangle wave and is adjusted to give a centered signal. Square-wave balance is achieved through potentiometers R224 and R225. You can now check the pulse output for TTL levels and a variable CMOS level. With the basic gen-



COMPONENT SIDE DAUGHTER BOARD foil pattern.

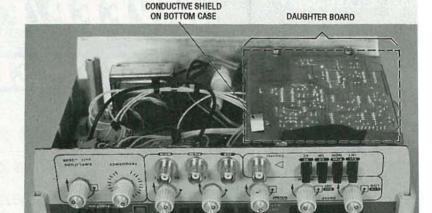


SOLDER SIDE DAUGHTER BOARD foil pattern.

erator now functioning, build the sine-shaper circuit (component numbers 3XX) and verify a sine wave at the output of IC9.

Adjust R323 for a two-volt peak-to-peak sine-wave output at IC9 pin 12. The amplitude of the square wave is controlled by R324, which should be set to give a clean square wave without any overshoot or rounding on the edges.

The output amplifier should be built next. That section uses the 4XX numbering scheme. Set to R423 to its center posi-



COPPER TAB CONTACTS

FUNCTION FREQUENCY
SWITCHES RANGE SWITCHES

FIG. 6—INSIDE VIEW OF the author's prototype. A transparent red acrylic sheet w used for the front panel. A copper tab is soldered to the ground plane of the daugh board and contacts a 9½ by 3½-inch conductive shield, which is glued to the inside the bottom case (not shown).

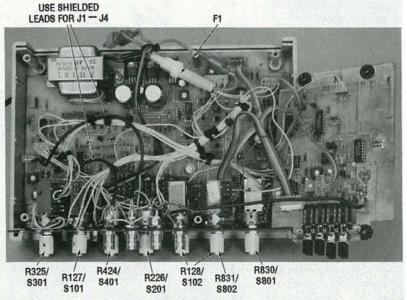


FIG. 7—INTERNAL PHOTO OF the author's prototype. Start construction by connecting all cable assemblies to switch-potentiometers mounted on the front pan

tion and adjust it only if there is no output. Next, put your oscilloscope on DC coupling and observe the DC level of the output, adjust R422 until the output waveform is centered around zero. Verify the open-circuit signal swing of 20 volts peak-to-peak and the -20-dB attenuator switch.

The last work on the mother board is to build the frequencycounting section and to mount the display board. The six display LED's are soldered to the display board, which is connected to the motherboard b 90-degree, 14-pin strip head With the display and components in place, observe the coplay. Select the MHz range a make sure that all the digits functioning. If not, go back a double check the circuit. Us frequency counter or scope calibrate the counter by adjuing C504 so that the disponential reading is the correct frequence selected.

The daughter board, whi holds the counter input amplier and sweep generator is

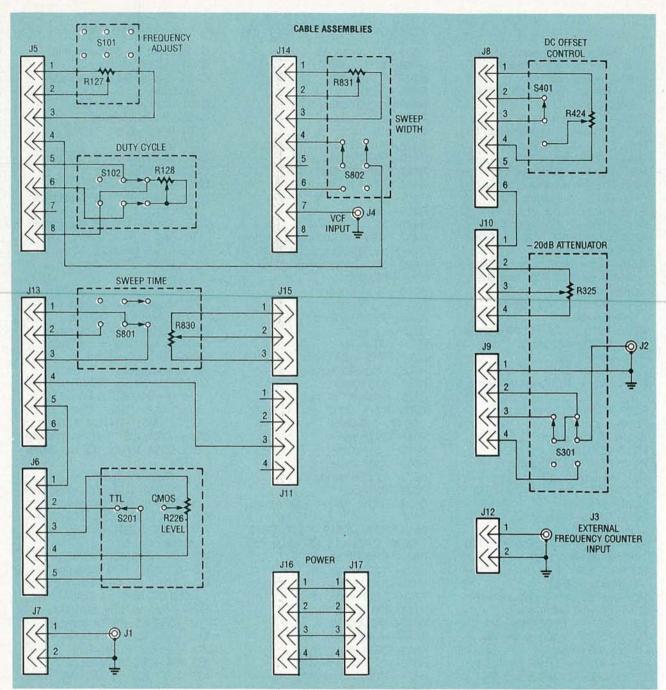


FIG. 8—CABLE ASSEMBLIES show the potentiometers that are connected to each of the function switches.

sembled next. That parts-placement diagram is shown in Fig. 10. The frequency-counter input circuit must be tested with an external signal or by selecting the external-signal source function and jumping the generator output to the counter input. Testing consists of verifying the operation of the switches, S11–S14 and the input amplifier.

The input amplifier can be tested by varying the amplitude

of an input signal from about 25 millivolts to 50 volts peak-to-peak (if no test signal is available, use the generator itself) and observing the frequency reading on the display. The frequency should remain the same for all amplitude conditions. When selecting the prescale function, the display should shift two decimal places to the right if working correctly.

All the boards were designed to use transistors with an emit-

ter-collector-base pin arrangement, and the rectangular pads are configured to accept that. If you choose to use the alternate transistors indicated in the parts list, they are American made, and use an emitter-basecollector pin arrangement. When the substitutes are used, a small circular pad is placed between the emitter and collector of the rectangular pads. This circular pad is used for the base pin and the collectors and emitters remain connected to the rectangular pads.

### **PARTS LIST**

All resistors are 1/4-watt, 5% un-
less otherwise indicated.
R101—2700 ohms, 1%
R102, R104, R105, R109, R111-
100,000 ohms, 1%
R106-33,200 ohms, 1%
R107, R108, R110-1000 ohms, 1%
R112, R114-3010 ohms, 1%
R113-49,900 ohms, 1%
R115, R120-4990 ohms, 1%
R116, R121-7150 ohms, 1%
R116, R121—7150 ohms, 1% R117, R122—348 ohms, 1%
R118, R123—75,000 ohms, 1%
R119, R124—750,000 ohms, 1% R125, R126, R826, R827—10,000
R125, R126, R826, R827—10,000
ohms, potentiometer
R127, R128-5000 ohms, potenti-
ometer (part of S101 and S102,
respectively)
R129, R825—20,000 ohms,
potentiometer
R201, R210, R220-10,000 ohms
R202, R222—470 ohms
R203—390 ohms
R204, R206, R219-1000 ohms
R205, R216, R217-2700 ohms,
1%
R207, R208-4020 ohms, 1%
R209—511 ohms
R209—511 ohms R211—30,000 ohms
R212-2000 ohms
R213, R214—13,000 ohms
R215—910 ohms, 1%
R218—7500 ohms
R221—47 ohms
R223, R828—5000 ohms,
potentiometer
R224, R225, R228, R229-2000
ohms, potentiometer
R226—10,000 ohms, potentiome-
ter (part of S201)
R227-4700 ohms, potentiometer
R301—49,900 ohms, 1%
R302, R303—11,300 ohms, 1% R304, R306—12,100 ohms, 1%
R304, R306—12,100 ohms, 1%
R305—309 ohms, 1%
R307—200 ohms, 1%
R308, R309—24,900 ohms, 1%
R310—127 ohms, 1%
R311—63.4 ohms, 1%
R312, R313, R320—1000 ohms
R314—5100 ohms
R315—680 ohms
R316—150 ohms
R317—6800 ohms
R318, R319—10,500 ohms, 1%
R321—2000 ohms
R322—12 ohms
R323, R324—1000 ohms,
potentiometer
R325—5000 ohms, potentiometer
(part of S301)
R401, R402, R503, R504—10,000
ohms

R403, R404-22,000 ohms

```
R405-170 ohms, 1%
R406-12.000 ohms
R407-1200 ohms
R408-2000
R409-18,200 ohms 1%
R410-270 ohms, 1%
R411-100 ohms, 1%
R412, R414, R502-3000 ohms
R413-24,3000 ohms, 1%
R415, R418-47 ohms, 1W
R416, R417-7.5 ohms
R419-50 ohms, 1/2W
R420-499 ohms, 1/2W
R421-56.2 ohms, 1%
R422, R424-10,000 ohms, poten-
 tiometer (R424 is part of S401)
R423-200 ohms, potentiometer
R501-100,000
R505-10 megohms
R701-10,000 ohms
R702-100,000 ohms
R703-1 megohm
R704-50 ohms
R705, R718-150 ohms
R706, R712-220 ohms
R707-470 ohms
R708, R715-51 ohms
R709-R711, R713, R714, R716,
 R717-510 ohms
R719-36 ohms
R720-1000 ohms
R801-7500 ohms, 1%
R802-33,000 ohms, 1%
R803-33 ohms, 1%
R804, R805, R807-5100 ohms,
R806, R810, R816, R817, R819,
  R820, R822-10,000 ohms, 1%
R808-510,000 ohms, 1%
R809-2200 ohms, 1%
R811-22,000 ohms, 1%
R812-2400 ohms, 1%
R813-100 ohms, 1%
R815-150,000 ohms, 1%
R818-15,500 ohms, 1%
R821-2000 ohms, 1%
R823-15,000 ohms, 1%
R824-18,000 ohms, 1%
R830, R831-5000 ohms, potenti-
  ometer (part of S801 and S802.
  respectively)
Capacitors
C101, C102, C204, C205-0.1 µF
  ceramic
C103, C203-100 pF, ceramic
C104-0.001 µF, Mylar
C105-0.01 µF, Mylar
C106-0.1 µF, Mylar
C107-1 µF, Mylar
C108, C504-15-60 pF, variable
  capacitor
C201-68 pF, ceramic
C202-0.047 µF, ceramic
```

C301, C303-0.1 µF, ceramic

C302, C304, C502-39 pF, ceramic

```
C305, C401-4.7 pF, ceramic
C307-15 pF, ceramic
C308, C408-5-35 pF, variable
 capacitor
C402-120 pF, ceramic
C403-2.2 pF, ceramic
C404, C406-6.8 µF, tantalum,
 20 volts
C405, C407-0.047 µF, ceramic
C501-33 pF, ceramic
C503-10 pF, ceramic
C601, C602-1000 µF, electrolytic
 50 volts
C603, C604-100 µF, electrolytic
 50 volts
C605-1 µF, tantalum, 20 volts
C701, C704-C706-0.1 µF,
 ceramic
C702, C707-100 pF, ceramic
C703 10u tantalum 16 volts C801-
 22 µF, tantalum, 16 volts
C802, C803-220 pF, ceramic
C804, C805-100 pF, ceramic
C806-500 pF, ceramic
Semiconductors
D101-D108.
                 D201-D204
  D206-D226, D301-D312
  D315-D318, D401, D402, D701
  D702, D801-1N4148 diode
D205-1N751, 5.1-volt Zener diode
D313, D314-1N746, 3.3-volt Zener
  diode
BR1-W02M bridge diode
Q1, Q4, Q12, Q13, Q21-2SC1815
  or MPSA05 NPN transistor
Q2, Q3, Q6, Q7, Q11, Q19, Q20-
  2SA1015 or 2N4403 PNP
 transistor
Q5, Q17-2N4416, N-channel FET
Q8-2N3904, NPN transistor
Q9, Q10, Q14-2SC1923 or
  MPSH34, NPN transistor
Q15-2N2219, NPN transistor
Q16-2N2905, PNP transistor
Q18-PN5139, PNP transistor
IC1, IC2—LM741, op-amp
IC3, IC4—LM308, op-amp
IC5, IC6, IC20-CA3086, NPN
  transistor IC (Harris)
IC7-7420, dual 4-input AND gate
IC8-4011, quad NAND gate
IC9-CA3030, op-amp
IC10-4066, CMOS quad bilateral
IC11-7216B, frequency counter
  and LED driver (Intersil)
IC12-7815, +15-volt voltage
  regulator
IC13-7805, +5-volt voltage
  regulator
IC14-7915. - 15-volt voltage
  regulator
IC15-MC10116, ECL triple-line re-
  ceiver with Schmitt trigger
  (Motorola)
```

IC16—SP8629, prescaler (Plessy) IC17—LM324, quad op-amp IC18—MC1458, dual op-amp IC19—CA3140, op-amp (Harris) SR801—1000 ohms, thermistor DISP1—DISP6—common-cathode LED (FND357)

Other components

S1-S7-4PDT-D switch

S8—DPDT switch

S9-S11-DPDT-D switch

S12-S14-DPDT-I switch

S15-DPDT on/off switch

S101—DTDP switch used with

R127 (5K potentiometer)

S102—DTDP switch used with R128 (5K potentiometer)

S201-SPDT switch used with

R226 (10K potentiometer)

S301-DPDT switch used with

R325 (5K potentiometer) S401—SPDT switch used with

R424 (10K potentiometer)

S801—DPDT switch used with R830 (5K potentiometer)

S802—DPDT switch used with R831 (5K potentiometer)

J1-J4-BNC connector

J5, J14—8-position female/male, 0.1-inch centers

J6—5-position female/male, 0.1inch centers

J7, J12—2-position female/male

J8, J13—6-position female/male J9-J11, J15, J16—4-position

female/male, 0.1-inch centers

XTAL1—10-MHz AT/CUT crystal T1—115/40 volts AC, 0.5-amp

transformer F1—0.5-amp fuse

Miscellaneous:Case (CTP-1 by Global Specialties), three 1.75inch standoffs, four 2-inch standoffs, two T0-5 heatsinks, three T0-220 heatsinks, three PC boards, internal wiring, fuseholder, 3-conductor 18gauge power-supply cord, and strain relief.

Note: The following items are available from Tristat Electronics, Inc., 66A Brockington Cres., Nepean, Ontario, Canada, K2G 5L1, (613) 228-7223:

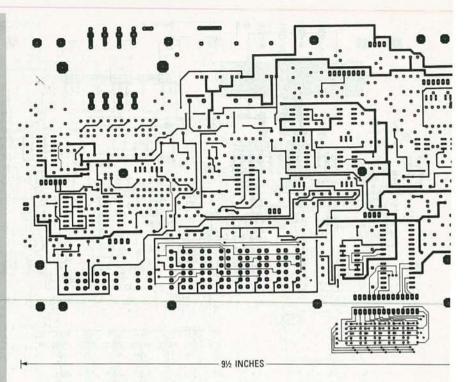
A set of three etched and drilled PC boards—\$76.

 All components without the PC board and case—\$250.

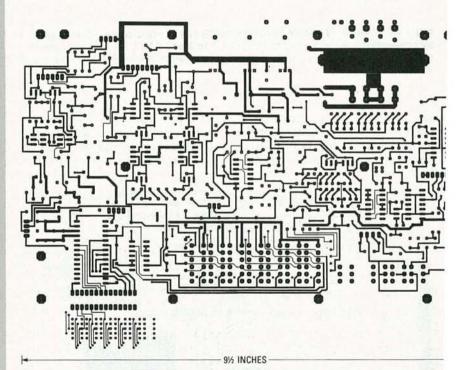
Complete kit of all parts (unfinished front panel)—\$300.

 Cut and silk-screened front panel—\$10.

Add \$17 for shipping and handling. Send check or money order only.



COMPONENT SIDE FOIL pattern of the mother board.

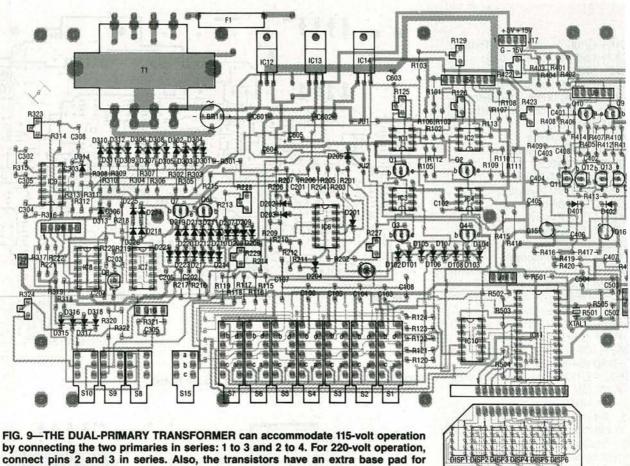


SOLDER SIDE FOIL PATTERN of the mother board.

The sweep generator is built next. If you're using the boards supplied with the kit, mount potentiometers R825–R828 to the solder side of the board. That will make adjustments easier when the unit is assembled. If you're making your

own boards, place the potentiometers on the component side and make your adjustments before the board is connected to the mother board.

Once again you'll need an oscilloscope to verify proper alignment. Set R828 to its midpoint,



connect pins 2 and 3 in series. Also, the transistors have an extra bar different packages.

and adjust R825 to give a good log output (when selected) and a linear output. Adjust R826 to achieve a good input signal to

IC19 pin 2 and R827 will set the maximum sweep width. If a scope is not available, most potentiometers can be set to their

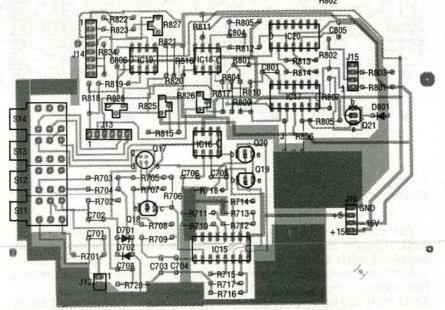


FIG. 10—PARTS PLACEMENT OF DAUGHTER BOARD holds the input amplifier and sweep generator circuit.

center position and adjuments can be made by obse ing the LED display with t counter set to the interncount mode.

If everything is working pro erly, you can install the co pleted boards into the case. T top of the case uses four 2-in standoffs. The front and ba panels supplied with the ca are of 0.065-inch aluminu and are not recommended 1 use as a front panel. A comple cut and silk-screened panel available from the source me tioned in the parts list, or y can make your own using trar parent red acrylic. Secure t mother board in place (top h of case) and finally install t daughter board uses three 15 inch standoffs. You're no ready to power up and use yo combination function gene ator and frequency counter.

### Using your unit

Table 1 shows a complete li

### TABLE 1—FUNCTION GENERATOR SPECIFICATIONS

FUNCTION	MIN	MAX	UNITS
Sine Wave	0.1	2.5 Mega	Hz
Triangle Wave	0.1	2.5 Mega	Hz
Square Wave	0.1	2.5 Mega	Hz
Pulse	0.1	2.5 Mega	Hz
Ampitude	are time		
Main Output	3.0	20	Vp-p
- 20dB	0.5	6	Vp-p
TTL Pulse	50	5	Vp
CMOS Pulse	0.5	15	Vp
Duty Cycle	10	90	%
DC Offset	-10	+10	VDC
Sweep Generator			
Sweep Width	1	1000	X Initial Freq.
Sweep Time		20	Seconds
Frequency Counter	the mit		Coociido
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	The Book		100 300
Input Sensitivity	20	100	Vp-p
Input Range	0.1	150 Mega	Hz
Input Impedance	50	1 Mega	Ohms
Gates Times	.01	10	Seconds
Error	±LSD		W. III SHAW
Stability	50ppm/°C		

of functions and specifications of the unit.

The square wave output is in phase with the sine wave and the triangle wave, but is 180 degrees out phase with the TTL and CMOS pulse outputs. That feature is useful for creating a two-phase clocking system if you happen to be working with digital equipment. The unit is calibrated to give a frequency range of 0.1 Hz to 2.5 MHz. The upper frequency limit can be extended by adjusting variable capacitor C108 and/or R129. With the component values that we have given, the upper frequency limit can reach as high as 4 MHz.

Changing the values of the timing resistors R115-R119 and R120-R124 will produce output frequencies as determined by the formula 1/RC. That method will achieve a maximum sinewave output of 10 MHz with an amplitude of 1 volt peak-to-peak above 2 MHz.

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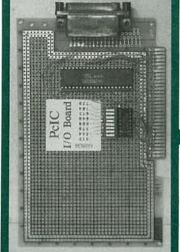
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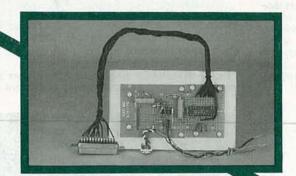
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# EXPERIMENTING WITH ADC FOR



# ADC FOR YOUR PC



JAMES J. BARBARELLO

# Add a variety of analog inputs to the PC-based analog-to-digital convertor.

PC-BASED TEST INSTRUMENTATION has turned out to be a popular topic among readers. We continue this ongoing series by interfacing new sensing devices (a linear displacement transducer, a piezoelectric transducer, and a microphone) to the analog-to-digital converter (ADC) discussed in the January 1992 issue. If you're just getting started with this series, here's a brief review of progress thus far.

### Quick review

The heart of the system is a PC I/O expander called the PC IO that adds 24 lines of digital I/O by means of an 8255 Parallel Input/Output (PIO), all on a single 8-bit expansion card. In the January 1992 installment, we added an outboard analog-todigital converter (ADC), based on an ADC0804. The ADC allows you to measure and capture any 0-5 volt analog signal (e.g., temperature, displace-ment, and audio). The circuit includes a variable-gain amplifier for low-level inputs, and a DC-offset adjustment for inputs with unwanted DC components. A temperature probe shown in that article was built around the base-collector junction of a silicon transistor. With the proper settings for amplification and DC offset, a several-hundred millivolt change over a 100°reeC temperature range produced a digital output spread over the full input range of the ADC0804.

In general, an A/D converter and a PC can provide very low-cost solutions to measurement problems that would ordinarily require costly test equipment. Following are some ideas, practical circuits, and software for interfacing other types of devices. These ideas cover the three most common types of sensing: mechanical, electrical, and acoustic.

### Mechanical sensing

As an example of mechanical sensing, the author and a friend were contracted to measure the displacement, impact force, and velocity of electromechanical rappers used in the pollution-control industry. Factory smokestacks have environmental controls that contain huge, electrostatically

charged metal plates. As the smoke goes up the smokestack, it passes by those plates; the plates "pull" the suspended par-ticles to them, removing pollu-tion that would otherwise be released to the outside air. Particles accumulate on the plates, and eventually have to be removed. To "clean" the plates, rappers (like giant solenoids) provide quick, hard jolts to the plates, breaking trapped particles free in huge sheets that fall to the bottom of the smokestack. Our task was to determine the characteristics of existing commercial rappers, and then determine whether our customer's rapper could be

Our test instrumentation consisted of an 8-bit A/D converter hooked up to a computer, and fed by a rectilinear potenti-

made better than the competi-



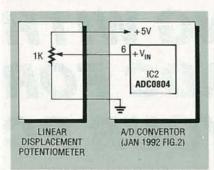


FIG. 1—INTERFACE A LINEAR displacement transducer to the PC IO as shown here. The wiper of the LDT drives the ADC0804 directly, so remember to disconnect the op-amp output (pin 7) from the ADC's input. (The original circuit was shown in Fig. 2 in the January 1992 installment.)

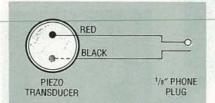


FIG. 2—INTERFACE A PIEZOELECTRIC transducer as shown here. Make sure the red lead goes to the tip and the black lead to the ring of the plug. Also, to avoid feeding DC voltage into the transducer, disconnect the J1 end of R1.

ometer (also called a linear displacement transducer, or LDT). LDT's are precision potentiometers that move linearly, rather than circularly. Even at surplus prices, LDT's aren't cheap (\$20-\$50), but they do a great job. Figure 2 in the January 1992 issue shows the complete ADC circuit; we simply supplied it with the input shown here in Fig. 1. Note that we power the LDT directly with a 5-volt DC supply, so neither amplification nor DC offset were required. Instead, we drive the ADC0804 (IC2) directly, as shown in the figure.

If you use this type of arrangement, be sure to disconnect the op-amp's output (pin 7) from the ADC's input (pin 6). In addition, make sure the potentiometer has a resistance of at least 1K, so as not to draw too much current from your PC's power supply. Also, the mechanical linkage between the LDT and the rapper must be firm so there is little or no slippage at the speeds encountered. Otherwise, the potentiometer will not

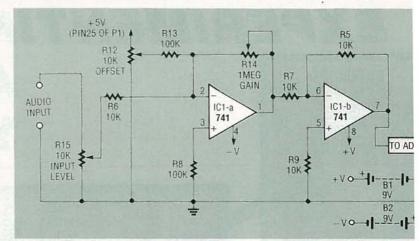


FIG. 3—INTERFACE AN AUDIO SOURCE as shown here. The nonsequential numbers occur to keep numbering consistent with the original circuit.

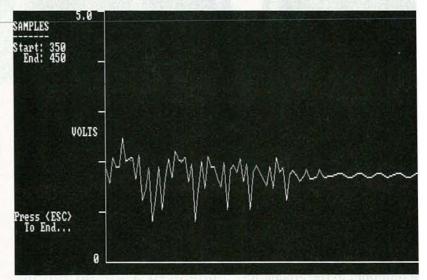


FIG. 4—GRAPHICAL OUTPUT from GRAFDATA.BAS (Listing 2), which allows yo display as many as 1000 data points captured by ADC.BAS (Listing 1).

give a true indication of displacement. This type of setup would also be useful for measuring the movement of solenoids, pistons, cams, and similar devices.

Using that circuit, we obtained a series of outputs that showed exactly how the rapper's plunger moved a quarter of a second after it triggered. Eight bits of digital data made it easy to calculate the rate of change of displacement (velocity), as well as the maximum displacement. We determined impact force using strain gages.

The only problem we had was in determining just when to read the LDT's resistance. The solution turned out to be straightforward, as we'll see momentarily.

### **Electrical sensing**

The temperature probe veloped last time is one exam of electrical sensing. Anoth good sensing device is pie electric material, available both film and crystal form. inexpensive source of pie electric crystal is Radio Shac Piezo Transducer (273-07 Simply break open the plas case, and you have a circu piezoelectric transducer w red and black leads. When fl ed in any way, the transdu produces a voltage that var proportionally to the amoun flexing.

A piezo transducer can used to measure force of pact, or the amount of bend and flexing. Figure 2 shows h to connect a piezo transduce

### LISTING 1

```
REM***
 2 REM** ADC.BAS - V910803 - JJ Barbarello *
 3 REM** Capture/Store Analog Data with PcA/D-MATE
 4 REM****
                                                                    X: DIM A(1000): GOSUB 370: LOCATE 1,
 20 PRINT "PCA/D DATA COLLECTION SYSTEM": LOCATE 2, 1: PRINT STRINGS(79, 220)
30 LOCATE 5, 1: PRINT SPACES(79); : LOCATE 5, 10
40 LINE INPUT "Enter Time (0-3600 seconds) between samples...";
  intervals
 50 interval = VAL(interval$)
60 IF interval < 0 OR interval > 3600 THEN BEEP: GOTO 30
70 LOCATE 7, 10: PRINT "Press <Enter> to begin, or <Esc> to
80 GOSUB 350: IF A$ = CHR$(27) THEN CLOSE : END
90 LOCATE 5, 10: PRINT SPACE$(60): LOCATE 7, 10: PRINT SPACE$(60)
100 LOCATE 10, 22: PRINT "DIGITAL DATA (0-255):": LOCATE 12, 19
110 IF interval > 0 THEN PRINT "SECONDS BETWEEN SAMPLES: "; interval
120 LOCATE 13, 29: PRINT "SAMPLE NUMBER: "
130 LOCATE 16, 20: PRINT "Press <Esc> to End Sampling...";
140 acount = 1: xsample = 1
150 told = VAL(MIDS(TIMES - 4
 140 acount = 1: xsample = 1
150 told = VAL(MID$(TIME$, 4, 2)) * 60 + VAL(RIGHT$(TIME$, 2))
160 IF interval = 0 THEN GOTO 210
170 T = VAL(MID$(TIME$, 4, 2)) * 60 + VAL(RIGHT$(TIME$, 2))
180 IF T = 0 AND (told - T > interval) THEN told = told - 3600
190 IF INKEY$ = CHR$(27) THEN GOTO 260
200 IF T - told > 0 THEN told = told + interval ELSE GOTO 170
210 CUT ADD + 2, 0: OUT ADD + 2, 1
220 x = INP(ADD): LOCATE 10, 44: PRINT USING "###"; x
230 LOCATE 13, 44: PRINT xsample; : xsample = xsample + 1
240 IF acount < 1001 THEN A(acount) = x: acount = acount + 1
250 IF INKEY$ <> CHR$(27) THEN GOTO 160
260 BEEF: LOCATE 16, 15
  260 BEEP: LOCATE 16, 15
270 PRINT "Press <Enter> to save data, <Esc> for no save...";
280 GOSUB 350: IP ASC(AS) = 27 THEN CLS : END
  290 LOCATE 16, 15
300 LINE INPUT "Enter File Name To Save Data (ex: TEST01.ADD)..."; f$
310 OPEN "r", 1, f$, 2: FIELD 1, 2 AS d1S
320 LOCATE 18, 20: PRINT "Saving Data...";
330 FOR i = 1 TO account: LSET d1$ = MKI$(A(i)): PUT 1, LOF(1) / 2 +
   1: NEXT
   340 PRINT "Done. Press ANY key."; : A$ = INPUT$(1): CLOSE : CLS :
   END
   END
350 A$ = INKEY$: IF A$ = "" THEN GOTO 350
360 IF ASC(A$) = 13 OR ASC(A$) = 27 THEN RETURN ELSE BEEP: GOTO 350
370 OPEN "R", 1, "HWADDRES.DAT", 4: FIELD 1, 4 AS A$
380 GET 1, 1: ADD = VAL(A$): CLOSE: DEF SEG = 64: OUT ADD + 3, 146:
  RETURN

1 REM** GRAFDATA.BAS

2 REM** Graph PcA/D-Mate .ADD File Data (Requires Graphics Monitor)

3 REM** V910802 - JJ Barbarello
    4 REM**
   10 CLEAR : DEFINT 1-J, Y: KEY OFF: CLS
20 COLOR 0, 7: LOCATE 3, 27: PRINT " GRAPH FCA/D-MATE DATA "; : COLOR
 7, 0
30 LOCATE 10, 20: INPUT "Enter File Name (ex: TEST1.ADD)..."; DFNS
40 OPEN "R", 1, DFNS, 2: FIELD 1, 2 AS DS: IF LOF(1) > 0 THEN GOTO 80
50 CLOSE: KILL DFNS: BEEP: LOCATE 25, 13
60 PRINT "That File Doesn't exist. Press ANY key to try again...";
70 A$ = INPUT$(1): CLS: GOTO 20
80 LOCATE 21, 34: COLOR 16, 7: PRINT " Reading data "; : COLOR 7, 0
90 DIM I((LOF(1) / 2) + 3)
100 FOR I = 1 TO LOF(1) / 2: GET 1, I: I(I) = 190 - CVI(D$): NEXT
110 LOCATE 21, 34: PRINT SPACE$(20)
120 LOCATE 12, 20: PRINT "File Has"; LOF(1) / 2; "Samples."
130 LOCATE 14, 20: INPUT "Enter Start Sample To View..."; ISTART
140 LOCATE 15, 20: INPUT "Enter End Sample To View"; IFIN
150 IF IFIN - ISTART > 1000 THEN IFIN = ISTART + 999
160 I(I) = I(I - 1): I(I + 1) = I(I): I(I + 2) = I(I + 1)
170 YINC = 500 / (IFIN - ISTART)
180 IF (IFIN - ISTART) > 499 THEN istp = 2 ELSE istp = 1
190 SCREEN 2: LOCATE 2, 1: PRINT "SAMPLES": LOCATE 3, 1: PRINT "-------"
   200 LOCATE 4, 1: PRINT "Start:"; ISTART: LOCATE 5, 3: PRINT "End:";
    IFIN
    210 LOCATE 20, 1: PRINT "Press <ESC>": LOCATE 21, 3: PRINT "TO
   End..."

220 LINE (138, 0)-(138, 190): LINE (138, 190)-(639, 190): J = 139
230 FOR I = 0 TO 152 STEP 38: LINE (128, I)-(137, I): NEXT
240 LOCATE 1, 13: PRINT "5.0": LOCATE 24, 16: PRINT "0";
250 LOCATE 12, 12: PRINT "VOLTS";
260 FOR I = ISTART TO IFIN STEP istp
270 LINE (J, I(I))-(J + YINC, I(I + istp)): J = J + YINC; NEXT I
280 A$ = INKEY$: IF A$ = "" THEN 280
290 IF A$C(A$) = 27 THEN SCREEN 0: END ELSE BEEP; GOTO 280
```

our circuit. We want only the voltage generated by the piezo sensor, so disconnect the J1 end

of R1, shown in Fig. 2 last time (R1 provided +5-volts DC to the temperature probe). With no in-

put signal, adjust R11 for maximum gain, and R12 so output is about 2.5-volts DC. (The latter setting allows the piezo voltage to vary from that quiescent level.) You might also want to adjust the value of R3 so that the piezo sensor produces maximum indication at its maximum output.

To test the circuit, use a piece of masking tape to secure the piezo sensor to a flat surface, making sure you aren't flexing it. Tap the surface firmly and note the response. In actual use, you would mount the sensor using a clamping device or flexible adhesive. This type of device is useful for measuring applied impact, oscillation after impact, or amount of flex or bend.

Acoustic sensing

You've probably seen audio signals displayed on an oscilloscope. Now imagine "freezing" those signals—i.e., storing them in digital form. Scientists capture digitized audio in this way to study the sounds that whales, birds, and other animals make. In digitized form, it's easy to compare and contrast different sounds to determine which have similar characteristics, or to look at other factors that wouldn't otherwise be obvious.

To accommodate a microphone input, we modified the ADC circuit as shown in Fig. 3. The changes allow us to increase the gain of IC1-a to a maximum of 100, and to attenuate high-level inputs. Gain is determined by the ratio R14/  $R6 = 10^6/10^4 = 10^2 = 100$ . If the part numbering in Fig. 3 seems strange, it's because we tried to stay consistent with the main circuit shown in Fig. 2 in January. Note that in the January version, R6 was 100K; here we decreased its value to 10K. Also, we no longer use R1–R4.

In operation, first set R12 to mid-value. Then adjust R14 for maximum range, as described last time. Last, readjust R12 as necessary to set the quiescent level to about 2.5-volts DC. For example, a microphone might provide a maximum output

# LISTING 2 1 REM\*\* GRAPDATA.BAS 2 REM\*\* Graph PCA/D-Mate .ADD File Data (Requires Graphics Monitor) 3 REM\*\* V910802 - JJ Barbarello 4 REM\*\* 10 CLEAR : DEFINT I-J, Y: KEY OFF: CLS 20 COLOR 0, 7: LOCATE 3, 27: PRINT " GRAPH PCA/D-MATE DATA "; : COLOR 7, 0 30 LOCATE 10, 20: INPUT "Enter File Name (ex: TEST1.ADD)..."; DFNS 40 OPEN "R", 1, DFNS, 2: FIELD 1, 2 AS D\$: IF LOF(1) > 0 THEN GOTO 80 50 CLOSE : KILL DFNS: BEBF: LOCATE 25, 13 60 PRINT "That File Doesn't exist. Press ANY key to try again..."; 70 A\$ = INPUT\$(1): CLS : GOTO 20 80 LOCATE 21, 34: COLOR 16, 7: PRINT " Reading data "; : COLOR 7, 0 90 DIM I((LOF(1) / 2) + 3) 100 FOR I = 1 TO LOF(1) / 2: GBT 1, I: I(I) = 190 - CVI(D\$): NEXT 110 LOCATE 21, 34: PRINT SPACE\$(20) 120 LOCATE 12, 20: PRINT "File Has"; LOF(1) / 2; "Samples." 130 LOCATE 14, 20: INPUT "Enter Start Sample To View..."; ISTART 140 LOCATE 15, 20: INPUT "Enter Ends Sample To View..."; ISTART 150 IF IFIN - ISTART > 1000 THEN IFIN = ISTART + 999 160 I(I) = I(I - 1): I(I + 1) = I(I): I(I + 2) = I(I + 1) 170 YINC = 500 / (IFIN - ISTART) 180 IF (IFIN - ISTART) > 499 THEN ISTP = 2 ELSE ISTP = 1 190 SCREEN 2: LOCATE 2, 1: PRINT "SAMPLES": LOCATE 3, 1: PRINT "---- 200 LOCATE 10, 13: PRINT "Start:"; ISTART: LOCATE 5, 3: PRINT "End:"; IFIN 210 LOCATE 10, 13: PRINT "Start:"; ISTART: LOCATE 5, 3: PRINT "End:"; 151 LOCATE 10, 13: PRINT "Start:"; ISTART: LOCATE 21, 3: PRINT "TO End..." 220 LINE (138, 0)-(138, 190): LINE (138, 190)-(639, 190): J = 139 230 FOR I = 0 TO 152 STEP 38: LINE (128, I)-(137, I): NEXT 240 LOCATE 1, 13: PRINT "5.0": LOCATE 24, 16: PRINT "0"; 250 LOCATE 1, 13: PRINT "Start: HEN 280 260 IF ASC(A\$) = 27 THEN SCREEN 0: END ELSE BEEP: GOTO 280

voltage of 0.5. Adjust R14 so the maximum is about 4.0 volts. Then readjust R12 so the no-signal (quiescent) value is about 2.5-volts DC. Now you'll get the best resolution from the circuit.

### Software

We wrote two programs for data capture and display. Listing 1 shows the capture program (ADC.BAS), and Listing 2 the display program (GRAF-DATA.BAS)—both are available on the RE-BBS (516-293-3000, 1200/2400, 8N1) as a file called PCADMAT2.LST. Figure 4 shows sample output from GRAFDATA. Enhanced versions of both programs are available on disk from the author for a nominal fee; see the sidebar for details.

ADC.BAS is a general-purpose data capture and storage utility. To use it, you must create a data file called HWAD-DRES.DAT in the same directory as the program. The file contains the decimal address of the PC IO card. You can create the file with any text editor or word processor capable of storing text in ASCII format. Assuming your card is set to the default

address (640), create a one-line file that contains "640D" (without the quotes) followed by a carriage return.

Connect the ADC circuit to your PC and run ADC.BAS. It initializes the PC IO card, then asks you for the interval (in seconds) to wait between samples. If you want continuous samples (with no delay), enter 0. Otherwise, you can enter any number between 1 and 3600 (one hour). When you press Enter, sampling begins.

The program displays three pieces of information: current data (line 100), time between samples (line 110), and current sample number (line 120). Press Esc at any time to end sampling (line 130).

Lines 150–200 take care of interval timing. The sampling program showed last time used a timing loop that was system-dependent; the current version reads the system clock, hence is system-independent. Sampling takes place in lines 210–250; as many as 1000 samples are saved in array A.

When you press Esc to end sampling, execution continues at line 270. If you press Esc

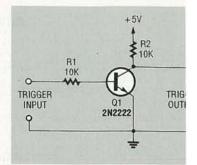


FIG. 5—DIGITAL TRIGGER CIRCUI lows the PC IO to start reading based on the appearance of a pred mined signal. Connect this circuit tween that signal and an unused P input, and modify the software accingly.

ORDERING INFORMATION

The following items are availab from JJ Barbarello, 817 Tenne Road, Manalapan, NJ 07726.

 Complete PC IO Board with F board and all components (part PCIO)—\$39.95

 An ADC0804 and a calibrate PN222A temperature sensor tra sistor (part #ADC)—\$8.00

PC IO software, including corpiled and source code version with continuous and interval sar pling and data logging/listin Specify disk size, 3.5" or 5.25 (part #ADC-S)—\$8.00.

 Software from this installmer including a menu-driven, compile program (with source code), e panding on the identified functior and adding discrete data listin graphed data sample selectio value display, and other feature (part #ADM-S)—\$10

Specify part number(s) and ser check or Money Order.

The author will be glad to answer at questions, but they must be a companied by a self-addresse stamped return envelope.

again, data is abandoned and program ends. If you press En the program requests a file na for storing the data. Specify complete file name, includany path and extension (e. C:\SUB1\TEST01.ADD.) If y don't specify a complete path, file will be stored in the curr directory. If the file already exist current data will be appended the end of the file.

GRAFDATA.BAS allows you plot your data on-screen. Wh you run the program, it as you to specify a data file. As w ADC.BAS, specify the full path if the file is not in the c

(Continued on page

# WORKING WITH LED'S

We continue our survey of optoelectronic principles and systems, with an in-depth look at practical LED chaser and bar-graph displays.

**RAY MARSTON** 

LAST MONTH, WE BEGAN INTRODUCing the general subject of optoelectronics, and we examined light-emitting diodes (LED's) and several practical LED flashers in detail. In this article, we'll examine several practical LED chaser (or sequencer), dot, and bar-graph displays.

Chaser principles

One of the most popular LED displays is known as a chaser, also called a sequencer. That's when an IC drives an LED array, so that each LED (or small groups thereof) turns on and off in a fixed, periodic sequence, that appears as a ripple of light running along a chain. The LED's don't necessarily have to be arranged linearly, and can be placed in any desired geometric pattern, to alter the visual effect.

The most popular CMOS IC which is used for that purpose is the CD4017B, which is a decade counter/divider IC with 10 decoded outputs, each capable of directly driving an LED display. If desired, the outputs can be coupled back to the IC control terminals to make the device count to (or divide by) any number from 2–9, and either stop or recycle.

The CD4017B is easily cascaded for use in multi-decade frequency division, or for use in counters with any number of decoded outputs. It's extremely versatile, and it can easily be used in a chaser or sequencer LED display of any desired

Figure 1 shows the pinouts of a CD4017B, with decoded outputs in arithmetic order. Figure 2 is its timing diagram; the CD4017B is a 5-stage Johnson counter with CLOCK, RESET, and CLOCK INHIBIT inputs. The counters are advanced with each positive-going clock pulse, when the CLOCK INHIBIT and RESET inputs are low. At any time, nine of the 10 decoded outputs are low, while the remaining one is high.

The 10 outputs go high sequentially in step with the clock, with the selected output

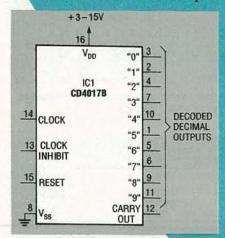


FIG. 1—PINOUTS OF THE CD4017B decade counter/divider, with its decoded outputs shown in ascending arithmetic order. The clock is inhibited by a high on pin 13, and the counter is reset by a high on pin 15 and advances on a positive-going clock transition.

staying high for one full clock cycle. The CARRY OUT goes high for one clock cycle out of every 10 clock cycles, and it can be used to ripple-count more CD4017B's in a multi-decade counting application. The counting cycle is inhibited by setting CLOCK INHIBIT high. A high on the RESET input clears the counter, and sets the "O"-output high.

### CD4017B chaser circuits

Figure 3 shows a practical CD4017B 10-LED chaser, with IC1, a 555 astable multivibrator, which is used as a variable-speed clock generator. The CD4017B becomes a decade counter by grounding pins 13 (CLOCK INHIBIT) and 15 (RESET). The visual display will appear as a moving dot sweeping from left to right (or from LED's "0"—"9") in 10 steps, as the outputs go high and turn the LED's on sequentially. They can either be arranged in a straight line, or configured circularly, so that the dot appears to rotate.

The LED's shown in Fig. 3 aren't current-limited. Manufacturers don't give a maximum short-circuit current for the CD4017B, but practical experience dictates a value somewhere between 10–15 milliamps. The maximum dissipation per output on some data sheets is 100 milliwatts, so up to 7 volts DC can be developed safely across a CD4017B output stage at maximum current.

Each LED is connected between output and ground, and can have a maximum supply of 9 volts DC, for a 2-volt DC drop across each LED that's lit. Above 9 volts DC, use the version shown in Fig. 4, which contains a current-limiting resistor, and is capable of being used with supplies up to 12 volts DC.

Figure 5 shows a possible equivalent of the circuit in Fig. 4, that uses a 15-volt DC supply, that also illustrates a major design flaw. When one LED is on, the anodes of the others are grounded, so R1 reverse-biases them. Due to low LED reverse voltage ratings, you'll often find that an LED that's off will ac like a Zener diode at about for the state of the state of

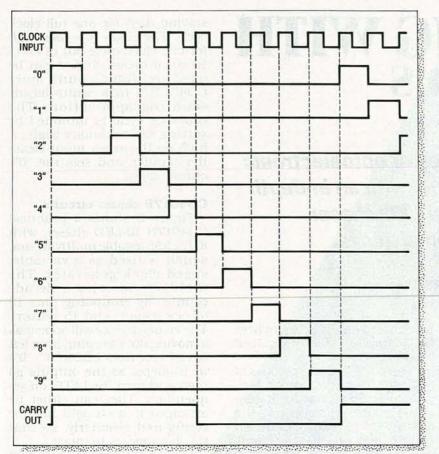


FIG. 2—WAVEFORM TIMING DIAGRAM OF THE CD4017B, with its RESET and CLOCK INHIBIT terminals (pins 13 and 15) grounded.

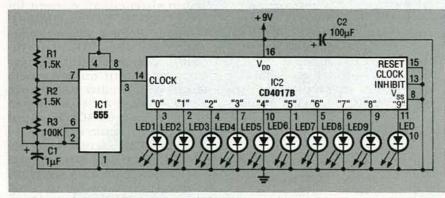


FIG. 3—A 10-LED CHASER OR SEQUENCER that can be used with supply voltages up to only 9 volts DC, and which produces a "moving-dot" display.

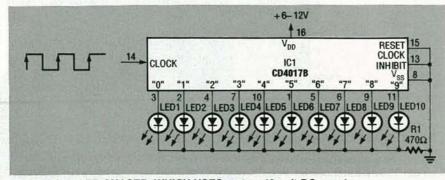


FIG. 4—A 10-LED CHASER, WHICH USES up to a 12-volt DC supply.

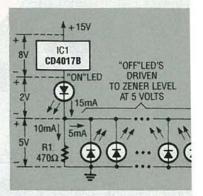


FIG. 5—A POSSIBLE EQUIVALENT Fig. 4, which uses up to a 15- volt-supply.

volts DC, and possibly destring a CD4017B output stage.

When a CD4017B driv LED's in moving-dot mode, the can be connected directly to the IC outputs if supply values a not more than 9 volts DC. For higher supplies, you'll need current-limiting resistors. Seven such display circuits are shown in Figs. 6–12.

### Alternative LED displays

The output stages of tl CD4017B can either source sink currents equally well. Fig shows IC2 used in sink-mode a moving-hole LED displa nine of the 10 LED's are on any given time, while one turn off sequentially. If the LED's a arranged circularly, they see to rotate. Since all LED's exce one are on at a time, they need current-limiting resistor

Moving-dot displays a much more popular than the moving-hole variety. The type shown in Fig. 3 can be designed to use fewer LED's just by ome ting the unwanted ones, but then the dot moves intermitently or scans, since IC2 tak 10 clock steps per sequence and all the LED's will be off during the unwanted steps.

If a continuously-moving diplay with fewer than 10 LED's needed, connect the first u used CD4017B output to pin (RESET), as indicated in the LED version shown in Fig. 7.' achieve an intermittent displusing a controlled number of a steps, just connect the desir unwanted output to pin 15 RESET). Or, in other words, mothe connection going to pin

of IC2 to pin 9. In that type of an intermittent display, the LED's will light for four cycles, go blank for four cycles, and the

sequence then repeats.

Figure 8 shows a visually attractive 4-LED, 5-step sequencer. Initially, all four LED's are on, and then turn off sequentially until they're all off in the fifth step, as shown in the accompanying table. The LED's are effectively in series, and the basic circuit can't drive over four LED's.

Figure 9 shows another version; here, the CD4017B does a 10-step sequence, with LED 1 on from steps "0"-"3," LED 2 on for "4"-"6," LED 3 on for "7" and "8," and LED 4 on for step "9." The display will accelerate from LED 1-LED 4, not just sweeping smoothly from one LED to the next, and the cycle then repeats ad infinitum.

Figure 10 shows such a circuit modified to produce an intermittent display, where the visual acceleration occurs for 10 clock cycles, the LED's all blank for 20 cycles, and then the counting cycle repeats. When IC2 is in a ÷10 mode as shown in Figs. 9 and 10, pin 12 (CARRY OUT) produces an output each time IC2 does a decade count, which is used to clock IC3 (which is connected in ÷3 mode), with its "0" output fed to Q1.

For the first 10 cycles of a sequence, the "0" output of IC3 is high, and Q1 is biased on, so IC2 acts as shown in Fig. 9, with the LED's turning on sequentially through Q1. After the 10th clock pulse, the "0" output of IC3 goes low, turning Q1 off; the LED's can no longer light, but IC2 keeps counting. After the 30th clock pulse, the "0" output of IC3 again goes high and turns Q1 on, reenabling the display.

Figure 11 is a simple multiplexed display, where IC3 and Q3 enable or disable a bank of LED's. Figure 11 is yet another example of a multiplexed display, which uses three lines of six intermittently-sequenced LED's. They're each sequentially enabled via IC3 and individual gating transistors, only

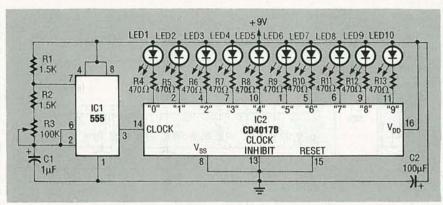


FIG. 6-A 10-LED "MOVING-HOLE" DISPLAY.

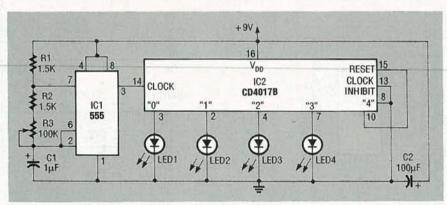


FIG. 7—A 4-LED CONTINUOUS "MOVING-DOT" DISPLAY. To get an intermittent "moving-dot" display using a 50% "blanking" period, just change pin 10 (or output "4") to pin 9 (or output "8").

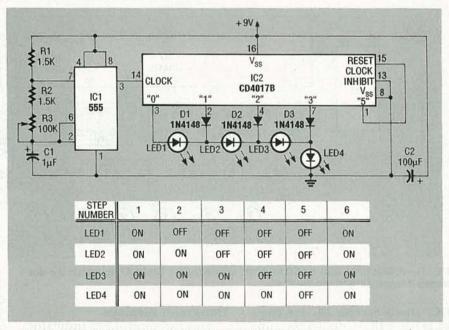


FIG. 8—A 4-LED, 5-STEP SEQUENTIAL TURN-OFF DISPLAY.

one line at a time; if you want, you can expand this version still further to control a 10-line, 100-LED, matrix display.

Figure 12 shows a 4-bank, 5-

step, 20-LED chaser; the four LED's are in series in each of the five CD4017B outputs, so four LED's are lit at any one time. Each lit LED drops about 2 volts

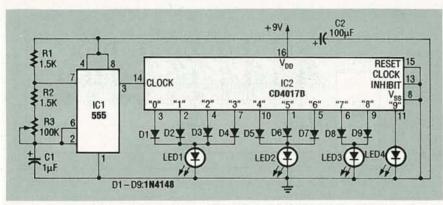


FIG. 9-A 4-LED CONTINUOUS "ACCELERATOR" DISPLAY, where the pattern of the dots appears to accelerate from left to right.

can use the LED's as eithe bar- or dot-graph display. I bar-graph display, the input ue is indicated by the to number of LED's that are lit the dot display, the input va is indicated by the relative p tion of just one lit LED.

Special IC's are available building LED analog displa the most useful examples be the U2X7B family from AI and the LM3914 family from tional Semiconductors. 7 U2X7B family consists of s ple, dedicated devices, wh

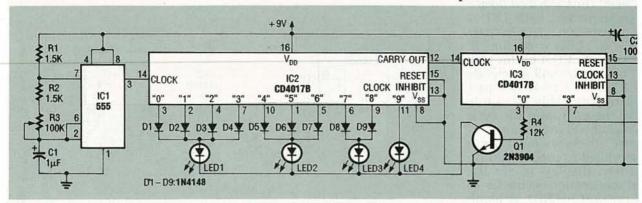


FIG. 10-A 4-LED INTERMITTENT "ACCELERATOR" DISPLAY, where the "acceleration" occurs for 10 out of every 30 clock steps.

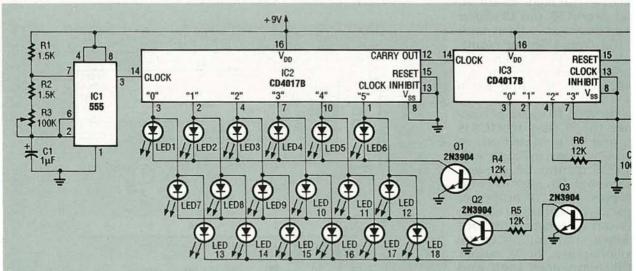


FIG. 11-A MULTIPLEXED 6-LED × 3-LINE MOVING-DOT DISPLAY, in which the dot moves intermittently along the lines.

DC: that's 8 volts DC for each LED bank that's on, so the supply voltage must be greater than that for the circuit to work. A greater number of LED's can be used in each LED bank if the supply voltage is correspondingly increased to handle the 72 added load.

### Bar-graph displays

Another multi-LED indicator circuit is the analog version, which drives a chain of linearlyspaced LED's. The number of LED's that are lit is proportional to the voltage applied to the LED-driver, so the circuit acts like an analog voltmeter. You

can be usefully cascaded drive up to 10 LED's in ba graph mode only, the member being the U237B, U247 U257B, and U267B. T LM3914 family is more compl and versatile by compariso and are easily cascaded to dri up to 100 LED's in either b graph or dot-graph mode. Bo varieties of IC's are consider to be bar-graph drivers.

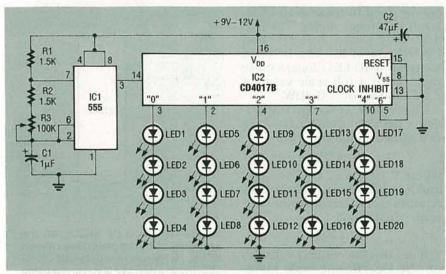


FIG. 12—A 4-BLANK 5-STEP 20-LED CHASER, for use with a supply above 9 volts DC.

### TABLE 1—U2X7B INTERNAL TRANSISTOR STATES AT VARIOUS INPUT VOLTAGES

V <sub>IN</sub> ,V	Q1	Q2	Q3	Q4	Q5
1.0	Off	Off	Off	Off	Off
8.0	Off	Off	Off	Off	On
0.6	Off	Off	Off	On	On
0.4	Off	Off	On	On	On
0.2	Off	On	On	On	On
0.0	On	On	On	On	On

IC-driven bar-graph displays are inexpensive, superior alternatives to analog meters. They don't stick, they're fast, and they're unaffected by both vibration and attitude. Their scales can have any desired shape, they can have mixed LED colors to highlight special sections, and they can be equipped with over-range detectors that are activated by the

drivers to either sound an alarm, flash the display, or both.

The linearity of such a bar- or dot-graph meter is considerably better than that of most analog meters, and is generally about 0.5%. The resolution depends on the number of LED's that are used; a 10-LED version has adequate resolution for most hobbyist purposes.

### Basics of the U2X7B IC family

The AEG U2X7B IC family is composed of four different 8-pin DIP's, each capable of driving five LED's. The U237B and U247B pair produce a linear display, and are used together when driving 10 LED's. The U257B and U267B pair produce a logarithmic display, and are also used together when driving 10 LED's. All four IC's in the family use the same internal circuitry, in block diagram form, as shown in Fig. 13.

All four IC's contain five Schmitt voltage comparators with unique thresholds feeding

### TABLE 2-U237B INTERNAL STEP VOLTAGES

Device	Step 1	Step 2	Step 3	Step 4	Step 5
U237B	200 mV	400 mV	600 mV	800 mV	1.00 V
U247B	100 mV	300 mV	500 mV	700 mV	900 mV
U257B	0.18V/ -15 dBW	0.53V/ -6 dBW	0.84V/ -1.5 dBW	1.19V/ +1.5 dBW	2.0V/ +6 dBW
U267B	0.1V/ -20 dBW	0.32V/ -10 dBW	0.71V/ -3 dBW	1.0V/ 0 dBW	1,41V/ +3 dBW

## TABLE 3—U237 IC FAMILY MAJOR SPECIFICATIONS

Parameter	Mini- mum	Typ- ical	Maxi- mum
Supply voltage	8V	12V	25V
Input voltage	-	-	5V
Input current		-	0.5 mA
Max supply current	-	25 mA	30 mA
Power dissipation (at 60°C)	-	-	690 mW
Step tolerance	-30 mV	-	30 mV
Step hysteresis		5 mV	10 mV
Input resistance	_	100 K	ji <del></del>
Output saturation voltage	-		1V

into transistor switches. The thresholds are fixed by the tapping points on voltage divider R1–R6, which is powered using a built-in voltage regulator: each comparator input is connected to pin 7.

All four IC's also contain an internal 20-milliamp constant-current source, and the five external LED's go in series between it and ground (pin 1), as shown. Groups of LED's are turned on or off using the individual switching transistors. If Q3 is turned on, it sinks 20 milliamps via LED's 1 and 2, so they turn on, and LED's 3–5 turn off.

The U2X7B family has step voltages spaced at 200-millivolt DC intervals, and Table 1 lists the states of its five internal transistors at various input voltages. At 0 volts DC input, all five transistors are switched on, so Q1 sinks the full 20 milliamps, and all five LED's are off. At 200 millivolts DC, Q1 turns off but all other transistors are on, so Q2 sinks the 20 milliamps via LED 1, driving LED 1 on and turning all others off.

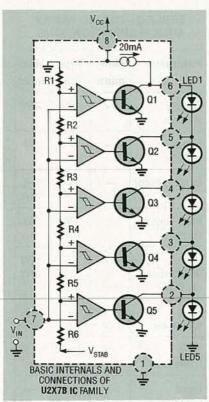


FIG. 13—BLOCK DIAGRAM OF a U2X7B bar-graph driver, showing the basic external connections.

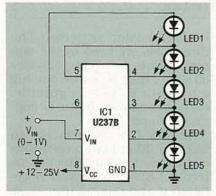


FIG. 14-A 0-1-VOLT DC, 5-LED, linearscale bar-graph meter using a U237B.

With an input of 1 volt DC, all transistors are off, the 20 milliamps go to ground via the LED's, so all five LED's are on. The IC current is independent of the number of LED's turned on, so minimal RF interference (RFI) is produced as it switches transistors and LED's.

The four IC's in the U2X7B family differ only with regard to their step voltages, which are fixed by R1-R6 as shown in Table 2, and the values for which are also given in dBW (or dB relative to a watt). The linear-scale 74 U237B and U247B pair of IC's can be used to make a 10-LED. 1-volt DC linear meter. The logarithmic-scale U257B and U267B pair of IC's can be used to make a 10-LED logarithmic meter with a full-scale value of 2.0 volts DC, or +6 dBW.

The reason for the correspondence between those two values is justified as follows. Since

$$P = E^2/R$$

where P is power, E is voltage, and R is resistance, then the assumption, for purposes of convenience, is that:

$$R=1$$
 ohm.

If so, then to convert voltages on the logarithmic-scale meter into a quantity proportional to power (and not into power itself), just square the voltage indicated, take the log<sub>10</sub> of the result, and multiply by 10. If E has the unit of volts (as opposed to some fractional or multiple unit, like millivolts, for exam-

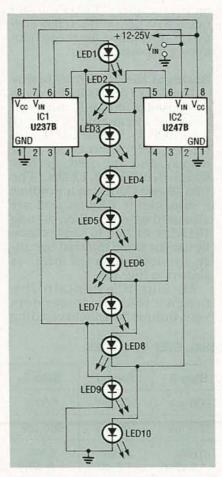


FIG. 15-A 0-1-VOLT DC, 10-LED, linearscale bar-graph meter using a U237B and a U247B connected as a pair.

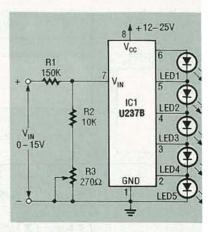


FIG. 16-METHOD OF REDUCING th sensitivity of the bar-graph meter show in Fig. 14, for use in a 0-15-volt DC, LED, linear-scale, bar-graph meter usir a U237B.

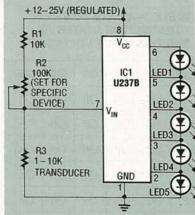


FIG. 17—SIMPLE USE OF A transduce to show the value of a physical quantit

ple), then P has the units of watts, and the units in dB ar called dBV, since they're ex pressed relative to a fixed valu of potential.

Likewise, if you wanted to ex press dB in terms of power, the the proper terminology woul be dBW, or a similar unit for an fractional unit of power. Th number of dBV is always doubl the number of dBW, since taling the log10 of both sides of th power relation gives

$$\begin{aligned} \log(P) &= \log(E^2/R), \\ &= 2 \times \log(E) + \log(R), \\ &= 2 \times \log(E) + \log(1), \\ &= 2 \times \log(E). \end{aligned}$$

For that reason,

1 dBW = 2 dBV.

For example, in Table 2, fc the U267B and step 5, the entr given is 1.41 volts DC, or + dBW. On squaring that, you ge 2 volts², so 10 times its log<sub>10</sub> is +3 dBW, and doubling that gives +6 dBW. Of course, when ever you take the logarithm of a quantity like voltage or power, you always operate on the numerical part alone, and ignore the units. If you ever hear of an audio or noise level that's expressed in dB alone, with no unit appended to indicate "dB with comparison to what," such a specification is nonsense.

To express an amplitude in dB relative to a unit of potential or power with a multi-letter abbreviation, just append the whole unit, like dBmV for dB relative to a millivolt. Sometimes, the term dBm is used as an abbreviation for dBmW, or dB relative

to a milliwatt.

Table 3 lists the specifications of the U2X7B family. When driving five red LED's, each with a 2-volt DC forward drop, the minimum supply value required must be 12 volts DC. Different-colored LED's with different forward drops can be used together, if the supply voltage is adequate.

Although the IC input impedance is typically 100K, the IC becomes unstable if the source impedance is above 20K. It should ideally be kept under 10K; if it's not, place a 0.01-µF capacitor between pins 1 and 7

for added stability.

### **Practical U2X7B circuits**

Figures 14–19 show practical U2X7B-family circuits; in all of them, the supply is 12–25 volts

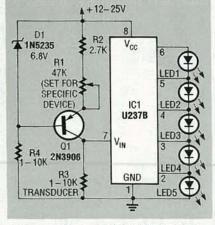


FIG. 18—AN ALTERNATIVE USE of a transducer to show the value of a physical quantity.

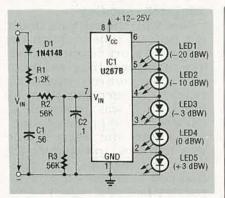
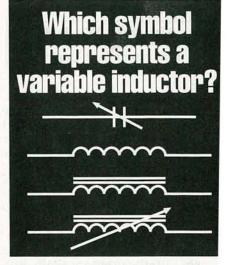


FIG. 19—A 5-LED LOG-SCALE audiolevel meter; a 10-LED version is made using a U257B and U267B pair, in a fashion similar to the version shown in Fig. 15.

DC, but you'll have to remember the constraints previously mentioned. Figure 14 shows a 0–1-volt DC, 5-LED, linear-scale meter using a U2X7B, and Fig. 15 shows a U237B and U247B pair used in a 0–1-volt DC, 10-LED, linear-scale meter. The latter circuit operates each IC as shown in Fig. 14, with supply voltages that are appropriate to five LED's, but their input terminals are tied together, and the LED's are alternated, to achieve a 10-LED display.

Figure 16 shows how the fullscale sensitivity of the meter is reduced by feeding the input to IC1 via R1-R2-R3, using a ratio of 15:1, and giving full-scale sensitivity of 15 volts DC. Figures 17 and 18 show how the circuit shown in Fig. 14 can be used to display a physical quantity like light intensity or heat, as represented by the analog resistance R3 of a transducer. In both, the transducer is fed by a constant-current source, so the input voltage to IC1 is directly proportional to the transducer resistance.

As shown in Fig. 17, constant transducer current is derived from regulated supply via R1-R2, since regulated supply voltage is large relative to the 1-volt DC full-scale meter sensitivity. By contrast, as shown in Fig. 18, constant current is ensured via D1-Q1. Finally, Fig. 19 shows the U267B used in a 5-LED logarithmic audio-level meter. A 10-LED meter can be made using a U257B and U267B pair as shown in Fig. 15.



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rent directory. If the file exists, the program then tells you how many samples it contains, and asks start and stop points for the plot; the maximum number is 1000.

The program (line 170) scales the graph to produce the widest possible graph; lines 220-270 graph the data. Press Esc to terminate the program. To "magnify" a limited portion of the data set, run the program again, and enter appropriate start and end values (e.g., 350 and 450). You can print your graphs by running the DOS program GRAPHICS.COM before GRAFDATA.BAS. When the desired graph appears on the screen, press PrintScrn. (You must have a compatible printer in order to print out any of the graphs.)

Triggered sampling

Now with the software under our belt, it's time to finish the "rapper" story begun earlier. The rapper was triggered by an electronic control circuit. We tried to trigger sampling by hand, but it was impossible to tell when the rapper was about to energize, and reaction time was too slow and unsure for accurate triggering. Our solution was to create a trigger input. We tapped a digital signal from the control circuit that changed just before the rapper triggered.

The ADC circuit uses only 8 of the 24 input lines on the PC IO. What we did is use bit 0 of port B as a trigger input. Then by adding a single line of code, we could trip on either a low-tohigh signal:

145 IF (INP(ADD + 1) AND 1) = 0 THEN **GOTO 145** 

or a high-to-low signal:

145 IF (INP(ADD + 1) AND 1) = 1 THEN**GOTO 145** 

If you want to add a slight d between the trigger and start of sampling:

146 FOR I = 1 TO DELAYTIME : NE However, the delay time in case would vary with the sp of your PC. In addition, m sure the trigger signal is T compatible (logic low = 0V, logic high = 5V). If it isn't you want to buffer the trig signal from your system, can use the circuit of Figur Remember, this circuit inve the incoming trigger signal a positive-going trigger will negative-going when it exits buffer circuit. Adjust added 145 accordingly.

### Conclusions

The analog world of natur not so distant from the dig world of computers. Simple cuitry can allow your PC to fu tion as a digital eye, ear, or ha on the external world. The cuits and software shown h are only the beginning.



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avelets. We have got lots of wavelets. You getcher wavelets here. As we've discovered a number of times before, wavelets are a stunning new math concept that is profoundly changing virtually all the advanced electronic topics. A failure to learn wavelets now is the same as volunteering for early retirement.

We've already seen that Jones and Bartlett has published THE great new wavelets book, and that the Ultrawave Explorer from the Aware folks is definately one fine commercial wavelet study and de-

velopment program.

But the big news is that I've just posted full working PC shareware copies of the Wavelet Packet Library from Digital Diagnostics on GEnie PSRT as #365 WAVELET.PS.

Those of you into satellite dishes and microwave electronics are now probably familiar with *Smith Charts*, a handy graphical method of doing things like impedance matching and tuning. I have written a PostScript Smith Chart generator that lets you instantly create all your own Smith charts in any quantity, any size, any resolution, and any where in your publication. Check *GEnie* PSRT #367 SMITHCHT.PS for several freeware samples. Your downloading cost on this is around twenty one cents.

### Perpetual motion again

I get an average of three to five helpline calls a week on "free energy" and other perpetual-motion topics. As we have seen in the past, perpetual motion is definitely real as a historic and ongoing societal phenomenon. We have also seen that two ongoing sources of perpetual-motion books, videos, and papers are High Energy Research and Lindsay Publications.

Now, I personally feel that looking for any free-energy systems is rather dumb. First, because the desirability of any free energy ranks somewhere between Herpes and AIDS. Why? Because this would obviously hasten the already ongoing entropic heat death of the planet. If someone does in fact find a free-energy system, they should be spanked and sent to bed without any supper. Or, better yet, chopped up and fed to the cows.

Second, because the odds of your accomplishing anything that's even remotely useful involving free energy are stupendously low. Third, because your credibility starts out as less than zero and quickly plummets. Owing to previous scams, the "not even wrong" research, and the "few-chips-shy-of-a-full-board" guilt by association.

And, finally, because there's so much better to be doing. We're sitting on the greatest mountain of new hardware hacking chips, tools, info, and concepts anywhere ever. Stuff that's crying for hacker use, and stuff that is nearly certain to result in lots of interesting and profitable things. Why should you ignore the obvious?

Several of the recent callers were making measurements that were just plain wrong. Since I am one of the world's foremost experts in gathering incorrect, misleading, or meaningless lab data, I thought we might briefly focus on a few of the

ways that casual measurements may not end up what they appear to be.

In general, you'll always want to assume that all meter pointers and, especially, all of your digital numeric displays are lying through their teeth. Or, if they are giving you a correct reading, the odds are overwhelming that the meaning and the underlying reasons for that reading are not at all what you had in mind.

Oscilloscopes do a far better job than the meters or digital displays at showing you what is really coming down. Even here, an uncompensated probe, the wrong setting, improper sync, an invisible glitch, any outband signals, or just a ground clip that is slightly too long can cause you wildly incorrect results.

It is only when the same tests are run over and over again by different people under different circumstances that you can even remotely begin to trust your instruments. Even when repeated, that trust should only apply to the *exact* measuring conditions.

A ferinstance: Figure 1 shows you a seemingly simple method to measure AC power. You connect your new motors-and-magnets perpetual motion machine load to the AC power line through an ammeter and then separately measure the line voltage. Since power equals volts times amps, you just multiply your two readings together and you'll have the input power. Right?

Wrong. Dead wrong.

Let's temporarily forget about any noise, spikes, back-EMF effects, harmonics, and non-linearities that are certain to be present with your new motors-and-magnets load. Assume a pure sine-wave voltage and a similar current waveform. You have to take the phase of the current into account. You would get a zero phase shift

### **NEED HELP?**

Phone or write your Hardware Hacker questions directly to: Don Lancaster Synergetics Box 809 Thatcher, AZ 85552 (602) 428-4073 with a purely resistive load. In a purely inductive load the voltage would lead the current by 90 degrees. In a purely capacitive load, the voltage will lag the current by 90 degrees.

Good old ELI THE ICE MAN. The voltage is ahead of the current in the eLi's Linductor; the current is ahead of the voltage in his iCe capacitor.

And if you have any purely active load such as another generator, your current could end up phased by 180 degrees. Sourcing, not sinking.

Your actual power will end up as the voltage times the current times the cosine of the phase angle between the two. If your voltmeter reads 110 and your ammeter reads 4, your actual circuit power will be 440 watts to a purely resistive load, ZERO to any purely inductive or capacitive load, and MINUS 440 watts to any purely active load. Or anything between, depending upon your phase angle.

Why is the power zero to a purely inductive load? Because of the

### you the full cycle cross product of a sine and its cosine is zero. Intuitively, on the first quarter cycle, you have positive voltage and current. On your next quarter cycle, you will have positive voltage and negative current. On the next, negative voltage and negative current. And finally, negative voltage and positive

phase angle. A math freak will tell

Yes, you will get lots of back-andforth reactive power that can give you real fits. And hack off your electric utility. But your net real power into a pure inductive or capacitive

Thus, as far as power goes, all the voltmeter and ammeter readings are totally meaningless. And they are even less so in the presence of noise, back EMF's, sparking, or harmonics.

### Measuring real power

So how do you measure real and reactive power? The trick is that you have to multiply the instantaneous voltage and current together. Then

form is equal to the DC continuous power that would give you exactly the same amount of total heating in a purely resistive load.

You can do this measurement with a real wattmeter, or by measuring the rotational speed and direction of a watthour meter. The wattmeters and watthour meters are often available through Fair Radio Sales or Herbach and Rademan.

Electronically, you can use a multi-

4 amps Motors and AC power Magnets Volts line Load

FIG. 1-WHAT IS THE REAL POWER being consumed in this test circuit? There's way to tell with the setup shown. But you can safely bet that it is probably anywhere near 440 watts

calculating circuit. Analog Devi is one leader in low-cost po chips of this type. of all the exact voltage and cur waveforms, split them up into t slices so narrow that the voltage current does not change much, r tiply the results of those slices

current. Add them all up and average them all out and you end up with zero real power.

load is precisely zero.

For these reasons, it is extren difficult to accurately measure y input power to a motors-and-m

plier chip or a special RMS por

Or graphically, you can take p

Note that you must multiply and then add. Never vice versa

But you still do have to be care

Nonlinearities, pulses, harmon

motor back-EMF effects, and no

require special treatment. And m

power measurement schemes h

a crest factor limit which ruins t

accuracy on strong but nar

pulses. Especially things like spi

then sum the results.

and glitches.

Typical IC

Series Regulator

you sum to find the total power.

The power of any arbitrary wave-

FIG. 2-WHEN IS A REGULATOR n regulator? Any time that your load t to source (rather than sink) power, a ical IC voltage regulator will shut d or else become unstable. There is current path to ground.

Motors an

Magnets

Load

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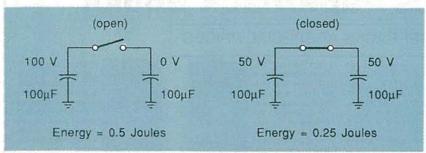


FIG. 3—QUICKLY CLOSE THE PERFECT AND LOSSLESS SWITCH. And half of your circuit energy will vanish without a trace. Where did the energy go?

nets perpetual motion machine. If you do not know *exactly* what you are doing, all your results are *guaranteed* to be wildly wrong. And so, of course, will be all of your conclusions.

Figure 2 shows you a second measurement pitfall that the recent callers have all decided to ignore. A voltage regulator is always a voltage regulator, right?

Wrong. Dead wrong.

Most popular voltage regulators are only capable of sourcing current. If the load starts sourcing any power even briefly, there is no place for the current to go, and the regulator either shuts down or starts oscillating.

Thus, if you have a motors-andmagnets load, there could be times when the back-EMF effects, spikes, commutator noise, or whatever, will try to *source* power back *into* your supposed power source.

Put in another way, typical power supplies and most regulators have wildly different impedances between when they source and sink power.

Note that any normally connected Zener diode will behave precisely the opposite—they are great power sinks but poor sources.

An output filter capacitor on your regulator is essential for grabbing and smoothing out high-frequency load sourcing variations.

Beyond proper output filtering, two ways around load sourcing effects are to hang enough of a resistive load on your regulator that the regulator will always output a net sourcing current. Most batteries are usually capable of sourcing and sinking any reasonable amount of current.

Figure 3 shows you yet another way to go astray. All bets are off if

there is any sparking or arcing. It is physically impossible to instantly change the voltage across a circuit capacitor or the current through an inductor. The usual result when you try this is sparking or arcing.

Take a 100-microfarad capacitor and charge it up to 100 volts. Your energy in any capacitor is...

E = 0.5CV<sup>2</sup>

or, in this case, 0.5 Joules of stored energy. Now, you close your lossless switch so you have two capacitors in parallel. The voltage must, of course, drop in half, since the same charge is now spread across twice your plate area. And by the same formula, you now have only 0.25 Joules of stored energy.

Question: Where did the rest of your energy go? If you have a non-lossless switch of resistance R, the answer is easy. In the process of charging the second capacitor, the extra energy got burned up in your resistor as heat during charging. But go through the charging math, and you'll find that the loss of half the stored energy is a constant which is totally independent of the value of R!

If R equals zero, then you have to get a spark and radiated energy. But you still lose half of it, regardless of how good the switch is.

Thus, if there is any sparking or arcing whatsoever in your machine, your readings are once again absolutely certain to be wrong.

Always think carefully about your measurements and how they could be wrong or misleading.

### **Lumeloid and Lepcon films**

We sure had a bunch of helpline calls over the new materials stuff I announced a column or two back and in our *Hardware Hacker III* reprints. I've picked up some more

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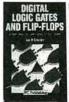
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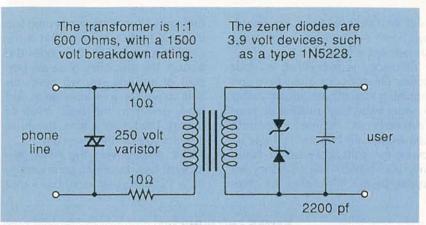


FIG. 4—A FCC PART 68 INTERFACE is required any time you connect any circuit of your own to the phone line. While this interface can be both simple and cheap, the required submission and approval process is not.

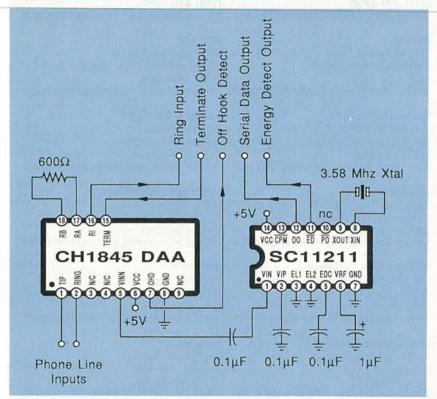


FIG. 5—PRE-APPROVED PART 68 INTERFACE HYBRIDS are available, but they are rather expensive. Here is a caller-ID circuit that uses the Cermetek CH1845 DAA interface and the Sierra SC11211 caller ID chip.

info, and have summarized where to go for more in our *Lumeloid and Lepcon Solar Resources* sidebar.

Let's start off with the bottom line: Yes, this looks like it someday could be real. Maybe. At least in the lab. No, you cannot yet buy the stuff by the yard through your local *K-Mart* fabric department and staple it to your roof. Yes, this is a great topic for a school paper or a science fair. And an incredible emerging re-

search area.

On the other hand, working prototypes do not yet exist. And there are just enough "penny stock" and "media hype" aspects to all this that I have lowered my rating from "solar breakthrough" to "an interesting potential solar development." But you could judge for yourself, just by picking up on the resources in our sidebar.

The key individual behind all this

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is one Alvin Marks and his company of Advanced Research Development. Their OTC pink sheet stock is traded under the name Phototherm. This is strictly an unregistered blue sky security, and trading remains illegal in Massachusetts, the issuing state.

Marks is a credible, experienced, and independent researcher with a long history of successful energy, optical-film, and pollution-control developments. Among other things, he developed the cheap glasses once used for 3-D movies.

And EPRI, that ultra-conservative Electric Power Research Institute electric utility consortium has seen fit to fund Marks with a modest research grant. Albeit a paltry one by EPRI standards. Coffee money.

The two key patents that are involved in this are #4,445,050 Device for Conversion of Light Power into Electric Power, and #4,574,161 An Ordered Dipolar Light-Electric Power Converter.

There is very little published to date. And all of it is single sourced. None appears to be peer reviewed or critiqued. A collection of reprints is now available free on request from Advanced Research Development. One original paper has shown up as Lumeloid Solar Plastic Films and Lepcon Submicron Dipolar Antennae on Glass, from the 1990 International New Energy Technology symposium published by the Planetary Association for Clean Energy, located in Ottowa, Canada.

As we've seen a number of times in the past, you can quickly research any technical topic by using the Dialog Information Service at your local library, and then can get any reprint by using either interlibrary loan or the UMI reprint service.

So what is the big deal here and how does it work? Your traditional methods of generating electricity from the sun are seriously flawed. The old mirrors-and-boilers method involves a thermodynamic cycle with a *Carnot* thermodynamic efficiency limit around 35 percent. Besides not downsizing very well. Silicon solar cells at a theoretical 26 percent are even less efficient. It seems that they can only accept "whole lumps" of quantum energy, and have to throw the rest away as

heat. And, before Marks, any photosynthesis scheme was well under six percent efficient.

Efficiency is everything in solar power. On a good day, you have one incoming kilowatt per square meter to work with. Say a nickel an hour "avoided cost" income for a perfect conversion. Or two cents a day allowing for night and weather. Naturally, your bottom-line efficiency will usually be much less than your the-

oretical. Let your efficiency drop t low and there's no way that so can be competitive. Get under t bottom-line efficiency of seven p cent or so, and you will *never* able to pay for your installation a land, owing to the time value money. The longer it runs, the most costs you for the financing.

But, alternatively, the nickel-p kilowatt-hour incoming solar ener on a 2200 square foot house ro

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10833 Valley View Street Cypress, CA 90630 (714) 229-4175 CIRCLE 318 ON FREE INFORMATION CAR adds up to over \$3000 a year. Which is lots more than usually gets used underneath as electricity. So efficient solar electric conversion could completely blow away coal, nuclear, and even most hydro.

Marks has developed two different solar-to-electric systems that seem to have rather high theoretical efficiencies.

Radio waves are electromagnetic. Solar energy is electromagnetic. The main difference between orange light (at 600 nanometers) and television channel two (6 meters) is a 10,000:1 size factor. Those light wavelengths may seem tiny, but we are starting to routinely handle submicron distances in integrated-circuit manufacturing.

There's this thing called a crystal set that you might have heard of. Just shove some electromagnetic energy into an antenna, rectify it somehow, and out comes DC power. These days, we call the same thing a rectenna. So why not use light waves instead of radio waves?

An antenna is any subsystem for converting radiated electromagnetic energy into conducted wire electromagnetic energy. Or vice versa. As a transmitter, if your antenna is now properly matched to the rest of your circuit, nearly all of your input energy will get radiated. And, since most antennas are linear and reciprocal devices, if you input any electromagnetic energy well inside of the antenna's effective area, nearly all of it will get converted into conducted electricity. So, a properly matched antenna can be 100 percent efficient. And a rectifier nearly

Now, an optical antenna is trivial. Just make it any old color so long as it is black. Even a black felt tip pen will do. The trick lies in rectifying and gathering all the received solar electromagnetic electricity, rather than burning it up as heat.

The Lepcon panel is the older of Marks' two new developments. In a Lepcon panel, tiny rectenna elements are created on glass using more or less conventional but very advanced microlithography. These are basically a conductive channel ending with a metal barrier diode. The photons in the incoming solar

### **LUMELOID & LEPCON SOLAR RESOURCES**

### **Key Patents:**

#4,445,050-Device for Conversion of Light Power into Electric

#4,574,161—An ordered Dipolar Light-Electric Power Converter.

Key Paper:

Lumeloid Solar Plastic Film and Lepcon Submicron Dipolar Antennae on Glass. 1990 International New Energy Technology Symposium. pages 201-210. From Planetary Association for Clean Energy below.

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THE SCHOOL OF VCK REPAIR 2245 Perimeter Park, Dept. V B 342, Atlanta, Georgia 30341 energy are used to accelerate electrons, which jump the barrier diode to become a DC current. Unlike a traditional solar cell, there are no "whole lumps only" quantum effects involved, and nearly all of the available energy gets converted.

The antenna/rectifier combination only works with one polarization of light. It converts the one polarization with up to a theoretical 80 percent efficiency, and passes the remainder on through. You could put a second Lumeloid panel underneath that is oriented 90 degrees from the first to convert the other polarization.

Or, you could use a sneaky trick consisting of a *quarter wave plate* and a mirror to rotate your rejected polarization by 90 degrees and shove it back *up* through the original film. Your combined efficiency ends up around a theoretical 72 percent.

The projected costs of the Lepcon process is around \$250 per panel, and the panels should last 25 years.

The Lumeloid film process uses chemicals instead of very expensive microlithography. The chemical techniques in theory lend themselves to low-cost and high-volume production. The chemicals attempt to mimic the first half of the long photosynthesis process. A rather long chain carbon molecule, such as polyacetylene, is attached to some electron donor acceptor complex, such as porphyrin and quinone.

The long chain molecule acts as a conductive antenna, changing the input optical energy into electron energy. The tunneling gap effect between the large donor and small acceptor rings acts as a rectifying diode for DC conversion.

For all this to work, the molecules have to be carefully oriented while the sheet is being created. Mark's work has centered on suitable bulk processes to do the orientation in a low-cost and high-volume process. Projected costs are five dollars per meter and three cents per watt.

At present, the Lumeloid films are only expected to last a year in strong sunlight. Once again, Lepcon panels use conventional microlithography on glass, while Lumeloid use oriented films that mimic photosynthesis.

Interestingly, the Lumeloid process is totally reversible. You can input electricity and get light out as well. Which could lead to new lighting and display technologies.

For any of this to become real, we will need working prototype panels, credible third party research, and the proper peer review. My "usual suspects" of Science, Nature, Science News, and the technology page of the Wall Street Journal have been suspiciously silent to date.

My own feelings are that short and open circuits in production panels are going to lead to the very same type of yield problems that have held back and restricted development of large area flat-panel TV displays.

Because of the lack of even lab prototypes, their efficiency and cost projections at this time would appear totally meaningless.

### Caller ID update

Time sure does fly when you are having fun. As a result, I've gotten hopelessly far behind on a bunch of potentially great projects here. So my caller-ID project may take a while.

Caller ID should be available in most parts of the country very soon. The controversy is dying down, since the benefits so totally and ludicrously outweigh any potential problems. To see what dozens of others are now thinking about caller ID, you might want to check #2239 CALLERID.CAP on the *GEnie* RADIO RoundTable.

If for no other use, the convenience of having a no-charge, nohassle list of everyone that called you while you were out is just flat out wonderful.

Motorola has just announced a brand new MC145447 caller ID chip. Free sample kits are available. This one is supposed to include internal ring detection. But, as near as I can tell so far, the chip of choice remains the Sierra SC11211.

An FCC Part 68 interface is shown in Fig. 4. Which is what normally has to go between you and the phone company. Key points include an exceptionally well-balanced transformer with a 1500-volt isolation capability. While such an interface is fairly cheap and simple,

getting the needed approval is

Several companies now a some ready-to-go Part 68 in faces. These are priced well al what you could build your own But they come pre-approved, inating most legal hassles. D Semiconductor and Cermetel two typical sources. An inter between the new Cerme CH1845 and the Sierra SC1 caller ID chip is shown in Fig. 5.

Both Cermetek and Sierra free caller-ID ap notes available

As we've seen before, a nur of ready-to-use caller-ID prod are available from *Hello Direct*.

### New tech lit

From Sony, a new Laser D Guidebook. And from Hughe free brochure on their Nonvo. Serial Programmable Devices.

The Best of Analog Dialogue three decade compilation of very best in analog linear integr circuit design info. From the cor ny Analog Devices.

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A reminder that I do have a collection of reprints availa These include Hardware Hacke III, my Ask the Guru I & II & III, Blatant Opportunist I, LaserW Secrets, and our brand new B on-Demand Resource Kit. Just me a call on our no-charge helpline (per the box) for more tails. Or call me at my Synerge

You can also reach me via G PSRT (800) 638-9636. Besides wavelet freeware and the Si Chart package, you'll find lot Hardware Hacker and Midnight gineering hard-to-find resor stuff.

# **AUDIO UPDATE**

### More from the mail bag

LARRY KLEIN

ast month, I answered several hi-fi questions from readers, but ran out of room before getting to them all. This month, we'll get to the bottom of the mail bag.

### Overpriced signals?

I'm appalled by the proliferation of signal processors—particularly equalizers—in the audio market place. What ever happened to the notion that a hi-fi system should be a "straight wire with gain"?

A.T.

McAlester, OK

The idea is alive and well, but beset by philosophical confusions. While the concept has validity for, say, power amplifiers, it really can't be applied to the entire recordingreproduction chain. Straight-wirewith-gain audiophiles-for whom tone controls of any kind are anathema-appear to assume that whatever signal comes out of their carefully chosen disc player or tape machine somehow perfectly embodies an original performance. Anyone naive enough to harbor such a belief has, at best, a very unclear notion as to how sound is recorded and reproduced.

Assuming that you had a perfect stereo recording of the sound field (at a specific location) of a live musical event—and all the electromechanical and electronic elements in your playback system were perfect—your speakers would still have the task of replicating the acoustics of a concert hall within the comparatively cramped space of a conventional listening room. In short, the chances of exactly duplicating an original live sound field in your listening room are about zero.

Given the aberrations in frequency balance, noise level, and dynamic range likely to be introduced, plus the loss of rear ambience and reflections, I see nothing wrong with using signal processors to help minimize, ameliorate, or eliminate the various ill effects. I've long since given up any hope of reproducing the precise sound of any original musical performance in my home. But when I achieve plausible reproduction, then I'm satisfied that I've achieved high, if not absolute, fidelity.

### System imbalance

After a long struggle to find the reason for my having to operate the balance control on my preamplifier at the 3-o'clock position, I traced the difficulty to my speakers. What would account for the fact that a readjustment of the midrange control on one of my speakers cured the problem?

J.W.

Freeport, TX

The frequencies that contribute to the perception of "loudness" are mostly in the midrange. (You can confirm this for yourself by noting the small effect on the overall loudness of music produced by the outermost controls of a ten-band equalizer.) Hence, any control that boosts or cuts the mid-frequencies in a speaker system will also necessarily influence its relative "efficiency" or loudness.

### Alcoholic anxiety

Some tape-cleaner ads seem to say that alcohol may be injurious to the insides of recorders. But magazines seem to recommend alcohol as a cleanser. Which information is correct?

N.W.

Covington, LA

You should avoid solutions sold as "rubbing alcohols" because they are likely to include a skin lubricant (usually glycerin) that could be transferred to the tape and the pinch roller. Ask your pharmacy for isopropyl alcohol in "NF" purity; that will work fine for heads, pinch rollers, and for general internal cleaning of your machine.

### **Costly repairs**

My receiver recently went dead in one channel, and I brought it to a local authorized service center. They charged me \$75 to repair a unit that cost \$300 when new. My friends have had similar experiences. Are the repair-shop owners trying to get rich at our expense—and why don't the manufacturers do something about it?

Boston, MA

We live in a time when very complex electronic devices are manufactured by automated machinery controlled by computers. That is the reason why you can buy a digital watch or a pocket AM/FM radio for well under \$10. But the elimination or reduction of the expensive handlabor element in many of today's electronic devices is of no help when the device needs repair. The repair process continues to be labor intensive, and it involves skilled, expensive labor at that. In short, although electronic products are built by the most sophisticated automated techniques available to the 20th century, they are repaired one at a time by the equivalent of an 18th-century handicraft approach. As you have found, that's not cheap!

### Slam damage

I've noticed that when I close the trunk lid the cones of the woofers installed in my car's rear deck seem to jump forward. Can the woofers be damaged by my slamming the trunk shut?

E.C.

Chicago, IL

Possibly, but not probably. The variables in the situation are the rug-

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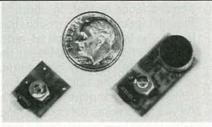
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gedness of the woofer-cone pensions, the size and air leaks the trunk, and the velocity of slam. To determine whether th a potential problem, watch woofer cone (with its prote grille removed, if possible) du typical slam. If the forced our excursion exceeds a quarter in so, it might be best to close trunk a bit more gently in the fu However, I expect that the b manufacturers of the larger car eo speakers, who knew where would be mounted, have des their cone suspensions to stand large pneumatic shocks

### FM bandwidth

What is the purpose of a na broad bandwidth switch on a tuner? RA

Bay Shore, NY

As far as I know, the only just tion for a narrow-band switch i rare case when a listener is loc between two transmitters of parable strength that are adjace each other on the FM dial. Ir case, a rotatable directional ant will probably be of more help in arating the two stations than tuner's ability to narrow its IF t width. The narrow bandwidth ting may be helpful if the confli stations are in approximately same direction, or possibly v there are severe noise condit

### Off-frequency FM

Many of the rock stations area advertise themselves as located at, for example, "100 c FM dial." But my digital tuner tune to even numbers; It sets for 99.9 or 100.1. Does some need adjustment? R.P.

San Diego, CA

Yes—the thinking of those like to reduce all communication the short, punchy, and simple-r ed. In the U.S., all broadcast tions are assigned odd-numb operating frequencies, 2-m hertz apart. Even if you could tu 100 MHz, you wouldn't find any there but a lot of noise and d tion. But, come to think of it, may be pretty close to what & stations are really broadcastin

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### **NEW LITERATURE**

continued from page 27

mation, complete specifications, and operating range data, are provided for more than 50 models. A five page summary of specifications and ranges is organized by instrument type to help the reader make model-by-model comparisons. Besides being chock full of test instruments, the catalog describes protective cases that are tailored for individual models, and a complete line of accessory test probes, cables, and test lead kits

THE HIDDEN SIGNALS ON SATELLITE TV: THIRD EDITION; by Thomas P. Harrington. Universal Electronics, Inc., 4555 Groves Road, Suite 13, Columbus, OH 43232; Phone: 614-866-4605; \$19.95, plus \$3.00 shipping and handling.

Everyone knows that you can pick up video signals with a satellite dish, and most satellite owners know

The Hidden Signals on Satellite TV

Third Edition Trainer R Harmaglan

A second Signals on The Satellites

The Second Signals On The Satellites

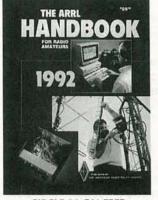
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that they can also receive audio channels on receivers equipped with tunable audio subcarrier sections. However, not many people are aware of the variety of non-video and data services that are also carried on satellites. Those services include audio news, stereo subcarriers, telephone systems, world news and press services, teletext, singlechannel-per-carrier (SCPC) systems, stock market reports, financial news services, and business data channels. This book covers all phases of this expanding side of the satellite business. Beginning with an explanation of the transmission and reception of satellite signals. the book goes on to provide details about each of the systems transmitting hidden signals. It describes each system and how it works, explaining who uses it and how the reader can receive it. The book also includes glossaries of data-communications and satellite-system terms.

THE ARRL HANDBOOK FOR RADIO AMATEURS 1992; Edited by Charles L. Hutchinson, K8CH and Joel P. Kleinman, N1BKE. American Radio Relay League, 225 Main Street, Newington, CT 06111; \$25.00.

Everything you ever wanted to know about amateur radio—and then some—can be found in the more than 1100 pages of this book. Aimed at hams, technicians, and engineers, the book provides a thorough introduction to the basics of amateur radio, including electrical fun-



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damentals, the techniques and terminology of radio design, and the basics of solid-state and vacuumtube sets. A comprehensive section on radio principles covers power supplies, audio and video communications, digital basics, modulation and demodulation, RF oscillators and synthesizers, principles of radio transmitting and receiving, transceivers, repeaters, amplifiers, antennas, and transmission lines. Modulation methods for voice, digital, and image communica-

continued on page 102

### Our long-lost discussion on digital scopes.

ROBERT GROSSBLATT

ell, it's been a while coming but, at long last, we're finally back to talking about digital scopes. There have been some interruptions in the meantime but that's the way life is—it sometimes interferes with living. This subject got put on hold for a bit because of the business of voltage regulators. Sorry about that but, even if you don't have any particular interest in cars or motorcycles, all that information should be put away for future reference. You never know

Just to refresh all our memories. we had been talking about the things to be considered in designing a circuit that would serve as the beginnings of a digital scope. All scopes, even the one we're going to design, have certain basic things in common and any project you have in mind that involves scope design has to start out life around these fundamentals. Your ultimate goal may be to construct something that's bigger, faster, or (to use my favorite phrase), "feature rich," but no matter what you have in mind, when you're just getting started it makes sense to approach things from the beginning.

The design criteria for the scope we are going to be putting together are the following:

- 1. The scope will have a maximum bandwidth of at least 1 MHz.
- 2. There will be eight selectable sweep speeds.
- 3. There will be eight selectable gain levels.
- 4. There will also be a variable gain control.
- 5. The display will be in a twenty-bytwenty matrix.

The block diagram of the scope

we're talking about is shown in Fig. 1. While you're looking at it keep in mind that, even though we're only talking about a demonstration cir-

cuit, the basic structure is the same for every scope there is. Once you go through the design of a simple scope, it'll be much easier to understand the workings of more complex ones.

There are all sorts of interesting things that can be done with the scope we're building and there's no reason whatsoever why you can't take the basic circuit and add anything you want to it. But we're getting ahead of ourselves.

One of the major players in the accuracy of a digital scope is the timebase. Ordinarily, in a simple scope such as ours, the timebase is an RC-type circuit that gives you... well, RC-type accuracy. But just because we're not building the world's most complex scope, there's no reason why we have to settle for so-so accuracy. Whenever you want accurate timekeeping, the answer is a crystal-based circuit, and that's what we'll use here.

There's no shortage of circui when it comes to building a crys oscillator, and the schematic show in Fig. 2 is as good as any. If yoneed frequencies up in the mamegahertz or even the gigaher range, you'd have to devote a lot time to this part of the scope, it since we're keeping everything under one measly megahertz, the schematic is a simple answer to the problem.

I've picked one megahertz for t basic crystal frequency because i a nice even number to work with a 1-MHz crystals are readily availab You shouldn't have any trouble giting the 4049's to work at 1 MHz even if you're only operating the cuit at 5 volts. If you have any prolems, up the voltage to 9 volts or (working with CMOS stuff great!), and that should take care the problem.

Should you want or need to st down at 5 volts and you find that t

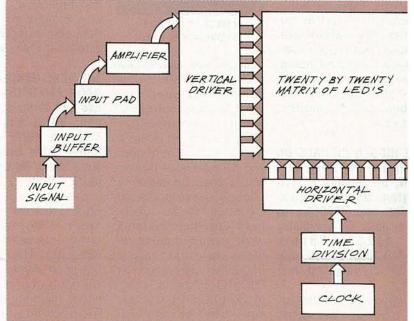


FIG. 1—BLOCK DIAGRAM of our oscilloscope. The basic structure is the same every scope there is.

oscillator isn't self-starting at that voltage, use an equivalent high-speed CMOS part like the 74HCT4049. Most of the mailorder houses carry the 74HCT family and you'll find that they're all faster than the 4000 series and just as reliable. Just about the only restriction you'll have is that 74HCT parts have the same voltage restrictions as TTL. They want a supply voltage of 5 volts and going any higher than that is a sure way to cook the chip.

Once we have the timebase circuit working properly, the next step is to do some straightforward frequency division to generate all the sweep speeds we need. First, however, we should decide what those sweep speeds are going to be and, even before that, we have to work out how the horizontal part of the display is going to be conceptually organized.

Our display is going to be, as we specified, a twenty-by-twenty LED matrix. There are twenty columns of LED's and each column is going to be enabled in turn for a particular length of time. When we refer to the sweep speed, we have to distinguish whether we're talking about how long it takes to sweep across the entire twenty columns or how long each of the twenty columns is enabled.

If you look at the sweep-speed settings on a standard oscilloscope, you'll see that it's marked in seconds/division. Since our display is made up of separate

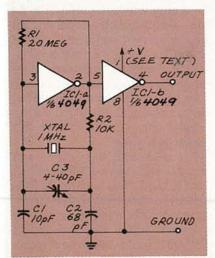


FIG. 2—A CRYSTAL OSCILLATOR for our scope. For frequencies below 1 MHz, this schematic is a simple solution.

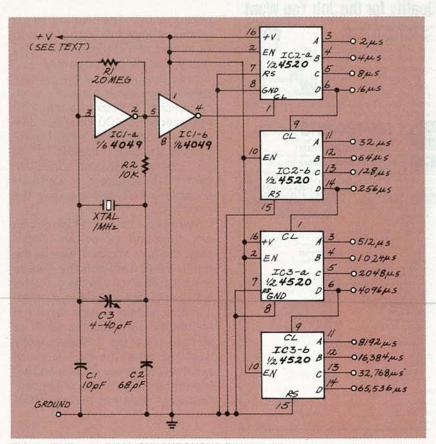


FIG. 3—THE 4520 DUAL SYNCHRONOUS BINARY COUNTER will provide us with a series of frequencies that are accurate enough for the kind of circuit we're designing.

columns, we can translate that into seconds per column. Therefore, we'll arrange our sweep speeds around the time each column is enabled, and not how long it takes to cycle through all the columns. That is important to keep in mind because we want to be able to get a rough idea of frequency when we're viewing a waveform on the scope, and the standard way of doing that is to count the number of divisions covered by a complete cycle. Since each division relates to a particular amount of time, you can estimate the period and calculate the frequency of whatever waveform is being displayed.

Standard oscilloscopes use a 5-2-1 counting sequence for dividing the sweep frequency. That means, at a basic level, that it takes the trace five, two, or one second (or some fraction of a second) to cover each division. The maximum sweep speed we can reasonably expect to have is about 10 microseconds since there are certain limitations to LED intensity, construction methods, and so on. It's

possible to do a lot better, but the stuff you have to worry about has nothing to do with the basic design of the scope itself.

The lowest sweep speed that makes sense for the scope we're working on is about a tenth of a second per column. The major factor here is that when you get much slower than this, it gets increasingly hard to visualize the waveform on LED's. Remember that the scope will be enabling one column at a time and only one LED in each column will be lit. If the sweep speed is too slow, the eye won't be fooled into seeing several of the columns lit at the same time.

Once we get the circuit working, you can experiment with the range of sweep speeds and see what the outside limits are. The top limit is a function of electronics but the bottom is determined by considering the persistence of the retina and other biological factors. If you want to drop the sweep speed to one second per division because you have a particular need to do that it's relatively simple to set the elec-

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tronics to do it. The best way to get an idea of what it would be like is to sit in front of a real scope and play with the sweep-speed control.

Now that we know the sweepspeed range—from a low of a tenth of a second (10 Hz) to a top of 10 microseconds (100 kHz) per division-we can decide what the remaining six sweep speeds should be. Generating divisions in the standard 1-2-5 sequence is certainly possible but it's also a pain in the neck to do.

We can cut this part of the design way down and reduce the needed parts to a bare minimum if we let the relationship between the sweep speeds follow the standard 1-2-4-8 binary sequence. By doing that, we can choose from a wide variety of standard binary counters and, as you can see in Fig. 3, that's exactly what I've done. The 4520 is a dual synchronous binary counter and will provide us with a series of frequencies that, while not exactly whole

numbers, are close enough for t kind of circuit we're designing.

Remember that the resolution the scope we're building isn't all tl great in the first place.

Feeding a standard CMOS p like the 4520 with a clock as high 1-MHz is an iffy business—6 pecially, as we discussed a wh ago, if you're running off a sup that's down in the range of only f volts or so. If you have such a pro lem, the ways to get around it a the same as the ones we talk about earlier; you can either rai the supply voltage or u: 74HCT4520's instead of the sta dard 4520.

The two 4520's in the circuit qi you a choice of sixteen clock fi quencies (seventeen if you cou the basic crystal frequency), so y have lots of sweep-speed choice When we get together next tim we'll finish the horizontal circuit a go through the design of the vertice amps and driver circuit as well. F



### **EQUIPMENT REPORT**

continued from page 16

the manual says to install C40, a 22 pF, 16-volt electrolytic, but the actual part, as shown in the parts list, is 22 µF. Also, a spring must be installed to the left of the 7106 IC to ground a metallic shield in the back of the meter housing; the instruction manual does not clearly show where the spring goes.

Other problems included R43, one of four 1-megohm resistors to be installed, but the parts list shows only three 1-megohm resistors and R43 as 100K-also, the 100K resistor was missing from our kit. Resistor R7 is said to be installed as 900K but the parts list shows it to be 898 ohms and that's what was included in our kit. Likewise with R8: it's installed as 100K but listed and included as 100 ohms. Another 100ohm resistor, RX, was not among the parts included in our kit, but they did include an unnecessary 75K resistor-perhaps it was intended to be close enough in value to R43. Resistors R09 and R17 are to be installed as 9 ohms each but listed as 8.98 ohms. Neither of the tw remaining resistors were color-co ded for 8.98 ohms, but they me sured about 12 ohms. Clos enough we decided, and the metseems to work just fine.

You never know exactly what's i side something until you take apart, so you can't help but be fam iar with the basic insides of any mu timeter once you build the 1001 The finished 100K is a sturdy, cap ble meter, and certainly worth it price. And although we feel that it a pretty decent meter and a greproject for someone new to ele tronics, the help of someone mo experienced might be necessar However, we've already pointed or the kit's sore spots so if you plan c building one you should save th review as a guide.

If you've read this review ar would like to own a 100K but dor want to build it yourself, the 100K available preassembled. And the a sembled 100K multimeter actual costs ten dollars less than the k (\$19.95). That's because it cos more to package the unit in piece and the kit includes a 47-page a sembly manual.

# COMPUTER CONNECTIONS

### **Pen-Based Computing**

**JEFF HOLTZMAN** 

en-based computing is one of this year's hot topics. At first glance, this new class of device seems to be more gadget than computer. On closer examination, however, it looks more like a glimpse of the future.

As with many hot topics in today's computer world, pen-based computing got its start at Xerox PARC (Palo Alto Research Center), a research division of the corporation mostly famous for photocopying, but whose basic research has fueled much of the personal computer revolution—but that's another story.

In 1968, a fellow by the name of Alan Kay, now a researcher at Apple, put together a cardboard model of something he called the Dynabook. Kay didn't call it a computer; he intended to suggest something far larger, more grandiose, more connected, and more accessible than any mere data-processing machine. The original design called for a notebook with a megapixel screen, multiple CPU's, and wired and wireless networking. Since then Kay realized that the hardware alone was not enough; a user-friendly (Macintosh-like) user interface would also be required. Even more important, a cooperating system of software "agents" would assist the user in gathering information and performing routine tasks. Agents are not yet ready for prime-time. User interfaces have evolved considerably since 1968, but still have a long way to go. Perhaps not surprisingly, as in most areas of the computer business, the greatest strides have been made in hardware.

Since portable computers, laptop computers, and notebook computers first started to appear, several companies have released suboptimal designs bearing the title Dynabook; however, it is only the very

latest generation of pen-based machines that even dignify the concept. NCR released the first of this new breed in the spring of 1991; fall COMDEX in Las Vegas saw the release of a spate of new machines by other vendors. This first generation of commercial machines illustrates several points: (1) The Dynabook concept is valid, but (2) current hardware and software have not fully achieved the vision; even so (3) there is a light at the end of the tunnel.

### Hardware and software

The typical pen-based machine is about the same size as a notebook PC (8.5" × 11" × 2", less than five pounds). The current generation typically has a 286 or 386SX processor, a few megabytes of memory, a floppy drive, possibly a hard drive, and a slot or two for special credit-card sized memory cards (these cards have now been standardized; more in a future installment). Usually there's no keyboard,

although there are "convertible" units that allow both keyboard and pen input. Some units, such as Grid's GridPad RF (shown in Fig. 1), allow wireless connection to standard networks. Overall, the most interesting thing about pen-based machines is that the screen is used for both input and output. Using a special stylus, you draw, write, and edit directly on the display surface-it's like an intelligent Etch-A-Sketch, one that allows you to store and recall text and graphics. It's what some call a direct-manipulation environment (DME).

If there's no keyboard, how do you use the thing? There are three basic approaches. The first simply glues a pen-input interface on familiar operating environments (DOS or Windows). The second creates a rich new environment (GO's Pen-Point operating system). The third creates a limited new environment, one that restrains cost and power in service of specialized applications.

Microsoft, as might be expected,

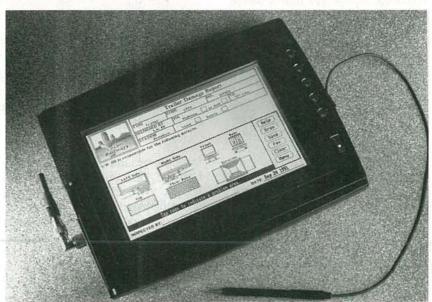


FIG. 1—THIS PEN-BASED PC from GRID features wireless RF connectivity to Novell networks.

has adopted the first course. The company has defined a set of penoriented extensions to the Windows environment, called Windows for Pen Computing (WPC). This environment is scheduled to be released in the first quarter of 1992. right after Windows 3.1. WPC has already garnered support from some three dozen hardware vendors, including AST, Dell, Grid/Tandv. NCR. Zenith, Sharp, Sonv. Toshiba, Tusk, Momenta, NEC. Samsung, Sanyo, and many more. Currently Grid owns more than 50% of the market, but in five years that's expected to drop to about 10% of the current level, with Sony, Toshiba, and Sharp accounting for about 36%, and IBM and Apple together for about 30%. Hundreds of software developers have also shown support for WPC.

A company called GO Corporation has pursued the second option. with a product called PenPoint, the chief competitor to WPC. PenPoint has not achieved as much support as WPC (vet), but the support it has achieved is guite meaningful. IBM. for instance, has licensed PenPoint. and has shown it running on a to-bereleased pen machine. Apple is evaluating use of PenPoint versus its own internally developed penbased operating system for a soonto-be-released pen machine.

Although extending an already popular environment has some advantages, some feel that a whole new way of looking at things is reguired. This new paradiam returns to square one in the process of thinking about how people can best interact with a computer. For example, the select-do paradigm (e.g., select text, press Delete) of Windows may not make sense in a direct-manipulation environment. In a DME you might simply draw a line through unwanted text. It's more direct, more natural, more efficient, more comprehensible by computer novices. This is the tack taken by PenPoint.

A related area is compound documents, documents that include text. graphics, possibly other media. Windows is just about to the point where building compound documents is reliable and efficient. By 92 contrast, PenPoint has been built

esture	Meaning							
٠	Places the insertion	point or selec	ts where you tap the pen.					
_	Selects all character	Selects all characters under the line.						
4,	Extends the selection	to the location	on where you draw the gesture.					
9	Deletes the current s	Deletes the current selection or the character to the right of the insertion point.						
7	Deletes words or obj	ects underne	ath the gesture.					
1	Backspaces and dele (Optional)	etes the chara	acter to the left of the insertion point.					
<u>_</u>	Inserts space at the	insertion poin	t. (Optional; can also be positional)					
-4	Inserts a new line (R positional)	eturn) at the i	nsertion point. (Optional; can also be					
<u>-</u>	Inserts a Tab at the i	Inserts a Tab at the insertion point. (Optional; can also be positional)						
V	Places the checked	Places the checked word or selection in the Edit Text dialog box.						
1	Cuts the selection ar	nd places it or	the Clipboard.					
×	Copies the selection	Copies the selection and places it on the Clipboard.						
^	Pastes the contents be positional)	of the Clipboa	rd at the insertion point. (Optional; can als					
8	Reverses the previou	s action.						
			a					
	Gesture	Alexant.	Meaning					
Ta	р		Select/Invoke					
Pr	ress-hold	•	Initiate drag (move, wipe-through)					
Ta	p-hold	• •	Initiate drag (copy)					
FI	ick (four directions)	1	Scroll/Browse					
Cı	ross out	×	Delete					
S	cratch out	_	Delete					
Ci	rcle	0	Edit					
Check		4	Options					
Caret /		1	Insert					
C	ares							
	rackets	[]	Select object, adjust selection					
В		[]	Select object, adjust selection  Delete character					

FIG. 2—PEN-BASED GESTURES differ between Microsoft's Windows for Pen Co puting (a) and GO Corp.'s PenPoint (b).

from the ground up to support Embedded Document Architecture (EDA). With EDA, you just grab something and start working on it. If it's text, a text-editing window pops up; if it's graphics, sizing/shaping handles appear. This focus on the document, rather than the applications used to produce it, is what will make pen PC's attractive to novices, and to the those of us tired of fighting the battle for integration.

Deferred I/O is another intere ing capability of PenPoint. It allo you to "send" documents to otl people, regardless whether you plugged into the company netwo or riding a camel in Riyadh. If I hardware can't physically send t file when you make your request adds it to a queue and sends it wh the required resources becor available. Likewise with modem o put, fax output, and printer output

### Gestures

Both PenPoint and WPC make use of gestures, pen motions that signal an intent to do something, and depending on the operation, the data to which it is done (e.g., striking a line of text). Gestures come in several sizes and shapes, depending on the system; and specific gestures tend to be inconsistent from system to system, as shown in Fig. 2-a (WPC) and Fig. 2b (PenPoint). (This is equivalent to the once-heated argument about whether the Delete key should work on characters to the right or left of the cursor. The vast majority of users simply didn't care, as long as usage was consistent from program to program.)

PenPoint demonstrations are extremely compelling. But Microsoft is Microsoft, and Windows is Windows. Does PenPoint have a chance? It's simply too soon to tell. The Windows juggernaut is rapidly crushing everything in its path; GO is working hard on data portability, so there's a good chance it will at least survive. In any case, most hardware vendors are playing it safe and supporting both operating systems. Phoenix has even released a dual-mode BIOS that provides low-level support for both.

Theoretically, anything that runs under Windows should run under WPC. PenPoint is in a more precarious position regarding applications; however, WordPerfect and Lotus are converting and developing applications, and several other companies are developing new applications, including telecommunication, word processor, spreadsheet, network interface, outliner, PIM, and more.

Some developers are targeting applications for both environments. Slate is one interesting example. The company has introduced a product called PenBook that allows you to take any file in PostScript format and convert it for use in a pen environment. The software allows you to build a table of contents and link specific pages to it. It also indexes the text. Rather than 45 pounds of manuals, imagine being able to take a notebook with all relevant service information on a house call, and instantly locate the desired

information with a few taps and flicks of the pen. There's potential here.

### Who cares?

Companies marketing pen products see two initial focii: highly mobile personnel (e.g., doctors and nurses, delivery people, sales people, insurance sales people and adjustors, etc.) and professionals who travel a lot.

Mobile usage is already happening. For example, a major pharmaceutical company recently purchased 1000 pen units from Grid for on-site sales; the San Jose Police Department is evaluating use of Grid machines to reduce paperwork

Some industry veterans feel that pen computing is just another overhyped technology, with little mainstream application. More informed sources, those with a little historical perspective, see the potential. It will take a few years, but by the end of the decade, most of us will be carrying "pentops" and wondering how we ever got along without them.

### **News bits**

Last time I talked about the significant effect that multimedia will be having on the computer industry, the publishing industry, and society in general. At the time, I wondered how IBM planned to get involved. Shortly after my deadline, Big Blue announced a wide variety of products and services under the banner "Ultimedia." The software (discussed last time) is in some ways the most interesting part of the announcement; however, there are some interesting hardware goodies as well, including a device that lets you broadcast and receive televisions signals across a token-ring network simultaneously with normal network traffic, thereby setting the stage for real-time video-conferencing. IBM also co-released with Intel a \$2000 NTSC video board, called the ActionMedia II, that allows playback of digitally recorded video. (A \$900 add-on allows digital recording.) The basic technology is Intel's DVI (Digital Video Interactive): the board, though it may sound expensive, is about half the cost of the previous version, occupies half as much space, and reportedly provides about twice the performance. In addition, the company released a rather weird multimedia PC (the M57SLC) that includes a high-performance CD-ROM drive, XGA graphics, 16-bit audio capture/playback, and a souped-up 386SX processor that sounds like a 486SX crammed into a 16-bit package.

After years of promises, Philips finally unleashed its CD-I (Compact Disc Interactive) technology on the consumer market under the name Imagination Machine. It costs in the neighborhood of \$800, but does only one thing. Conversely, you can upgrade your PC with a CD-ROM drive and a slew of useful software for that amount of money, have change in your pocket, and have a general-purpose tool that's truly only limited by your imagination. I think Philips' marketeers inadvertently hit on the right name, but for the wrong reason. The only imagination is in the amount of sales CD-I will generate.

On the software front, IBM has delayed release of a fully functional (i.e., Windows compatible) version of OS/2 2.0 until the end of the first quarter of 1992. In the meantime. Microsoft will sell another couple million copies of Windows. However, Microsoft also slipped its ship date for Windows 3.1 until the first quarter of 1992, but has publicly shown a fairly robust version of Windows NT (New Technology). betas of which will be shipping to developers by the time you read this. Digital Research released DR-DOS 6.0, the major addition to which is RAM-based task switching and some utilities. It seems like a good product, and three or four years ago would have been a great competitor to DESQview. R-E



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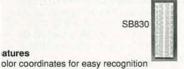


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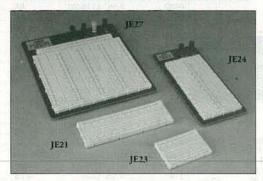
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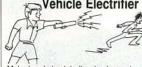
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continued from page 87

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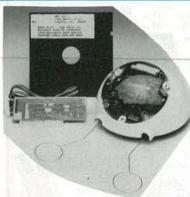
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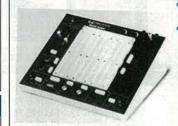
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Protoboard Design Station

STOCK

LDM135-5

LDM135-2

LDM135-3

LT1001

i - to -15 VDC @ 0.5 amp, ripple 5 mV Variable DC output -5

Frequency generator frequency range: 0.1 Hz to 100 KHz in 6

ranges output voltage: 0 to ± 10V (20 Vp-p) output impedance: 600 (except TTL) output current: 10mA max., short circuit

output waveforms: sine, square, triange, TTI

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versatility Base plates & cutting acces-

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Infra-Red Collimator Pen

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DESCRIPTION LSLENS Collimating Lens Assembly 23.74 24.99 21.37

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to draw, in addition to drawing straight lines, it can also accu-rately draw circles, and even draw out words and short phrases. WAO II comes with 128 x 4 bits RAM and 2K ROM.

and is programmed directly via the keypad attached to it. With its built-in connector port, WAO

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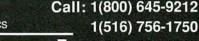
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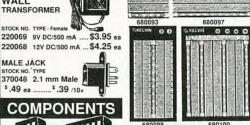
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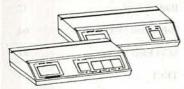
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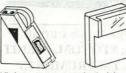


"MAX" allows you to watch and control a single VCR from other locations in the house. Transmits audio, video and IR signals up to 100 feet through mini-cable. Works on up to 4 televisions at a time, but a separate "MAX" receiver is required for each TV. Can also be used with other infrared controller devices such as CD players or stereos. Because it is hardwired, signal transmission is

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### TOUCH DIMMER

The "brain" part of the TOUCH\* touch dimmer, when connected to any lamp,



will turn it on and off and change the brightness level when any metal part is touched. We don't have the wiring harness that originally connected this to the lamp, but we can provide a simple hookup diagram and instruction sheet. The solid-state circuitry is contained in a thermo-plastic box 1.91" X 3.11" X 0.835". CAT# DMR-1 \$3.50 each

### **OPTO-SENSORS**

**GE H1381** U-shaped opto with 0.125" gap between emmiter and sensor. 0.75\* mounting centers. CAT# OSU-11 2 for \$1.00



TRW/Optron # OPB5447-2 IR emitter/sensor pair in rectangular package with 28" color coded leads. CAT# OSR-4 2 for \$1.00

### 4 AMP Full Wave BRIDGE

#RS405L 4 Amp 500 plv Epoxy package. In-Line leads CAT# FWB-405



### Rechargable Batteries SUB-C 2 PACK

2 Sub-C nickel-cadmium batteries with solder tabs. Connected in series. This size battery is typically found in power tools, remote control models, electric shavers and other home appliances. Each battery measures diameter X 1.66" long. CAT# NCB-2C \$3.50 per pack



clearer than more expensive non-hardwired

CAT# MAX \$40.00 each 4 or more \$35,00 each

L.E.D.'s

Standard JUMBO

Diffused T 1-3/4 size (5 mm)

RED CAT# LED-1

10 for \$1.50 · 100 for \$13.00

GREEN CAT# LED-2

10 for \$2.00 · 100 for \$17.00

YELLOW CAT# LED-3 10 for \$2.00 • 100 for \$17.00

FLASHING LED

TEL

**RED** \$1.00 each

CAT# LED-4 10 for \$9.50

GREEN \$1.00 each

CAT# LED-4G 10 for \$9.50

YELLOW \$1.00 each

CAT# LED-4Y 10 for \$9.50

RECHARGEABLE

BATTERIES

Nickel-Cad

AAA SIZE \$1.50 each

1.2 volts 180 mAh

CAT# NCB-AAA

AA SIZE \$2.00 each 1.25 volts 500 mAh

CAT# NCB-AA

AA SIZE \$2.20 each

WITH SOLDER TABS

CAT# NCB-SAA

C SIZE \$4.25 each

1.2 volts 1200 mAh

CAT# NCB-C

D SIZE \$4.50 each

CAT# NCB-D

LED HOLDER

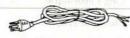
Two piece holder. CAT# HLED 10 for 65¢

W/ built in flashing circuit 5 volt operation. T 1-3/4

(5mm)

### 14/3 LINE CORD

8' BLACK SJT 14/3



Heavy duty A.C. power cord. Standard 3 prong grounded plug one end, bare wire the opposite end. Blue, brown, green w/stripe wire color code, 0.37" nom, o.d. CAT# RDAC-HD8 \$4.50 each

### WALL TRANSFORMERS

12 Vdc 500 ma.

2.1mm D.C. power plug with center negative. White case.

CAT# DCTX-125W \$4.50 each 12 Vdc 200 ma.

2.1 mm D.C. power plug with center negative. CAT# DCTX-122 \$3.00 each

### HEAT SINK COMPOUND



G C Electronics # 10-8109 - For effective transfer of heat between components and heat sinks. Z9 silicone heat sink compound. CAT# HSC-1 \$2.00 per 1 oz tube

### PHOTORESISTOR

1,000 ohms bright light. 16K ohms dark

0.182" dia. X .08"high. 0.18" long CAT# PRE-7 2 for \$1.00 100 for \$45.00 • 1000 for \$400.00

### DIP RELAYS

Miniature Relays With Pin Configuration To Fit 14 DIP.



5 Vdc - S.P.S.T.

GI Clare # PRMA-1A05B. Normally open reed relay. 500 ohm coil, U.L. listed. Diode protected.

CAT# DRLY-57 \$1.50 each

12 Vdc - S.P.S.T. Gordos# 846A-412

575 ohm coil, Sealed, Internal clamping diode. CAT# DRLY-12 \$1.25 each

24 Vdc - S.P.D.T. GI Clare # PRMA 1C24

2.150 ohm coil. 10 vA switching power. CAT# DRLY-1C24 \$1.00 ea

48Vdc - S.P.D.T. Aromat # DS1E-A-DC48V

5,750 ohm coil. 2 amo contacts. CAT# RLY-788 \$1.00 each

### **SWITCHES**

Pushbutton Switch

SMK Manufacturing 0.47" square black pushbutton. SPST normally open. 4 p.c. pins for mounting. Ideal for low current

switching applications. CAT# PB-29 5 for \$1.00 • 100 for \$15.00

### RFI/EMI LINE FILTER

Corcom# 20B6 20 amp RFI/EMI general purpose common-mode filter. Controls line-to-ground noise. Small size, low leakage 3.46" X 1.16" X 2.81" UL and CSA listed

CAT# RFI-201 \$8.50 each

### HALL EFFECT SENSORS

Microswitch #SS41 Tiny, solid state switch reacts instantly to proximity of magnetic field. Operates at extremely high speeds, up to 100 khz. Case size: 0.12" X 0.17" X 0.06" thick. 4.5 Vdc to 24 Vdc supply voltage. 10 ma. sink type digital output. Operating gauss -15 to 40. P.C. leads.

CAT# HESW-2 75¢ each 10 for \$6.50 • 100 for \$60.00

### SURFACE MOUNT STYLE

Sprague # UGN3075LT Operates on 4.5 - 24 Volts
Can sink 10 ma. With suitable output pull up, can be used directly with bi-polar or CMOS logic circuits. Especially suited for electronic com-mutation in brushless D.C. motors using multiple ring magnets. Very tiny surface mount package 0.175" X 0.09"X 0.06" thick.

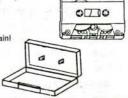
CAT # HESW-5 2 for \$1.00 100 for \$45.00 LARGE QUANTITIES AVAILABLE

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Premium quality metal tape in C-60 style cassettes (30 or more per side). One of the finest "brand-name" tapes on the market, in durable, clear plastic transport mechanisms. Recorded and bulk erased, the record-protect tabs have been removed and therefore, need to be taped over to re-record. Audiophiles will appreciate the wide dynamic range of this tape. If your cassette deck has a "metal" setting you will hear the difference. A real bargaint 60 min, tape - CAT# C-600M \$1.25 each • 10 for \$10.00

### CASSETTE STORAGE CASE

Black, unbreakable plastic audio cassette storage case. CAT# CBOX 5 for \$1.00 . 100 for \$15.00



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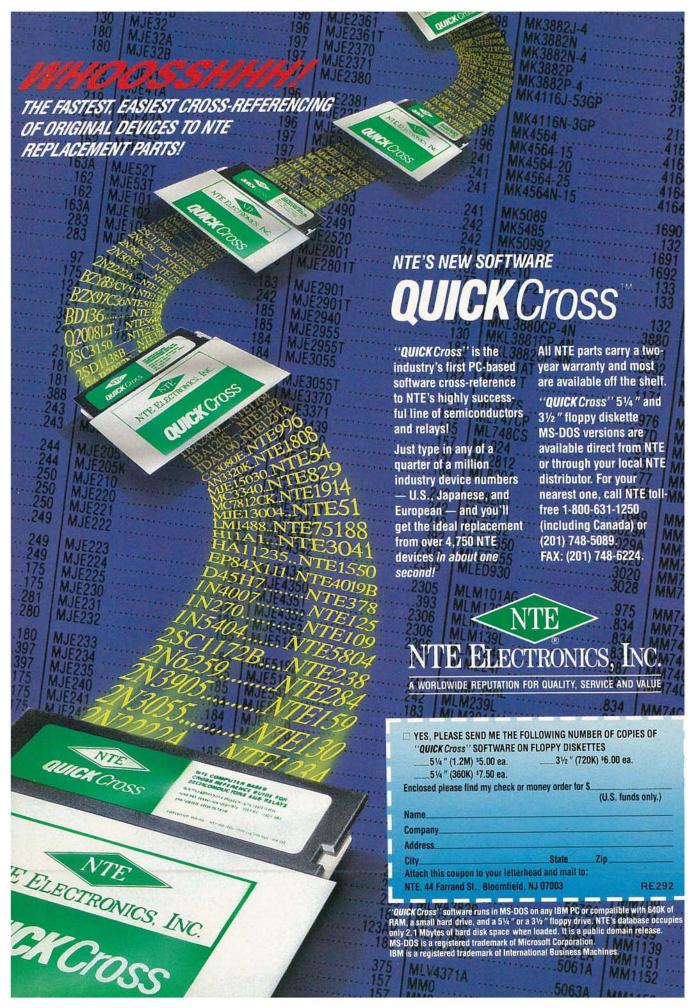
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